1. Recall that the vector space $\mathfrak{sl}(2,\mathbb{R})$ of 2×2 trace 0 matrices is a subspace of $\mathcal{M}_2(\mathbb{R})$. The list

$$\left(\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right).$$

Find two different subspaces W_1 and W_2 of $\mathcal{M}_2(\mathbb{R})$ so that

$$\mathcal{M}_2(\mathbb{R}) = \mathfrak{sl}(2,\mathbb{R}) \oplus W_1 \text{ and } \mathfrak{sl}(2,\mathbb{R}) \oplus W_2.$$

Example: Since $\mathfrak{sl}(2,\mathbb{R})$ is 3 dimensional, W should be 1 dimensional. Two possible choices are

$$W_1 = \operatorname{span}\left(\begin{pmatrix} 1 & 0\\ 0 & 0 \end{pmatrix}\right)$$
$$W_2 = \operatorname{span}\left(\begin{pmatrix} 0 & 0\\ 0 & 1 \end{pmatrix}\right).$$

and

2. Let V be the subspace of \mathbb{R}^4 spanned by the vectors

$$\left(\begin{pmatrix}11\\4\\1\\10\end{pmatrix}, \begin{pmatrix}2\\1\\1\\1\end{pmatrix}, \begin{pmatrix}8\\1\\-5\\13\end{pmatrix}, \begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}\right).$$

- (a) Determine the dimension of V.Solution: V is 2 dimensional, as is shown below.
- (b) Find a basis for V.

Example: The span of the list above is a vector space, so if the list itself is dependent, then we may reduce it to a basis for V by deleting dependent vectors. Thus we look for nonzero solutions to

$$\alpha \begin{pmatrix} 11\\4\\1\\10 \end{pmatrix} + \beta \begin{pmatrix} 2\\1\\1\\1 \end{pmatrix} + \gamma \begin{pmatrix} 8\\1\\-5\\13 \end{pmatrix} + \delta \begin{pmatrix} -1\\0\\1\\-2 \end{pmatrix} = \begin{pmatrix} 0\\0\\0\\0 \end{pmatrix}.$$

Per usual, we look at the coefficient matrix

$$\begin{pmatrix} 11 & 2 & 8 & -1 \\ 4 & 1 & 1 & 0 \\ 1 & 1 & -5 & 1 \\ 10 & 1 & 13 & -2 \end{pmatrix}$$

for the corresponding matrix equation, and row reduce to find solutions:

$$\begin{pmatrix} 11 & 2 & 8 & -1 \\ 4 & 1 & 1 & 0 \\ 1 & 1 & -5 & 1 \\ 10 & 1 & 13 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & -5 & 1 \\ 11 & 2 & 8 & -1 \\ 4 & 1 & 1 & 0 \\ 10 & 1 & 13 & -2 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 1 & -5 & 1 \\ 0 & -9 & 63 & -12 \\ 0 & -3 & 21 & -4 \\ 0 & -9 & 63 & -12 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 1 & -5 & 1 \\ 0 & 1 & -7 & 4/3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 1 & -5 & 1 \\ 0 & 1 & -7 & 4/3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 0 & 2 & -1/3 \\ 0 & 1 & -7 & 4/3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 0 & 2 & -1/3 \\ 0 & 1 & -7 & 4/3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} .$$

Thus γ and δ are free variables, and we parametrize them accordingly, say $\gamma = 1$, $\delta = 3$, so that $\alpha = -1$ and $\beta = 3$. Thus

$$-\begin{pmatrix}11\\4\\1\\10\end{pmatrix}+3\begin{pmatrix}2\\1\\1\\1\end{pmatrix}+\begin{pmatrix}8\\1\\-5\\13\end{pmatrix}+3\begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}=\begin{pmatrix}0\\0\\0\\0\end{pmatrix},$$

and we rewrite

$$\begin{pmatrix} 11\\4\\1\\10 \end{pmatrix} = 3 \begin{pmatrix} 2\\1\\1\\1 \end{pmatrix} + \begin{pmatrix} 8\\1\\-5\\13 \end{pmatrix} + 3 \begin{pmatrix} -1\\0\\1\\-2 \end{pmatrix} .$$

Thus

$$\operatorname{span}\left(\begin{pmatrix}11\\4\\1\\10\end{pmatrix}, \begin{pmatrix}2\\1\\1\\1\end{pmatrix}, \begin{pmatrix}8\\1\\-5\\13\end{pmatrix}, \begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}\right) = \operatorname{span}\left(\begin{pmatrix}2\\1\\1\\1\\1\end{pmatrix}, \begin{pmatrix}8\\1\\-5\\13\end{pmatrix}, \begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}\right);$$

if these three vectors are independent, then they form a basis for V. We check using the same process:

$$\begin{pmatrix} 2 & 8 & -1 \\ 1 & 1 & 0 \\ 1 & -5 & 1 \\ 1 & 13 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 4 & -1/2 \\ 0 & -3 & 1/2 \\ 0 & -9 & 3/2 \\ 0 & 9 & -3/2 \end{pmatrix}$$
$$\rightarrow \begin{pmatrix} 1 & 4 & -1/2 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
$$\rightarrow \begin{pmatrix} 1 & 0 & 1/6 \\ 0 & 1 & -1/6 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Again, we have a free variable: parameterizing c = 6, so that b = 1 and a = -1, we have

$$-\begin{pmatrix} 2\\1\\1\\1 \end{pmatrix} + \begin{pmatrix} 8\\1\\-5\\13 \end{pmatrix} + 6\begin{pmatrix} -1\\0\\1\\-2 \end{pmatrix} = \begin{pmatrix} 0\\0\\0\\0 \end{pmatrix},$$

again rewriting as

$$\begin{pmatrix} 2\\1\\1\\1 \end{pmatrix} = \begin{pmatrix} 8\\1\\-5\\13 \end{pmatrix} + 6 \begin{pmatrix} -1\\0\\1\\-2 \end{pmatrix}.$$

$$\begin{pmatrix} 8\\1 \end{pmatrix} \begin{pmatrix} -1\\0 \end{pmatrix} = \begin{pmatrix} 6\\1\\-2 \end{pmatrix} \begin{pmatrix} 8\\1 \end{pmatrix} \begin{pmatrix} -1\\0\\-2 \end{pmatrix} \begin{pmatrix} 8\\1\\-2 \end{pmatrix} \begin{pmatrix} 8\\1\\$$

 \mathbf{So}

$$\operatorname{span}\left(\begin{pmatrix}2\\1\\1\\1\end{pmatrix}, \begin{pmatrix}8\\1\\-5\\13\end{pmatrix}, \begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}\right) = \operatorname{span}\left(\begin{pmatrix}8\\1\\-5\\13\end{pmatrix}, \begin{pmatrix}-1\\0\\1\\-2\end{pmatrix}\right);$$

these last two vectors are clearly independent, so the list

$$\left(\begin{pmatrix} 8\\1\\-5\\13 \end{pmatrix}, \begin{pmatrix} -1\\0\\1\\-2 \end{pmatrix}\right)$$

is a basis for V.

3. Let

$$A = \begin{pmatrix} 1 & -1 & 4 \\ 2 & -1 & 5 \\ 1 & 0 & 1 \end{pmatrix}.$$

and

We can think of the columns of A as vectors in \mathbb{R}^3 . The subspace of \mathbb{R}^3 spanned by the columns of A is called the *column space* of A, denoted by column(A).

(a) Find two nonzero vectors in column(A).

Example: We could, of course, just pick two columns of A, but more interesting possibilities are (.) 1.1

$$\begin{pmatrix} 6\\8\\2 \end{pmatrix} = 2 \begin{pmatrix} 1\\2\\1 \end{pmatrix} - 4 \begin{pmatrix} -1\\-1\\0 \end{pmatrix}$$
$$\begin{bmatrix} 4\\-4\\0 \end{pmatrix} = \begin{pmatrix} 1\\2\\1 \end{pmatrix} + \begin{pmatrix} -1\\-1\\0 \end{pmatrix} - \begin{pmatrix} 4\\5\\1 \end{pmatrix}.$$

(b) Show that column $(A) \neq \mathbb{R}^3$ using an argument on the determinant of A. Solution: Since det(A) = 0, there are nontrivial solutions to the matrix equation

$$\begin{pmatrix} 1 & -1 & 4 \\ 2 & -1 & 5 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

i.e. there are nonzero scalars such that

$$x_1 \begin{pmatrix} 1\\2\\1 \end{pmatrix} + x_2 \begin{pmatrix} -1\\-1\\0 \end{pmatrix} + x_3 \begin{pmatrix} 4\\5\\1 \end{pmatrix} = \begin{pmatrix} 0\\0\\0 \end{pmatrix}.$$

Thus the three vectors are *not* independent, so that column $(A) \neq \mathbb{R}^3$.

(c) Find a basis for column (A) and determine the dimension of column (A). *Example*: Since the list of vectors

$$\left(\begin{pmatrix} 1\\2\\1 \end{pmatrix}, \begin{pmatrix} -1\\-1\\0 \end{pmatrix}, \begin{pmatrix} 4\\5\\1 \end{pmatrix} \right)$$

is not independent, but *does* span column (A), it contains a basis for column (A); deleting one (or two) carefully chosen vectors will result in the desired basis.

In essence, we would like to find a nonzero solution to the matrix equation

$$\begin{pmatrix} 1 & -1 & 4 \\ 2 & -1 & 5 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

. . .

so let's begin by row-reducing the coefficient matrix:

$$\begin{pmatrix} 1 & -1 & 4 \\ 2 & -1 & 5 \\ 1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 4 \\ 0 & 1 & -3 \\ 0 & 1 & -3 \end{pmatrix}$$
$$\rightarrow \begin{pmatrix} 1 & -1 & 4 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{pmatrix} .$$
$$\rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{pmatrix} .$$

Thus x_3 is free; choosing $x_3 = 1$, we have $x_2 = 3$ and $x_1 = -1$. Thus

$$-\begin{pmatrix}1\\2\\1\end{pmatrix}+3\begin{pmatrix}-1\\-1\\0\end{pmatrix}+\begin{pmatrix}4\\5\\1\end{pmatrix}=\begin{pmatrix}0\\0\\0\end{pmatrix},$$
$$\begin{pmatrix}1\\2\\1\end{pmatrix}=3\begin{pmatrix}-1\\-1\\0\end{pmatrix}+\begin{pmatrix}4\\5\\1\end{pmatrix}.$$
$$\begin{pmatrix}1\\2\\1\end{pmatrix}$$

Since

so that

is a linear combination of the other two vectors, we may safely remove it from the list. Thus

$$\left(\begin{array}{c} \begin{pmatrix} -1\\ -1\\ 0 \end{pmatrix}, \begin{array}{c} \begin{pmatrix} 4\\ 5\\ 1 \end{pmatrix} \right)$$

still spans column (A), and we can quickly row-reduce the resulting coefficient matrix to see that the vectors above are linearly independent:

$$\begin{pmatrix} -1 & 4\\ 1 & 5\\ 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -4\\ 1 & 5\\ 0 & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -4\\ 0 & 9\\ 0 & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -4\\ 0 & 9\\ 0 & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0\\ 0 & 1\\ 0 & 0 \end{pmatrix},$$

so that a = b = 0 is the only solution to

$$\begin{pmatrix} -1 & 4\\ 1 & 5\\ 0 & 1 \end{pmatrix} \begin{pmatrix} a\\ b \end{pmatrix} = \begin{pmatrix} 0\\ 0\\ 0 \end{pmatrix}.$$

Thus

$$\left(\begin{array}{c} \begin{pmatrix} -1\\ -1\\ 0 \end{pmatrix}, \begin{array}{c} \begin{pmatrix} 4\\ 5\\ 1 \end{pmatrix} \right)$$

is a basis for column (A), and dim(column (A)) = 2.

4. Let V be the subspace of $\mathcal{P}_4(\mathbb{R})$ of all vectors $p \in \mathcal{P}_4(\mathbb{R})$ so that

$$p''(1/2) = 0$$

(a) Find a basis for V. Example: If $p \in V$ with

$$p(x) = \alpha x^4 + \beta x^3 + \gamma x^2 + \delta x + \lambda,$$

then

$$p''(x) = 12\alpha x^2 + 6\beta x + 2\gamma,$$

so that

$$0 = p''(1/2)$$

= $3\alpha + 3\beta + 2\gamma$.

We have

$$\gamma = -\frac{3}{2}\alpha - \frac{3}{2}\beta,$$

so that

$$p(x) = \alpha x^4 + \beta x^3 + (-\frac{3}{2}\alpha - \frac{3}{2}\beta)x^2 + \delta x + \lambda.$$

Thus every vector in V may be written in the form

$$p(x) = \alpha(x^4 - \frac{3}{2}x^2) + \beta(x^3 - \frac{3}{2}x^2) + \delta x + \lambda,$$

so that the vectors

$$x^4 - \frac{3}{2}x^2, \ x^3 - \frac{3}{2}x^2, \ x, \ 1$$

form a spanning list for V. It is straightforward to show that this list is also independent, so the list

$$(x^4 - \frac{3}{2}x^2, x^3 - \frac{3}{2}x^2, x, 1)$$

is also a basis for V.

(b) Extend the basis to a basis for $\mathcal{P}_4(\mathbb{R})$.

Example: V itself is 4 dimensional, and $\mathcal{P}_4(\mathbb{R})$ is 5 dimensional, so we need to add a single vector to the basis to extend it to a basis for all of $\mathcal{P}_4(\mathbb{R})$. I claim that we can add x^2 and maintain independence of the list; to be certain, we check the coefficient matrix for the system

$$\alpha(x^4 - \frac{3}{2}x^2) + \beta(x^3 - \frac{3}{2}x^2) + \delta x + \lambda + \mu x^2 = \mathbf{0}.$$

The matrix is

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ -3/2 & -3/2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix},$$

which has determinant 1. Since the determinant is nonzero, the only solution to the matrix equation

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ -3/2 & -3/2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \\ \delta \\ \lambda \\ \mu \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

is the trivial solution

$$\begin{pmatrix} \alpha \\ \beta \\ \delta \\ \lambda \\ \mu \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

Thus the vectors are independent, and the list

$$(x^4 - \frac{3}{2}x^2, x^3 - \frac{3}{2}x^2, x, 1, x^2)$$

is a basis for $\mathcal{P}_4(\mathbb{R})$.

5. Prove that every subspace of \mathbb{R}^3 is either $\{\mathbf{0}\}$, a line through the origin, or a plane through the origin.

Solution: Every subspace V of \mathbb{R}^3 must have dimension

$$\dim(V) \le 3.$$

If dim V = 3, then clearly $V = \mathbb{R}^3$.

We handle the remaining cases separately:

(a) dim V = 0: Then the empty list is a basis for V, and span () = $\{0\}$.

(b) dim V = 1: Then there is a single vector $u \neq \mathbf{0}$ in \mathbb{R}^3 so that

$$V = \operatorname{span}(u),$$

say

$$u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}.$$

Then every vector $v \in V$ may be written in the form

$$v = \alpha \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} \alpha u_1 \\ \alpha u_2 \\ \alpha u_3 \end{pmatrix},$$

 $\alpha \in \mathbb{R}$. Now the set of all scalar multiples of a nonzero vector in \mathbb{R}^3 is a line, and particular this line must pass through the origin $(\alpha = 0)$.

(c) dim V = 2: There is a pair of (nonzero) vectors $u, v \in \mathbb{R}^3$ so that

$$V = \operatorname{span}\left(u, \ v\right),$$

say

$$u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}, \ v = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}.$$

Then every vector $w \in V$ may be written in the form

$$w = \alpha \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} + \beta \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix},$$

 $\alpha, \beta \in \mathbb{R}$. But the set of all vectors of this form is just a plane in \mathbb{R}^3 , again passing through the origin since we can set $\alpha = \beta = 0$.

6. Prove that if U and W are both 5 dimensional subspaces of \mathbb{R}^9 , then $U \cap W \neq \{\mathbf{0}\}$.

Solution:

Recall that

$$\dim(U+W) = \dim U + \dim W - \dim(U \cap W)$$

If $U \cap W = \{\mathbf{0}\}$, then $\dim(U \cap W) = 0$, and we have

$$\dim(U+W) = \dim U + \dim W = 10$$

However, U + W is a subspace of the 9 dimensional vector space V; we now have a contradiction, since the dimension of a subspace of V cannot be more than the dimension of V itself. Thus $U \cap W \neq \{0\}$.

7. The notation

 $\dim_{\mathbb{F}}(V)$

denotes the dimension of V as a vector space over field \mathbb{F} .

Let V be any vector space over \mathbb{C} . Since $\mathbb{R} \subset \mathbb{C}$, V is also a vector space over \mathbb{R} . Prove that

 $\dim_{\mathbb{R}}(V) = 2 \dim_{\mathbb{C}}(V).$

Solution: Suppose that $\dim_{\mathbb{C}}(V) = n$; that is, every basis of V over \mathbb{C} contains n vectors. Let

$$B_{\mathbb{C}} = (v_1, v_2, \ldots, v_n)$$

be one such basis.

I claim that

$$B_{\mathbb{R}} = (v_1, v_2, \ldots, v_n, iv_1, iv_2, \ldots, iv_n)$$

is a basis for V over \mathbb{R} . To prove the claim, we need to show that $B_{\mathbb{R}}$ is independent and spanning.

To show that $B_{\mathbb{R}}$ spans V over \mathbb{R} , suppose that $v \in V$. Now $B_{\mathbb{C}}$ spans V over \mathbb{C} , so we know that there constants $\alpha_j \in \mathbb{C}$ so that

$$\alpha_1 v_1 + \alpha_2 v_2 + \ldots + \alpha_n v_n = v.$$

Of course, each α_j may be rewritten as

$$\alpha_i = a_i + ib_i,$$

 $a_j, b_j \in \mathbb{R}$, so that we may rewrite v as a linear combination of vectors in $B_{\mathbb{R}}$ as follows:

$$v = \alpha_1 v_1 + \alpha_2 v_2 + \ldots + \alpha_n v_n$$

= $(a_1 + b_1 i)v_1 + (a_2 + b_2 i)v_2 + \ldots + (a_n + b_n i)v_n$
= $a_1 v_1 + a_2 v_2 + \ldots + a_n v_n + b_1(iv_1) + b_2(iv_2) + \ldots + b_n(iv_n);$

since all of the scalars above are elements of \mathbb{R} , this is the desired linear combination of vectors in $B_{\mathbb{R}}$, which clearly spans V over \mathbb{R} .

To show that the vectors are independent over \mathbb{R} , recall that the only constants $\alpha_i \in \mathbb{C}$ so that

$$\alpha_1 v_1 + \alpha_2 v_2 + \ldots + \alpha_n v_n = \mathbf{0}$$

are

$$\alpha_1 = \alpha_2 = \ldots = \alpha_n = 0.$$

Thus if

$$a_1v_1 + a_2v_2 + \ldots + a_nv_n + b_1(iv_1) + b_2(iv_2) + \ldots + b_n(iv_n) = \mathbf{0}$$

we may rewrite this as a linear combination of vectors in $B_{\mathbb{C}}$ by setting $\beta_j = a_j + ib_j$. Then we have

$$0 = a_1v_1 + a_2v_2 + \ldots + a_nv_n + b_1(iv_1) + b_2(iv_2) + \ldots + b_n(iv_n)$$

= $\beta_1v_1 + \beta_2v_2 + \ldots + \beta_nv_n$,

so that $\beta_j = 0$ for all j by the above argument. Thus $a_j = b_j = 0$ for all j, and the vectors in $B_{\mathbb{R}}$ are independent over \mathbb{R} .