



# SCADA- Supervisory Control and Data Acquisition System

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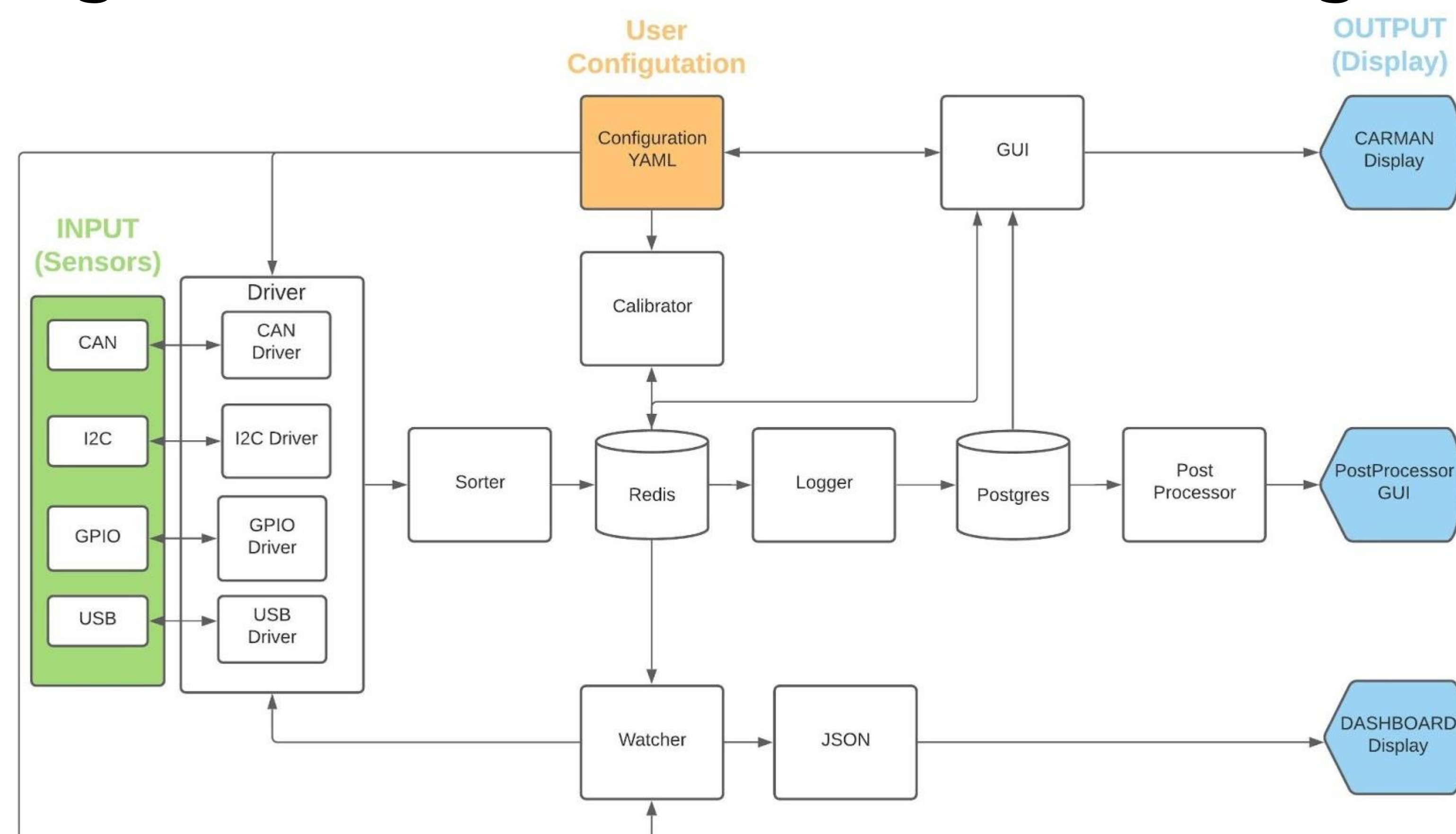


A joint project of the Lafayette College ECE and ME Departments

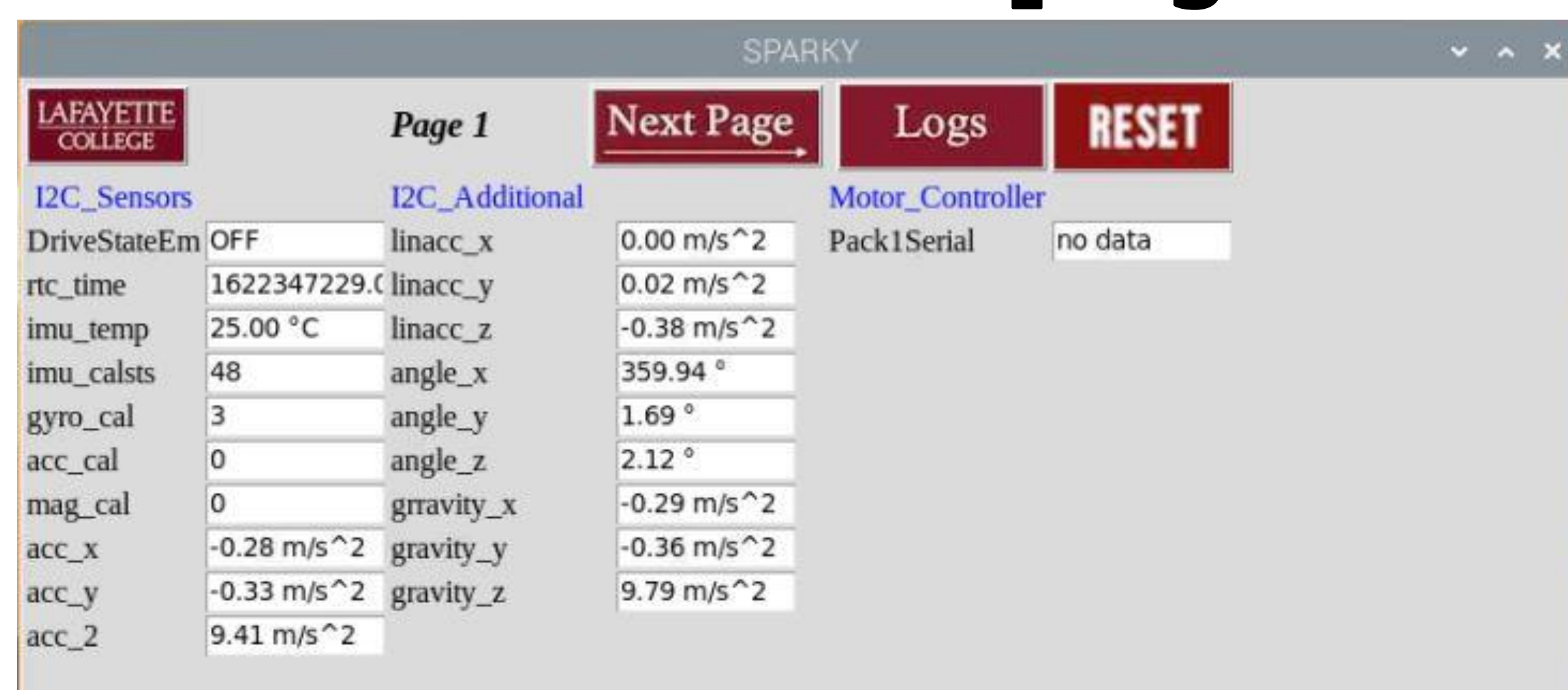
## Overview

The SCADA (Supervisory Control and Data Acquisition) system is a maintainable, configurable system that reads and writes to a network of sensors on the vehicle. There is currently support for reading I2C, CAN, Parallel IO, and USB sensors. SCADA includes active system control which logs errors, sends warnings, or writes to sensors based on conditions defined in the configuration file. A post-processor allows for data collected during a drive session of the car to be analyzed after the fact.

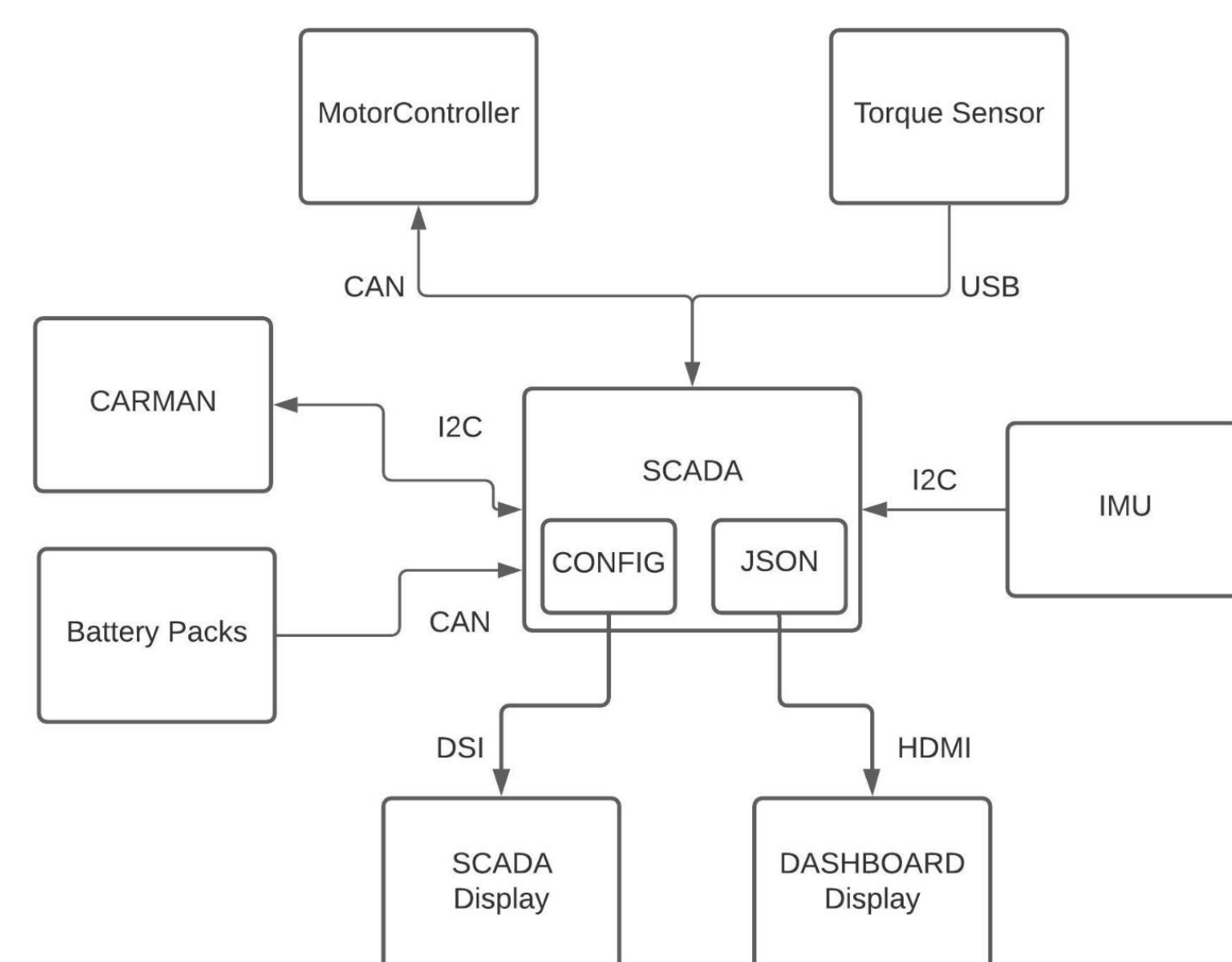
## High-Level Software Architectural Diagram



## Live Data Display



## Hardware Diagram



## Passive Data Acquisition

**Driver** consists of read and write methods for I2C, CAN, USB, and GPIO sensors  
**Sorter** polls raw data from sensors  
**Calibrator** uses config to calibrate raw data  
**Logger** stores final data into **Postgres** database for post processing

## Active Control

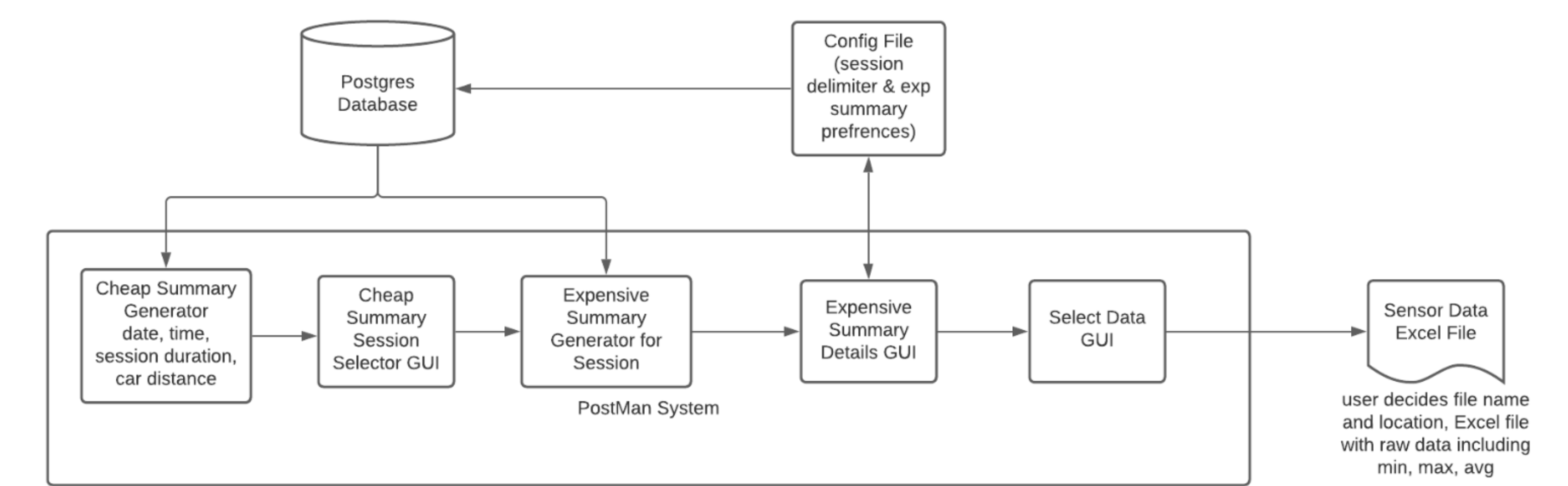
The **Watcher** module handles the active control aspect of the SCADA system. It checks for changes in sensor values and triggers various actions. One of the major roles of the **Watcher** is to trigger the safety relay whenever cooling temperature exceeds a critical value.

## Sensor Configuration

Sensors and actions can easily be added and modified to specify how the sensor data is displayed, how often that sensor is polled, and how that data is read/calibrated using the configuration file. Below is an example of how a sensor is configured.

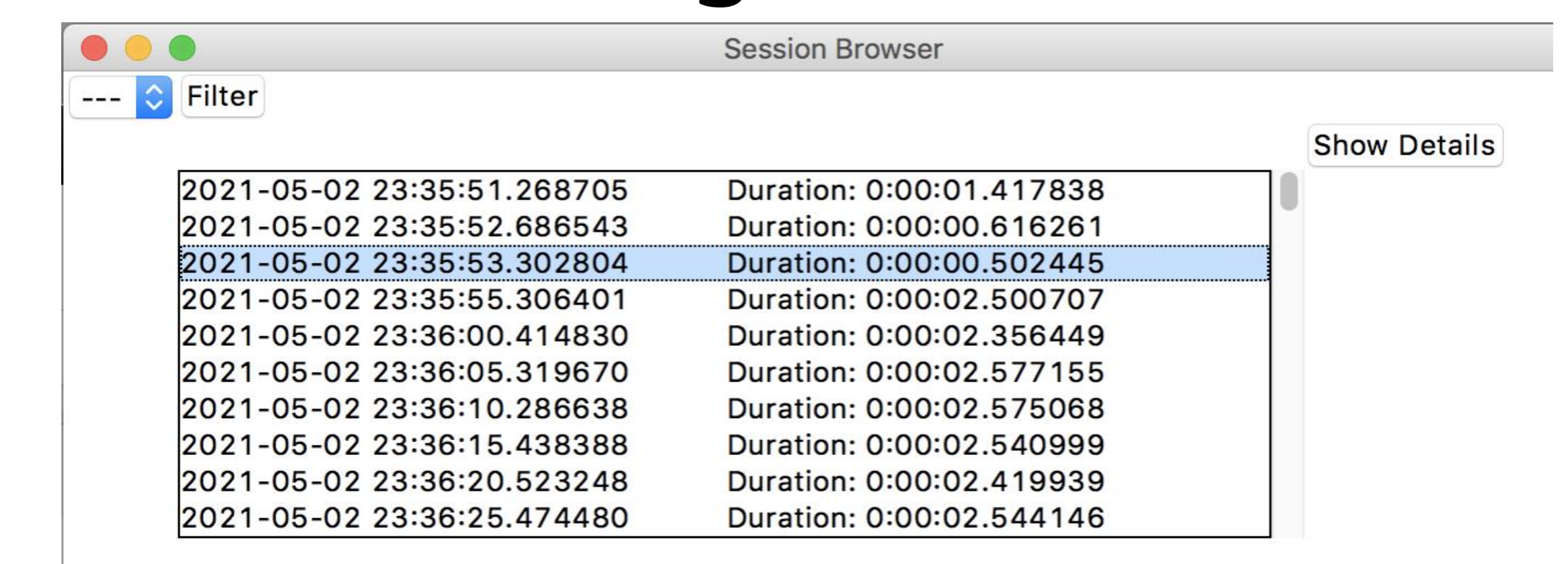
```
gravity_x:
  unit: 'm/s^2'
  inputs:
    In: gravity_x
  cal_function:
    'In>1000': ' (-1) * (65536-In) * (1/100) '
    'In<=1000': 'In*(1/100) '
  bus_type: I2C
  primary_address: 0x28
  secondary_address: [0x2E,0x2F]
  precision: 2
  display_variable: number
  description: "IMU Gravity X Component"
  bit_length: 8
  sample_period: 0.2
  var_name: gravity_x
```

## Post-Processing Architectural Diagram



**Postman** is the post-processing component of SCADA. It uses past data stored in the **Postgres** database to organize "drive sessions" that a user can select to export specific sensor data to an **Excel** spreadsheet for further analysis.

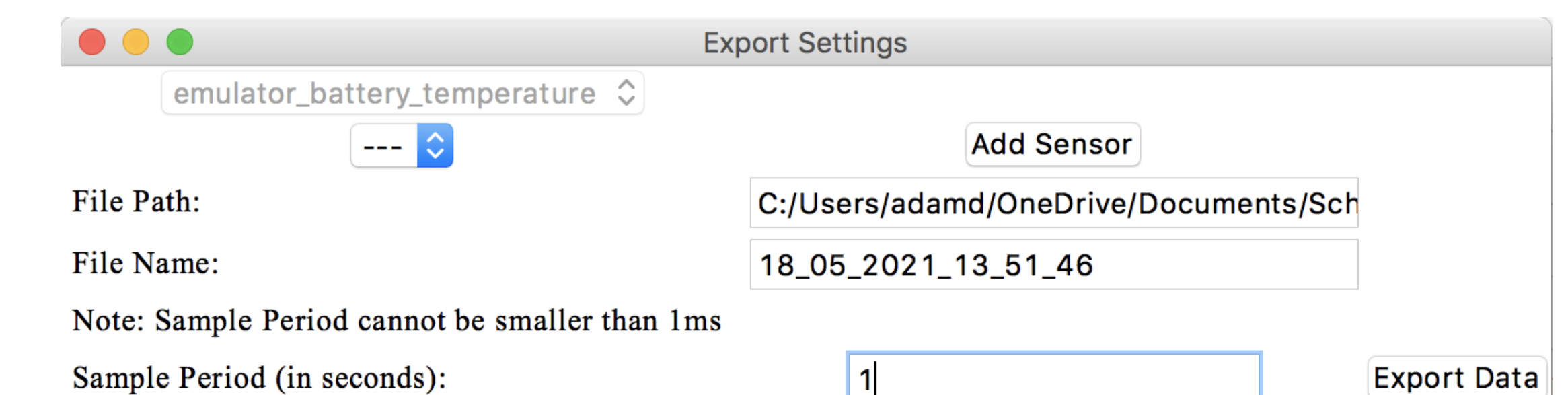
## Post Processing Session Browser



Session Preview: 2021-05-12 04:45:45.313193 Duration: 0:00:17.448923

sensor_id	mean	minimum	maximum
emulator_car_mph	20.38888888888889	0.0	40.0
emulator_engine_temperature	147.61764705882354	72.0	200.0
emulator_battery_percentage	16.661111111111111	0.5	39.2

Export Session



**Website QR**  
 Scan this code to view the car on our website!

