

SPP tutorial for BIOL357 Spring 2023

All the *m*-files you need to do this tutorial is in the folder SPP that you should now have on your desktop and from the previous Matlab/Netlogo tutorial you know how to operate Matlab and run such *m*-files.

ATTRACTION ONLY (The Local Attraction Model.)

Here you will investigate the attraction only model without a blind angle. Review the lecture slides so you know what the model parameters represents and how the model works. You will only vary the model parameter c here. All other model parameters have been fixed to $d=1$, $R=4$, $\delta=0.5$. You also have to specify the number of time steps t you want the simulation to run for.

1. To complete a) and b) below you will use the command `LAM(c, t)` to generate all three groups known to be produced by this model. Hint: One figure on slide 30 in Lecture 6 may be helpful.

a) Start by running the command with $c=0.15$ and $t=2000$. Keep watching the animation until the simulation stops, save the figure, and close the figure window. You **will** get one of the three groups you are looking for here, be **patient** and observe, it will eventually happen.

b) Now set $t=50$ and run new simulations by slowly increasing c from 0.35 (in increments of 0.2). If the group you are looking for hasn't appeared when the simulation stops, increase c a bit and try again. Once you got one of the groups write down the c value used to generate it and save the figure. Continue until you have c values and figures for all three groups.

ATTRACTION AND ORIENTATION

Here you will explore how adding orientation affects group formation in the LAM.

2. Use the command `LAMO(o, c)` to investigate how increasing the relative strength of orientation o affects the formation and persistence of the groups you found in exercise 1. That is, use the same c value you used to obtain each particular group in 1 (mill, polarized, swarm) and run a sequence of simulations with increasing o from $o=0.05$ (in increments of 0.05) with this same c and observe how the resulting group is affected by increasing o .

How much orientation does it take to significantly affect the formation and/or behavior of each type of group? That is, when o increases above some value another type of group forms, or the same group forms but much faster/slower. Write down an estimate of this o value for each type of group. Save figures showing what the 'significantly affected' groups look like.

ATTRACTION ONLY WITH A BLIND ZONE

Here we will study the attraction only model with a blind zone and will only vary the parameter d . All other parameters are fixed to $c=1$, $R=4$, $\delta=0.5$, and the angle specifying the blind zone is 2 radians ≈ 115 degrees.

3. Use the command `LAMB(d, t)` to generate a String, an Oriented Mill, and a Figure of Eight. Use one of the figures on lecture slide 32 to guide your choice of d values to try. Once you got one of the groups, write down the d value used. Also use the **ZOOM tool** in the Matlab figure window to zoom in on the group and then save it as a **png** figure.

String(s): Use $t=300$. If no string has formed by then change the d value and try again.

Oriented Mill: Use $t=500$. If you get non-oriented mills try again. (To save time, if a non-oriented mills has formed you may stop the simulation by closing the figure window.)

Figure of Eight: Use $t=1500$. Do not mistake something else for a Figure of Eight! The Figure of Eight moves across the figure window in a fairly straight line. It is never stationary or rotate around a fixed point, that would be something else. Also, you may have to run several simulations (even with a good d value) before a figure of eight emerges.

ATTRACTION & REPULSION IN A WALLED-OFF REGION

Here you will work with an attraction-repulsion model where the particles move inside a walled-off rectangular area rather than on a doughnut shaped (torus) environment as before.

4. In a)-c) below you will use the command `LARWM(β, N)` to explore the potential existence of transitional behavior between milling and polarized groups by varying the size of the blind zone via the blind angle parameter β .

a) If $\beta=2.5$ we get milling groups, and if $\beta=3.35$ we get polarized groups. Verify this by running a simulations for each of these β values with $N=100$.

b) This suggests that something interesting happens for some β values between 2.5 and 3.35 . Two possible scenarios A and B are

A. As β is increased from 2.5 to 3.35 there is a value of β , a threshold of sorts, at which the model entirely stop producing mills and from then on only produce polarized groups.

or

B. For some range of β values between 2.5 and 3.35 the model produces groups that continuously transition between milling an polarized motion.

Try to figure out which scenario most accurately describe what is going on by varying β in some appropriate way. Again using $N=100$. Describe how you decided to vary β and motivate which of the scenarios A and B you think is most likely. If neither A or B are any good, what actually happened?

c) Pick the β value that generated the most interesting behavior in b) and try a few different N values (e.g. $30, 70, 150$). Save the most interesting figure you obtained.

THE SHEPHERDING MODEL

5. Here you will use the command `SHEEP (N, n, t)` to study a shepherding algorithm. N is the total number of sheep and n is the number of neighbors a sheep has (topological interactions). If $n \approx N-1$ all sheep are attracted to all other sheep. If $n=0$ a sheep is not attracted to other sheep at all and will run off on its own if the dog approaches. t is the maximum simulation time and the simulation will stop before then if the sheep has been delivered to the target (green asterisk).

Pick an N between **30** and **60** and run **two** simulations with $n=N-1$ and $t=2000$. Does the dog manage to herd the sheep to the target? If yes, decrease n by an appropriate amount and run **two** simulations (keeping N and t the same). Keep decreasing n until the dog fails in both simulations for a particular n . Write down the largest n at which failure occurred, the N used, and save the figure. Note that it can happen that the dog never fails, even at $n=0$. In this case write down $n=0$ and save the figure.

END OF SPP-MODEL TUTORIAL

How to make an mp4 movie of a simulation

1. **Immediately** after the simulation has stopped type (or copy paste) **exactly** `MakeMovie(ans)` on the command line i.e.

```
>> MakeMovie(ans)
```

and press enter.

2. A file called filename.mp4 should now have appeared in your SPP folder. **Manually change the filename** to something else, e.g. oddthing.mp4.

Important

- If you run another command in between 'simulation stop' and 'movie making' **no movie** will be created. (`ans` is the output of the last command executed in Matlab).

- If you forget to rename the file so that it is still called filename.mp4 the next time you make a movie the old one will be overwritten and **lost forever**.