

# Visualizing clutters

Lorenzo Traldi

Department of Mathematics, Lafayette College  
Easton, Pennsylvania 18042

## Abstract

If a picture is worth a thousand words, then surely clutters are among the least intuitively compelling objects studied in combinatorics. What picture is conveyed by *a family of subsets of a finite set, none of which contains any other*? A large Venn diagram perhaps, in which certain unions of regions cannot be empty? In this expository note we discuss a simple technique for visualizing arbitrary clutters using graphs.

## 1. The clutter of a $K$ -terminal network

A  $K$ -terminal network is a graph  $G$  some of whose vertices have been designated as *terminals*; it is traditional to use  $K$  to denote the set of terminals. We think of a  $K$ -terminal network as representing a real structure like a telephone or computer network: the terminal vertices represent the people who use the network, and the edges and non-terminal vertices represent the internal structure (cables, switching locations, etc.) of the network. Because they are useful as models of such real-world structures,  $K$ -terminal networks have been thoroughly studied, especially in connection with their reliability; see [1] for a discussion.

With these thoughts in mind, if we are given a  $K$ -terminal network  $(G, K)$  we define  $C(G, K)$  to be the collection of minimal sets of non-terminal vertices which are sufficient (along with their incident edges) to provide paths connecting all the terminal vertices. That is, an element of  $C(G, K)$  is a minimal subset  $W \subseteq V(G) - K$  such that the induced subgraph of  $G$  with vertex-set  $K \cup W$  is connected. For instance, if  $(G, K)$  is any of the  $K$ -terminal networks pictured in Figure 1 then  $C(G, K) = \{\{a, c\}, \{a, d\}, \{a, e\}, \{b\}, \{c, d\}, \{c, e\}\}$ . (In the figure terminals are represented by large nodes and non-terminal vertices by small, lettered nodes.)

It is important to emphasize that  $C(G, K)$  is defined using sets of vertices of  $G$ , not sets of edges. Using edges instead of vertices would result in a strictly smaller class of structures, associated with matroids; see [3, 4, 7]. If

desired, an edge may be represented in  $C(G, K)$  by inserting a non-terminal vertex of degree two.

In reliability theory the elements of  $C(G, K)$  are referred to as *minimal pathsets of the  $K$ -terminal connectedness problem on  $(G, K)$* ; we will call them the *minpaths of  $(G, K)$*  for short. Otherwise we use standard graph-theoretic terminology and notation; in particular we use  $N(v)$  to denote the set of neighbors of a vertex  $v$ .

The fact that each element of  $C(G, K)$  is a *minimal* set of non-terminal vertices sufficient to connect all the terminal vertices certainly guarantees that  $C(G, K)$  must be a clutter. The purpose of this note is to discuss the result of [8] that every clutter is  $C(G, K)$  for some  $K$ -terminal networks  $(G, K)$ . An important tool for proving this result, and possibly the most important topic in the elementary theory of clutters, is the *dual* or *blocker*  $C^*$  of a clutter  $C$ : if  $\emptyset \neq C \neq \{\emptyset\}$  then  $C^*$  is the collection of minimal sets which intersect all the elements of  $C$ . The definition is completed by defining  $\emptyset^* = \{\emptyset\}$  and  $\{\emptyset\}^* = \emptyset$ . If  $(G, K)$  is a  $K$ -terminal network then an element of  $C(G, K)^*$  is a minimal set of non-terminal vertices whose removal (along with all incident edges) will leave a subgraph of  $G$  with terminals in different connected components; that is, an element of  $C(G, K)^*$  is a minimal vertex cut of  $G$  which consists of non-terminal vertices and whose removal will separate at least one pair of terminal vertices.

**Theorem 1** [2]. *If  $C$  is a clutter then  $C^{**} = C$ .*

**Proof.**  $C = \emptyset$  and  $C = \{\emptyset\}$  satisfy the proposition by definition.

Suppose  $C$  is a clutter of subsets of the finite set  $S$  and  $\emptyset \neq C \neq \{\emptyset\}$ . The definition of  $C^*$  implies that every element of  $C$  must intersect every element of  $C^*$ , so every element of  $C$  must contain an element of  $C^{**}$ .

Conversely, if  $W \in C^{**}$  then  $W$  intersects every  $B \in C^*$  and hence  $S - W$  does not contain any  $B \in C^*$ . By the definition of  $C^*$ , this implies that there is at least one  $V \in C$  which does not intersect  $S - W$ . That is, every element of  $C^{**}$  contains an element of  $C$ . ■

Theorem 1 is the only result of the elementary theory of clutters that we will need here; we refer the reader to [2, 5, 6] for more thorough discussions.

**Theorem 2** [8]. *If  $C$  is a clutter then there is a  $K$ -terminal network  $(G, K)$  with  $C = C(G, K)$ .*

**Proof.**  $C = \{\emptyset\}$  and  $C = \emptyset$  correspond to edgeless networks with one or two terminals.

Suppose  $|C^*| = 1$  and  $\emptyset \notin C^*$ ; then every  $W \in C$  has  $|W| = 1$ . If  $G$  is a  $K$ -terminal network with  $|K| = 2$  which has a non-terminal vertex for each element of an element of  $C$ , such that every non-terminal vertex is adjacent to all the other vertices of  $G$  and the two terminal vertices are not adjacent, then  $C = C(G, K)$ .

If  $C$  is a clutter on a set  $S$  and  $|C^*| \geq 2$  then we construct a  $K$ -terminal network  $(G, K)$  with  $K = C^*$  and  $V(G) - K = S$  as follows: all of the non-terminal vertices of  $G$  are adjacent to each other, none of the terminal vertices are adjacent to each other, and a terminal vertex  $B \in C^*$  has neighbor-set  $N(B) = B$ , i.e., the non-terminal vertices adjacent to  $B$  are the elements of  $B$ .

The elements of  $C(G, K)$  are the minimal subsets  $T \subseteq S$  such that  $T \cup K$  induces a connected subgraph of  $G$ . Certainly such a  $T$  must include at least one neighbor of each terminal vertex; by the definition of  $C(G, K)$ , this implies that  $T \cap B \neq \emptyset$  for every  $B \in C^*$ . Conversely, if  $T \subseteq S$  has the property that  $T \cap B \neq \emptyset$  for every  $B \in C^*$  then  $T \cup K$  induces a connected subgraph of  $G$ , for the vertices in  $T$  are all adjacent to each other and each terminal vertex is adjacent to at least one of them. It follows that  $C(G, K)$  consists of the minimal subsets  $T \subseteq S$  such that  $T$  intersects every  $B \in C^*$ , i.e.,  $C(G, K) = C^{**}$ . By Theorem 1, this implies that  $C(G, K) = C$ . ■

The proof of Theorem 2 shows that every clutter  $C$  is  $C(G, K)$  for a  $K$ -terminal network in which all non-terminal vertices are adjacent; we say such a network has a *non-terminal clique*.

## 2. $K$ -terminal networks with the same clutter

As indicated in Figure 1, it is not unusual for nonisomorphic  $K$ -terminal networks to have the same associated clutter  $C(G, K)$ . Here are four simple ways to modify any  $K$ -terminal network without changing  $C(G, K)$ .

(1) If  $G$  has two terminal vertices with precisely the same neighbors then one of these terminals may be removed from the network without affecting  $C(G, K)$ ; conversely a new terminal may be introduced with the same neighbors as an existing terminal.

(2) If two terminal vertices in  $G$  are adjacent, the edge connecting them may be contracted; that is, the two terminals may be combined into a single terminal which is adjacent to all the other vertices adjacent to either of the original two. Conversely, a terminal vertex may be split into two adjacent terminal vertices whose other neighbors are precisely the neighbors of the original terminal vertex.

(3) If  $v$  and  $w$  are terminal vertices such that neither is adjacent to any terminal,  $N(v) \subseteq N(w)$ , and every neighbor of  $w$  not adjacent to  $v$  is adjacent to every neighbor of  $v$ , then removing  $w$  from the network will not affect  $C(G, K)$ ; conversely one may choose any terminal  $v$  not adjacent to any other terminal and introduce such a  $w$ .

(4) If  $v$  is a non-terminal vertex which does not appear in any minpath of  $(G, K)$  then any edge incident on  $v$  may be removed from  $G$ ; conversely an edge incident on  $v$  may be added, so long as it does not create a minpath involving  $v$ .

The reader may inspect Figure 1 to see some instances of these modifications, and also to see that they are not sufficient to generate all the different  $K$ -terminal networks with a given  $C(G, K)$ .

Given a clutter  $C$ , it is natural to seek the simplest  $K$ -terminal network with  $C = C(G, K)$ . A reasonable definition of “simplest” involves having the smallest possible number of terminal vertices. The proof of Theorem 2 shows that if  $|C^*| \geq 2$  then  $C$  may be realized by a network with  $|C^*|$  terminals, but it is often true that smaller networks will suffice. For instance  $C = \{\{a, b, d\}, \{a, b, e, f\}, \{a, c, d\}, \{a, c, e, f\}\}$  has  $C^* = \{\{a\}, \{b, c\}, \{d, e\}, \{d, f\}\}$  but only two terminals are required in a network realizing  $C$ . We leave it as an exercise for the reader to construct such a network. (Hint: Start with two terminals separated by a cutpoint  $a$ , and then separate one terminal from  $a$  with a vertex cut  $\{b, c\}$ ; separate  $a$  from the other terminal with a vertex cut  $\{d, e\}$ , and then find a place to insert  $f$  so that  $\{d, f\}$  is also a vertex cut.)

Sometimes, though,  $|C^*|$  terminal vertices are required. For instance, let  $S = \{1, \dots, n\}$  and let  $C = C_{2,n}$  contain all the 2-element subsets of  $S$ ; then  $C^* = C_{n-1,n}$  consists of the  $(n-1)$ -element subsets of  $S$ . We claim that any  $K$ -terminal network  $G$  with  $C(G, K) = C$  has at least  $|C^*| = n$  terminals. Suppose instead that such a  $G$  has fewer than  $n$  terminals; using modification (2) above we may presume that no two terminals are adjacent in  $G$ . There must be at least one element of  $C^*$  which is not the neighbor-set of a terminal; as mentioned above, this element of  $C^*$  must be a minimal vertex cut of  $G$  which separates at least two terminals. Suppose  $\{1, \dots, n-1\}$  is such a vertex cut.

Consider the subgraph  $H$  of  $G$  obtained by removing the non-terminal vertices  $1, \dots, n-1$  and all edges incident on them. The remaining vertices include all the terminals of  $G$  and in addition the non-terminal vertex  $n$ . If any of the terminal vertices is isolated in  $H$  then all the neighbors of that terminal in  $G$  are included among  $1, \dots, n-1$ . This is impossible, because

$\{1, \dots, n-1\}$  is not the neighbor-set of any terminal and if a proper subset  $N \subset \{1, \dots, n-1\}$  is the neighbor-set of a terminal then some subset of  $N$  is a minimal vertex cut separating that terminal from another terminal; this subset of  $N$  is then an element of  $C^*$ , contradicting the fact that all the elements of  $C^*$  have cardinality  $n-1$ . Hence none of the terminal vertices is isolated in  $H$ , so all the terminal vertices are adjacent to the non-terminal vertex  $n$ . It follows that  $H$  is connected, contradicting the assumption that  $\{1, \dots, n-1\}$  is a vertex cut of  $G$ .

### 3. Structural features of clutters

A useful visualization technique should make it easy to see structural features of the object being represented. It is a drawback of the technique we are discussing that a single clutter may be represented by many non-isomorphic  $K$ -terminal networks, because this guarantees that some of the information conveyed by each of the networks is irrelevant and potentially confusing. For example, in Figure 1 none of the edges between non-terminal vertices is of any significance.

An important structural feature of some clutters is the presence of *parallel elements*: if  $C$  is a clutter on a set  $S$  then  $s, s' \in S$  are parallel with respect to  $C$  if every  $B \in C^*$  which contains one of  $s, s'$  also contains the other. In an ordinary graph, parallel non-loop edges are not difficult to recognize: they have the same end-vertices. However, parallel non-terminal vertices in a  $K$ -terminal network may not be immediately noticeable. For instance, it may not be evident in Figure 1 (iii) - (vi) that  $d$  and  $e$  are parallel, though the similarity of their placement in Figure 1 (i) and (ii) does catch the eye. On the other hand, parallels are readily identified in networks of the type constructed in the proof of Theorem 2, for which  $C(G, K)^*$  is visible as the collection of neighbor-sets of terminal vertices.

**Proposition 3.1.** *Suppose that a 1-1 correspondence between  $K$  and  $C(G, K)^*$  is defined by associating each  $k \in K$  with  $N(k)$ . Then two non-terminal vertices of  $(G, K)$  are parallel with respect to  $C(G, K)$  if and only if they have precisely the same terminal neighbors.*

Two elements  $s, s' \in S$  are *in series* with respect to a clutter  $C$  if every  $W \in C$  which contains one of them also contains the other. Equivalently, every  $B \in C^*$  with  $s \in B$  has  $(B - \{s\}) \cup \{s'\} \in C^*$  and every  $B' \in C^*$  with  $s' \in B'$  has  $(B' - \{s'\}) \cup \{s\} \in C^*$ . Once again, this condition is fairly easy to recognize in  $K$ -terminal networks of the type constructed in the proof of Theorem 2.

**Proposition 3.2.** *Suppose that a 1-1 correspondence between  $K$  and  $C(G, K)^*$  is defined by associating each  $k \in K$  with  $N(k)$ . Then two non-terminal vertices  $s$  and  $s'$  of  $(G, K)$  are in series with respect to  $C(G, K)$  if and only if whenever  $s$  (resp.  $s'$ ) is adjacent to a terminal vertex  $k$ , there is another terminal vertex  $k'$  with neighbor-set  $N(k') = (N(k) - \{s\}) \cup \{s'\}$  (resp.  $N(k') = (N(k) - \{s'\}) \cup \{s\}$ ).*

Two operations that are important in network reliability [1] and in the combinatorial theory of clutters [5, 6] are *deletion* and *contraction*. Both of these operations are easily performed on  $K$ -terminal networks representing a clutter  $C$ . Deleting a non-terminal vertex  $v$  is accomplished by removing the vertex and all its incident edges, just as one would expect. To motivate the contraction of a vertex, consider first what it means to contract an edge in an ordinary graph: the edge's function is to provide communication between its end-vertices, and after it is contracted this communication is guaranteed. In a  $K$ -terminal network the function of a non-terminal vertex  $v$  is to provide communication among its neighbors; we contract  $v$  by removing  $v$  from the network and then guaranteeing communication among its neighbors by inserting an edge connecting each pair of elements of  $N(v)$ . If  $v$  has a terminal neighbor then the effect is the same if we leave the network unchanged except for declaring that  $v$  has become a terminal.

## 4. Generalizations

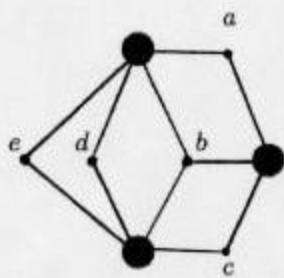
If the definition of  $C(G, K)$  is generalized to allow non-unique labeling of the non-terminal vertices of  $G$  then any clutter  $C$  may be realized by a 2-terminal network. If  $C^* = \{B_1, \dots, B_n\}$  we may construct such a network from the disjoint union of  $n$  cliques, the  $i$ th of which has vertices labeled by the elements of  $B_i$ , by making all the vertices in the  $i$ th clique adjacent to all the vertices in the  $(i+1)$ st clique for each  $i < n$ , and also making all the vertices in the first (resp.  $n$ th) clique adjacent to the first (resp. second) terminal.

Two other generalizations which may be useful are: first, to allow directed edges; and second, to consider, for  $j \in \{1, \dots, |K|\}$ , the clutter  $C_j(G, K)$  of minimal subsets  $W \subseteq V(G) - K$  such that the induced subgraph of  $G$  with vertex-set  $K \cup W$  has no more than  $j$  connected components which intersect  $K$ .

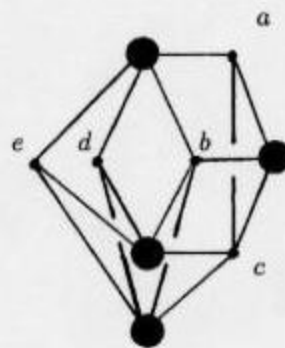
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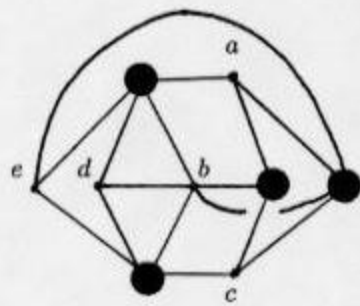
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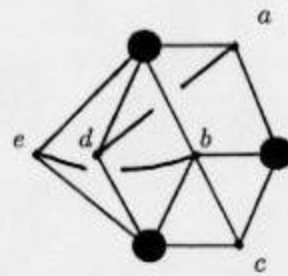
(i)



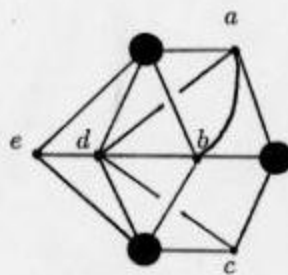
(ii)



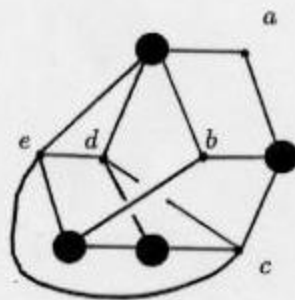
(iii)



(iv)



(v)



(vi)

Figure 1