

Dynamometer Acceptance Testing Plan

ECE 492 - Spring 2019

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Abstract

This document details the acceptance test plan for the dynamometer system being developed for the Lafayette Formula Electric Vehicle Design Project.

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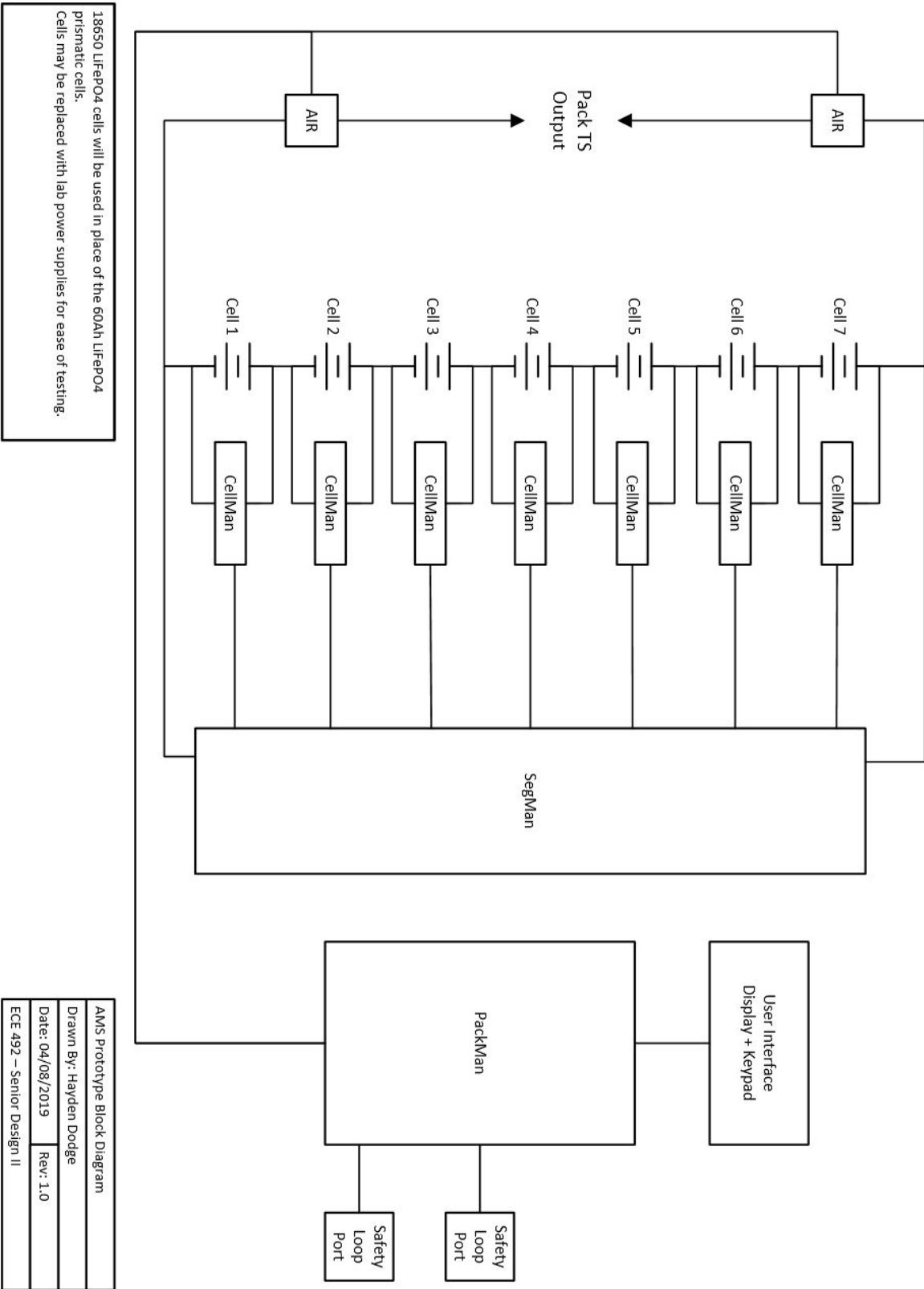
System Summary

This semester we will deliver a dynamometer room integrated with GLV, TSI, SCADA, and Cooling systems. Additionally we will deliver a battery system prototype. This document explains all of the tests we plan to run on the system. In our compliance matrix, we list each requirement that will be met, which design document is associated with the system being tested, and how the requirement is being met, whether through testing, analysis, inspection, or some combination thereof.

Dynamometer Testing Block Diagram

https://sites.lafayette.edu/motorsports/files/2019/04/ATP_2019_v1.1.0.pdf

TSV/AMS Testing Block Diagram



18650 LiFePO4 cells will be used in place of the 60Ah LiFePO4 prismatic cells.
Cells may be replaced with lab power supplies for ease of testing.

AMS Prototype Block Diagram	
Drawn By: Hayden Dodge	
Date: 04/08/2019	Rev: 1.0
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Compliance Matrix

Design documents needed to show requirement compliance will be linked to in the Acceptance Testing Report. (ATR) ATP Test Results will be in the ATR. Analysis documentation will be uploaded to the website and referenced in the ATR. Inspection reports will be uploaded to the website and referenced in the ATR.

Requirements	Design Document	ATP Test Procedure	Analysis Document	Inspection Report
GPR001		10		
GPR006		8		
GPR007		8		
GPR008		10		
T7.4.1		4.9		
EV2.8.3		4.2		
EV9.3.3		9.3		
EV9.6		9.3		
EV2.10.1		4.1		
EV2.10.3		1.1, 1.3		
EV2.11.2		1.8, 9.1, 9.2, 9.3		
EV3.5.2		1.2		
EV3.5.3		1.2		
EV3.5.4		1.2		
EV3.5.5		1.2		
EV3.5.9		1.4		
EV7.1.1		1.4, 2.1		
EV7.3.1		1.5, 2.1		
EV7.4.1		2.1, 2.4		

EV7.4.3		2.6		
EV7.5.4		2.1		
EV7.6.3		2.1, 2.3		
EV7.6.5		1.6		
EV7.7.1		1.4, 3.1		
EV7.7.2		1.1, 1.2		
EV7.8.2		1.1, 4.3, 4.4, 4.5, 4.6		
EV7.9.6		1.7		
EV7.9.7		1.7		
EV9.1.3		4.8		
EV9.1.8		4.7		
EV9.2.1		1.1, 1.2		
EV9.3.3		1.1, 1.4, 1.5, 1.8, 2.2, 9.3		
EV9.3.4		1.3, 1.6, 1.7, 2.2		
EV9.4.1		1.7		
EV9.4.2		1.7		
EV9.6		9.3		
EV10.1.2		1.7		
EV10.4		1.8, 9.3		

Waived Requirements

Requirement	Reason
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GPR003	EM testing
GPR004	
EV2.1.2	Will not be using pouch type cells
EV2.4.10	Accumulator Containers will not be completely sealed
EV2.5.5	Will not be using a monocoque
EV2.6.3	Will not be using nPmS connections
EV2.6.4	Will not be using nSmP
EV2.6.5	Will not be reducing fuse ratings
EV2.6.6	Will not be reducing fuse ratings
EV2.10.2	Will not be using a timed circuit for the pre-charge
EV2.10.6	Will not be using an always-on discharge circuit
EV2.12	Will not be using Virtual Accumulators
EV3.1.8	Will not be using interlocks
EV3.1.10	Will not be meeting rain test requirements
EV3.2.6	Will not be using conduit
EV3.2.7	Will not be using conduit
EV3.2.8	Will not be using outboard wheel motors or TS cabling outside the roll hoop
EV3.5.2	Will not be producing a foot pedal
EV3.5.3	Will not be producing a foot pedal
EV4.1.5	Will not be using a battery, will be using Shore Power
EV4.1.6	Will not be using a wet-cell battery
EV5.2.1	Will not be using conduit
EV7.3.3	Will not be using GLV charging system such as alternators or DC/DC converters
EV7.9.6	Will not be using latching circuitry for the IMD

EV9.1.2	Will be using an amber TSAL
EV10.5	Will not be conducting rain test
EV11	Will not be using pouch type cells
EV12.3.2	Will not be using and hand cart with a brake
EV12.3.3	Will not be using a hand cart with a brake

1. System State Integration

1.1 Non-Drive State Throttle Demo

- Summary: Follow the start up procedure but do not press the drive button. Slowly increase the throttle to observe if the motor spins.
- Requirements Met: EV7.7.2, EV 7.8.2, EV9.2.1, EV9.3.3, EV2.10.3
- Measurement:
- Materials: Voltmeter
- Pass Criteria:
 - a. Pre-charge operated (SCADA reported TSI state is Drive_Setup)
 - b. SSOK Lights are illuminated
 - c. TSAL is illuminated
 - d. Wheels do not rotate when the pedal is pressed

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

1.2 Drive State Throttle Demo

- Summary: Follow the start up procedure and put the system into drive mode. Slowly increase the throttle to observe if the motor spins. Interrupt the torque command signal by causing the throttle to be implausible and ensure the motor stops spinning.
- Requirements Met: EV3.5.2, EV3.5.3, EV3.5.4, EV3.5.5, EV7.7.2, EV9.2.1
- Measurement:
- Materials: Stopwatch
- Pass Criteria:
 - a. Ready To Drive Sound occurs when drive button is pressed and lasts for 1-3 seconds
 - b. Motor does not rotate before throttle is applied
 - c. Motor rotates when throttle is applied
 - d. When the throttle pots are returned to their original position the motor stops spinning
 - e. When throttle is applied and the torque command signal is interrupted, the motor slows down within 1 second

- f. SCADA indicates Throttle Implausibility after interrupting torque command signal.

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL
- e. PASS / FAIL
- f. PASS / FAIL

Test Observed By: _____ Date: _____

1.3 Cockpit BRB During Precharge

- Summary: Follow the start up procedure but do not press Cockpit Reset to turn on high voltage. Begin precharge, but open the Cockpit BRB during precharge. Ensure that precharge is disabled.
- Requirements Met: EV2.10.3, EV9.3.4
- Measurement: N/A
- Materials: Stopwatch
- Pass Criteria:
 - a. Precharge does is not allowed to reach completion when Cockpit BRB is opened during Precharge process
 - b. Precharge is allowed to reach completion when Cockpit BRB is not opened during Precharge process

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

1.4 Brake Over Travel Switch During Drive State Demo

- Summary: Follow the start up procedure and put the system in drive mode. Once throttle has been applied, open the Brake Overtravel Switch to ensure that the motor stops spinning. Verify by hand that the motor is free spinning.
- Requirements Met: EV3.5.9, EV7.1.1, EV9.3.3

- Measurement: N/A
- Materials: Stopwatch
- Pass Criteria:
 - a. SSOK lights are not illuminated after Brake Overtravel Switch is opened.
 - b. AIRs are open after the Brake Overtravel Switch is pressed
 - c. Motor stops spinning within 60 seconds.
 - d. Motor is free spinning.

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

1.5 GLVMS During Drive State Demo

- Summary: Follow the start up procedure and put the system in drive mode. Once throttle has been applied, open the GLVMS to ensure that the motor stops spinning.
- Requirements Met: EV7.3.1, EV9.3.3
- Measurement: N/A
- Materials: Stopwatch
- Pass Criteria:
 - a. SSOK lights are not illuminated after GLVMS is opened.
 - b. AIRs are open after the GLVMS is opened
 - c. Motor stops spinning within 60 seconds.

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

1.6 TSMS During Drive State Demo

- Summary: Follow the start up procedure and put the system in drive mode. Once throttle has been applied, open the TSMS to ensure the motor stops spinning.
- Requirements Met: EV7.6.5, EV 9.3.4
- Measurement: N/A

- Materials: Stopwatch
- Pass Criteria:
 - a. SSOKs remain illuminated after TSMS is opened
 - b. AIRs are open after the TSMS is opened
 - c. Motor stops spinning within 60 seconds

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

1.7 IMD Fault Demo

- Summary: Follow the start up procedure and put the system in drive mode. Set the TS power supply to 100V. Use two 51k Ohm resistors in parallel to short the HV+ TSMP to ground to induce an IMD fault. Remove the fault and wait one minute. Follow the start up procedure to re-energize the system. Use the same resistor configuration to short the HV- TSMP to ground to induce an IMD fault.
- Requirements Met: EV7.9.6, EV7.9.7, EV9.3.4, EV9.4.1, EV9.4.2, EV10.1.2
- Measurement: N/A
- Materials: Stopwatch, resistor
- Pass Criteria:
 - a. High voltage shuts off within 30 seconds of inducing the IMD fault on the HV+ TSMP
 - b. IMD Fault Light illuminates when a fault is induced on the HV+ TSMP
 - c. After the resistor is removed from the HV+ TSMP, the system does not re-energize without user input
 - d. High voltage shuts off within 30 seconds of inducing the IMD fault on the HV- TSMP
 - e. IMD Fault Light illuminates when a fault is induced on the HV- TSMP
 - f. After the resistor is removed from the HV- TSMP, the system does not re-energize without user input
 - g. While the IMD Fault light is on the SSOKs are off

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

- d. PASS / FAIL
- e. PASS / FAIL
- f. PASS / FAIL
- g. PASS / FAIL

Test Observed By: _____ Date: _____

1.8 AMS Fault Simulation

- Summary: Follow the start up procedure and put the system in drive mode. Remove the safety loop jumper to simulate an AMS fault.
- Requirements Met: EV2.11.2, EV9.3.3, EV9.6, EV10.4
- Measurement: N/A
- Materials: N/A
- Pass Criteria:
 - a. AMS Fault light illuminates less than 60 seconds after the jumper is removed
 - b. SSOK lights turn off when the jumper is removed
 - c. AIRs open when the jumper is removed

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

2. Safety Loop

2.1 Grounded Low Voltage Master Switch (GLVMS)

- Summary: Verify GLV turns on correctly
- Requirements Met: EV7.1.1, EV7.3.1, EV7.4.1, EV7.5.4, EV7.6.3
- Observation: GLV current and voltage from GLV multimeter display
- Materials: N/A
- Pass Criteria:

- a. The system only turns on the Left and Right BRBs are closed and the GLVMS is closed.

Observations:

GLVMS	R. BRB	L. BRB	SCADA Screen On	GLV Light	GLV Multimeter On	System On
OPEN	OPEN	OPEN				
OPEN	OPEN	CLOSED				
OPEN	CLOSED	OPEN				
OPEN	CLOSED	CLOSED				
CLOSED	OPEN	OPEN				
CLOSED	OPEN	CLOSED				
CLOSED	CLOSED	OPEN				
CLOSED	CLOSED	CLOSED				

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

2.2 Master Reset Button and SSOKs

- Summary: Pressing the Master Reset Button while GLVMS is on and while Fault light is off will illuminate the SSOK Lights. Pressing the Master Reset button while the GLVMS is off and / or while the fault light is on will not illuminate the SSOK lights. Cause IMD fault by shorting any single TSMP to Ground.
- Requirements Met: EV9.3.3, EV9.3.4
- Observation: SSOK Lights are illuminated when the correct start up procedure is followed. The SSOK Lights will not illuminate if the the GLVMS is off or the Fault light is on.
- Materials: N/A
- Pass Criteria:

- a. SSOK Lights light up when MReset is pressed
- b. SSOK Lights remain on when MReset is released
- c. SSOK Lights do not light up if the GLVMS is off but the Fault light is off
- d. SSOK Lights do not light up if the IMD Fault light is on and the GLVMS is on
- e. SSOK Lights do not light up if the Brake Overtravel button is pushed and the GLVMS is on
- f. SSOK Lights do not light up if the SCADA Relay is open and the GLVMS is on

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL
- e. PASS / FAIL
- f. PASS / FAIL

Test Observed By: _____ Date: _____

2.3 Cockpit Big Red Button (BRB) and Cockpit Reset

- Summary: Closing the Cockpit Big Red Button allows the system to follow the behavior described in the Safety Loop table. Verify AIRs light is on by following the Startup Procedure.
- Requirements Met: EV7.6.3
- Observation: AIRs light status
- Materials: Oscilloscope or Voltmeter
- Pass Criteria:
 - a. AIRs light turns on when following Startup Procedure when after Cockpit Reset is pressed
 - b. AIRs light turn off when Cockpit BRB is pressed
 - c. AIRs light turns on when Cockpit BRB is opened and Cockpit Reset is pressed
 - d. AIRs light remains off when Cockpit BRB is pressed and the Cockpit Reset is pressed

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL

Test Observed By: _____ Date: _____

2.4 Tractive System Master Switch (TSMS)

- Summary: Follow start-up procedure through turning the TSMS on and pressing the Cockpit Reset Button to close the AIRs. Turn off TSMS to turn off high voltage. Check that AIRs light is on. Turn TSMS back on.
- Requirements Met: EV7.4.1
- Observation: AIRs light illuminates on cockpit panel
- Pass Criteria:
 - a. AIRs light illuminated after TSMS is turned on and Cockpit Reset is pressed
 - b. AIRs light turns off after TSMS is turned off

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

2.5 SCADA Relay

- Summary: If a sensor reading is out of the range specified by the SCADA configuration file, the SCADA relay will open the safety loop. Will be tested at a minimum of 2 different thresholds set in configuration file.
- Requirements Met: N/A
- Observation: The SSOKs turn off when an out of range sensor value is detected
- Materials: Oscilloscope, Voltmeter, thermometer
- Pass Criteria:
 - a. Observe the SSOKs turn off when throttle voltage exceeds programmed threshold specified in configuration file

- b. Observe the SSOKs turn off when the GLV temperature sensor exceeds threshold specified in configuration file
- c. Observe the SSOKs turn off when the Motor RPM exceeds programmed threshold specified in configuration file

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

2.6 AIRs Operation

- Summary: Verify that the GLV has the ability to close all 4 of the AIRs in the Safety Loop under full load of Safety Loop components and cooling system. Using modified safety loop cable, connect 4 AIRs in series with safety loop. Power the GLV to the point before turning on the TSMS and pressing Cockpit Reset button. Check that cooling system is on and running. Monitor AIRs light on Cockpit Panel.
- Requirements Met: N/A
- Observation: AIRs light on Cockpit Panel
- Materials: EV7.4.3
- Pass Criteria:
 - a. AIRs light is off before pressing Cockpit Reset and turning on TSMS
 - b. AIRs light illuminates after turning on TSMS and pressing Cockpit Reset

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

2.7 GLV System Voltage and Current Measurements

- Summary: Measure and record maximum, minimum, and average GLV voltage and current during each stage of the startup procedure. Compare GLV system meter

measurements with voltmeter measurements. Record current and voltages on oscilloscope during transitions between stages of Safety Loop startup.

- Requirements Met: N/A
- Measurement: GLV System Current, GLV System Voltage
- Materials: Oscilloscope, Voltmeter
- Pass Criteria:
 - a. Maximum current measurement does not exceed 10 A.

Observations (Attach documents of data and all plots):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

3. Startup Procedure

3.1 Startup Procedure

- Summary: Following the procedure described in the Startup Procedure Maintenance Manual takes the system from fully de-energized to Drive Mode
- Requirements Met: EV7.7.1
- Observation: Startup Procedure was followed and no Faults occur. Ends in Drive state
- Materials: N/A
- Pass Criteria:
 - a. GLV light turns on after side panel BRBs are closed and GLVMS is turned on
 - b. SSOKs turn on after MReset button is pressed
 - c. Safe light turns on after MReset Reset button is pressed
 - d. AIRs light and TSAL turn on after Cockpit BRB is closed and TSVMS is turned on
 - e. Drive light stays off if drive button is pressed and brake is not pressed
 - f. Pressing the drive button and the brake at the same time before turning the TSVMS on does nothing
 - g. Safe light will not illuminate if Cockpit reset button is pressed while GLVMS is off
 - h. TSAL and AIRs lights remain off after Cockpit BRB is closed if the GLVMS is still off

- i. TSAL and AIRs lights remain off after Cockpit BRB is closed if the side panel BRBs are closed
- j. TSAL and AIRs lights remain off after Cockpit BRB is closed if the MReset button hasn't been pressed

Observations:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL
- e. PASS / FAIL
- f. PASS / FAIL
- g. PASS / FAIL
- h. PASS / FAIL
- i. PASS / FAIL
- j. PASS / FAIL

Test Observed By: _____ Date: _____

4. TSI

4.1 Precharge

- Summary: Precharge circuitry will reach 90% of TSV before connecting to and activating the Motor Controller.
- Requirements Met: EV2.10.1
- Measurement: Plot of voltage across R33 of TSI PCB versus Time. Plot of Pre_Charge_Ready signal on TSI PCB versus time. Tractive System Voltage (to determine 90% mark). Output Voltage of Precharge relay (K1 on TSI schematic). Motor controller connection to Motor Controller configuration PC.
- Materials: Oscilloscope(s), Isolated Probes
- Pass Criteria:
 - a. The Pre_charge_ready signal intersects with the V_{R33} signal above 90% TSV.
 - b. 24 V present at Precharge Relay after 90% TSV charged
 - c. Motor Controller Configuration PC is able to connect to Motor Controller

Observations (Attach a document / Pictures of graphs):

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

4.2 Discharge

- Summary: TSV must drop below 30 V in under 5 seconds after Safety Loop is broken or AIRs are opened.
- Requirements Met: EV2.8.3
- Measurement: Plot the voltage across the discharge resistors versus time.
- Materials: Oscilloscope
- Pass Criteria:
 - a. The signal across the discharge resistors is below 30 V within 5 seconds.

Observations (Attach a document / Pictures of graphs):

Results: PASS / FAIL

Test Observed By: _____ Date: _____

4.3 Ready To Drive Sound

- Summary: Entering the Drive state plays the Ready to Drive Sound for 3 seconds
- Requirements Met: EV7.8.2
- Observation: Measure Ready to Drive sound at a distance of 2 m.
- Materials: Sound meter
- Pass Criteria: Ready to Drive sound is played for 3 seconds at a minimum of 80 dB from a distance of 2 m.

Ready to Drive Sound Volume: _____

Results: PASS / FAIL

Test Observed By: _____ Date: _____

4.4 Drive - Over Current Transitions

- Summary: Enter drive mode and drive the motor such that an over-current error should occur. Verify that the over-current state is not left until the current is below the TSI overcurrent threshold and that the throttle is below 0.5V.
Demonstrate that the TSI overcurrent threshold can be changed without recompiling any firmware. Repeat the testing above for the new threshold.
- Requirements Met: EV7.8.2
- Observation: Lower the overcurrent limit in the TSI firmware to below the normal system operating current. SCADA displays the current state as Drive followed by Over Current.
- Materials: N/A
- Pass Criteria:*
 - a. The motor stops spinning when in the over-current state
 - b. The Drive Light in the cockpit flashes while in the over-current state.
 - c. The drive state field on the SCADA display shows that the system is in the over current state.
 - d. The system does not leave the overcurrent state until the current is under the TSI overcurrent threshold and the throttle is less than 0.5 V.

- e. The TSI overcurrent setting is not set by re-compiling and uploading firmware to the TSI microprocessor.

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL

Test Observed By: _____ Date: _____

*Note: TSI Current Sensor to be verified in order for this test to be valid.

4.5 Return to Drive Setup or Idle State Transitions

- Summary: Breaking the Safety Loop in any state returns to Idle state
- Requirements Met: EV7.8.2
- Observation: SCADA displays the current state as Idle after breaking the Safety Loop. The drive light turns off in any state that is not the Drive State.
- Materials: N/A
- Pass Criteria:
 - a. The drive state field on the SCADA display shows that the system is in the Idle State when the safety loop is broken.
 - b. The drive light turns off when the safety loop is broken

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

4.6 Drive to Drive Setup State Transition

- Summary: Put the system into drive state. Check that throttle implausibility, pressing the drive button, pressing the throttle and brake at the same time, or turning off the motor controller will return the system to the Drive Setup State.
- Requirements Met: EV7.8.2
- Observation: SCADA displays the current state as Drive Setup after breaking the Safety Loop
- Materials: N/A
- Pass Criteria:
 - a. The drive light turns off when in Drive Setup state
 - b. SCADA displays the current state as Drive Setup after the throttle is implausible
 - c. SCADA displays the current state as Drive Setup after turning off the motor controller
 - d. SCADA displays the current state as Drive Setup after pressing the drive button

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL

Test Observed By: _____ Date: _____

4.7 High Voltage Indicator Lights

- Summary: Follow the start up procedure until high voltage is present. The high voltage power supply should be set to 100 V. Tractive System Active Light (TSAL) and High Voltage present lights (HVPL) in the cockpit illuminate when high voltage is present in the system. Reduce the TS voltage supplied by the power supply. Record the voltage when the TSAL and HVPL turn off. Increase the TS voltage supplied by the power supply. Record the voltage when the TSAL and HVPL turn on.
- Requirements Met: EV9.1.8
- Measurement: TS voltage when TSAL and HVPL turn off
- Materials: N/A
- Pass Criteria:
 - a. TSAL turns off when the power supply is less than 40 V.
 - b. HVPL turns off when the power supply is less than 40 V.

- c. The difference between the voltages when the TSAL and HVPL turn off is less than 2V.
- d. TSAL is on when the power supply is greater than 60 V.
- e. HVPL is on when the power supply is greater than 60 V.
- f. The difference between the voltages when the TSAL and HVPL turn on is less than 2V.

Measurements:

Voltage TSAL turns off	
Voltage HVPL turns off	
Voltage TSAL turns on	
Voltage HVPL turns on	

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL
- e. PASS / FAIL
- f. PASS / FAIL

Test Observed By: _____ Date: _____

4.8 Tractive System Active Light

- Summary: Follow the start up procedure such that there is high voltage present in the system. The Tractive System Active Light (TSAL) flashes whenever there is high voltage present in the system outside of the power supply.
- Requirements Met: EV9.1.3
- Observation: TSAL flashes between 2 Hz and 5 Hz
- Materials: N/A
- Pass Criteria:
 - a. When high voltage is turned on, TSAL is flashing
 - b. When high voltage is turned off, the TSAL turns off

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

4.9 Brakes

- Summary: When the GLV is on (GLV light is on), pressing the Brake button sends a signal and is recognized by the TSI board
- Requirements Met: T7.4.1
- Measurement: SCADA displays that the brake is being pressed and the brake light illuminates
- Materials: N/A
- Pass Criteria:
 - a. The brake light is illuminated when the brake is being pressed.
 - b. The brake light is not illuminated when the brake is not being pressed.
 - c. SCADA display indicates that the brake is being pressed when the brake is being pressed.
 - d. SCADA display indicates that the brake is not being pressed when the brake is not being pressed.

Results:

Brake Button State	Brake Light	SCADA Brake Status
Pressed (1)	OFF (0) / ON (1)	
Released (0)	OFF (0) / ON (1)	

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL

Test Observed By: _____ Date: _____

5. Motor Characterization

5.1 SCADA Motor Data Acquisition

- Summary: SCADA is able to produce CSV of Motor RPM, Motor Torque, TS Current, TS Voltage relevant to motor characterization
- Requirements Met: N/A
- Observations: Motor RPM, Motor Torque, TS Current, TS Voltage
- Materials: N/A
- Pass Criteria:
 - a. SCADA produces a CSV only containing Motor RPM, Motor Torque, TS Current, and TS Voltage data

Observations (Attach a document / Pictures of graphs):

Results: PASS / FAIL

Test Observed By: _____ Date: _____

6. Motor Temperature & Cooling

6.1 Uncooled Motor Controller and Cooled Motor Controller

- Summary: Disable the cooling system by unplugging J8 from the TSI board. Allow motor controller to operate such that it heats up. Measure temperature over 30 minute time period or until 60°C (safety limit). Repeat with cooling system active for motor controller.
- Requirements Met: N/A
- Measurement: Plots of motor controller temperature versus time with and without cooling.
- Materials: Timer or Stopwatch
- Pass Criteria:
 - a. Plot of motor controller temperature vs time for cooled and uncooled conditions
 - b. Plot of cooled motor controller temperature always less than or equal to uncooled motor controller temperature

Observations (Attach a document / Pictures of graphs):

Results:

- a. PASS / FAIL

b. PASS / FAIL

Test Observed By: _____ Date: _____

6.2 Motor and Cooling Stress Test

- Summary: Run motor and measure time needed for motor controller temperature to reach 60°C or until 1 hour has elapsed. Throttle must be at least 50%.
- Requirements Met: N/A
- Measurement: Time, Motor Controller Temperature
- Materials: Timer or Stopwatch
- Pass Criteria:
 - a. Cooled Motor Controller temperature does not reach 60°C in 30 minutes.
 - b. No cooling leaks are observed during or immediately after the 1 hour stress test.

Observations (Attach a document / Pictures of graphs):

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

7. System Sensors

7.1 Motor Temperature

- Summary: Verify the functionality of the Motor Controller Temperature sensor for measuring the motor temperature. Sample data at a minimum of 3 operating points between ambient room temperature and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Motor Temperature
- Materials: Thermometer / Temperature Probe
- Pass Criteria:
 - a. Capable of measuring temperatures between ambient temperature and 60°C within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.2 Motor Temperature

- Summary: Verify the functionality of the Motor Controller Temperature sensor for measuring the motor controller temperature. Sample data at a minimum of 3 operating points between ambient room temperature and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Motor Temperature
- Materials: Thermometer / Temperature Probe
- Pass Criteria:
 - a. Capable of measuring temperatures between ambient temperature and 60°C within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.3 Motor Velocity at Motor Output Shaft

- Summary: Verify the functionality of the Motor Controller velocity sensor and Huff Box RPM sensor. Sample data at a minimum of 3 operating points between 0 RPM and 4000 RPM. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Motor RPM
- Materials: Handheld tachometer
- Pass Criteria:
 - a. Motor Controller RPM sensor capable of measuring RPMs within ± 75 RPM
 - b. Huff Box RPM sensor capable of measuring RPMs within ± 150 RPM

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

7.4 Huff Box Motor Output Shaft Torque

- Summary: Verify the functionality of the Huff Box Dynamometer Torque sensor. Apply static load to perform measurement using known weights. Sample data at a minimum of 3 operating points between 0 and 60 ft-lbs. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Torque
- Materials: Known weights
- Pass Criteria:
 - a. Capable of measuring Torque within ± 3 ftLbs

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.5 Motor Controller Motor Torque

- Summary: Verify the functionality of the Motor Controller Torque sensor. Apply dynamic torque load with the motor spinning the dynamometer pump. Compare to Huff Box torque reading on SCADA. Sample data at a minimum of 3 operating points between 0 and 60 ft-lbs. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Torque
- Materials: Known weights
- Pass Criteria:
 - b. Capable of measuring Torque within ± 3 ftLbs

Statistical Analysis (Attach Document):

Results:

- b. PASS / FAIL

Test Observed By: _____ Date: _____

7.6 Tractive System Voltage and Motor Controller Voltage Sensors on TSI

- Summary: Verify the functionality of the Tractive System Voltage and Motor Controller Voltage sensors. Place system in Drive Setup state before sampling. Sample data at a minimum of 3 operating points between 0 and 100 V. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Tractive System Voltage and Motor Controller Voltage sensors on TSI
- Materials: Oscilloscope or Voltmeter
- Pass Criteria:
 - a. Capable of measuring Voltage within ± 1 V

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.7 Tractive System Current Sensor in TSI

- Summary: Verify the functionality of the Tractive System Current sensor in TSI enclosure. Use the TS power supply to apply a current limit such that current is known through system. Induce current by applying short between High Voltage TSMPs. Record the current reported by the SCADA. Sample data at a minimum of 3 operating points between 0 and 300 A. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Tractive System Current sensor in TSI board
- Materials: Power Supply, Disabled IMD
- Pass Criteria:
 - a. Capable of measuring current within ± 1 A

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.8 Grounded Low Voltage Sensor

- Summary: Verify the functionality of the external multimeter sensor and SCADA reporting. Sample data at a minimum of 3 operating points between 0 and 24 V. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: GLV
- Materials: Special cable allowing GLV to be powered from variable DC power supply
- Pass Criteria:
 - a. Capable of measuring voltage within ± 0.5 V using GLV multimeter
 - b. Capable of measuring voltage within ± 0.5 V using SCADA reporting

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL
b. PASS / FAIL

Test Observed By: _____ Date: _____

7.9 Grounded Low Voltage Current Sensor

- Summary: Verify the functionality of the external multimeter sensor and SCADA reporting. Cause a short within the safety loop and measure current using current limiting power supply. Sample data at a minimum of 3 operating points between 0 and 8 A. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: GLV Current
- Materials: Variable DC power supply
- Pass Criteria:
 - a. Capable of measuring current within ± 0.1 A using GLV multimeter
 - b. Capable of measuring current within ± 0.1 A using SCADA reporting

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL
- b. PASS / FAIL

Test Observed By: _____ Date: _____

7.10 Grounded Low Voltage Temperature Sensor

- Summary: Verify the functionality of the GLV temperature sensor. Produce heat using heat source and compare with Fluke thermometer. Sample data at a minimum of 3 operating points between 0 and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: GLV Temperature
- Materials: Heat source, Fluke Thermometer
- Pass Criteria:
 - a. Capable of measuring temperature within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.11 TSI Temperature Sensor

- Summary: Verify the functionality of the TSI temperature sensor. Produce heat using heat source and compare with Fluke thermometer. Sample data at a minimum of 3 operating points between 0 and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: TSI Temperature
- Materials: Heat source, Fluke Thermometer
- Pass Criteria:
 - a. Capable of measuring temperature within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.12 Cooling Temperature Sensors

- Summary: Verify the functionality of the Cooling temperature sensor. Add / replace water with warmer water in order to modify temperature. Compare with Fluke thermometer. Sample data at a minimum of 3 operating points between 15 and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Cooling Temperature
- Materials: Fluke Thermometer
- Pass Criteria:
 - a. Capable of measuring temperature within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.13 Motor Controller Temperature Sensor

- Summary: Verify the functionality of the motor controller temperature sensor. Add / replace the cooling water with warmer water in order to modify temperature. Compare with Fluke thermometer. Sample data at a minimum of 3 operating points between 15 and 60°C. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Motor Controller Temperature
- Materials: Fluke Thermometer
- Pass Criteria:
 - a. Capable of measuring temperature within $\pm 1^\circ\text{C}$

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

7.14 Cooling Flow Rate Sensor

- Summary: Verify the functionality of the Cooling flow rate sensor. Fill the cooling system with water and let it run with the outflow tube running into a beaker/bucket. Time how long it takes the system to fill the beaker/bucket. Perform statistical analysis of errors.
- Requirements Met: N/A
- Measurement: Cooling Temperature
- Materials: Beaker/bucket, stopwatch
- Pass Criteria:
 - a. Capable of measuring L/min within specification described in Cooling User Manual

Statistical Analysis (Attach Document):

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

8. Maintainability Demo

8.1 24 Hour Demonstration

- Summary: Verify the system is able to be in an operational state for a continuous 24 hour period without raising a fault or requiring intervention. Must run motor at least once for 3 minutes above 1000 RPM during this time. At the end of the 24 hour period, the motor must spin above 1000 RPM for at least 1 minute.
- Requirements Met: GPR006, GPR007
- Measurement: 24 hour time period without fault, error, or system failure requiring human intervention.
- Materials: Timer or Stopwatch
- Pass Criteria:
 - a. A timer or stopwatch reaches 24 hours of system active time without powering the system down as a result of a fault, error, or system failure.
 - b. Motor runs above 1000 RPM for 3 minutes.
 - c. Motor runs above 1000 RPM for 1 minute after 24 hours of the system being on.

Observations:

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL

Test Observed By: _____ Date: _____

9. TSV/AMS Prototype

TSV Prototype Requirements (included above):

- EV2.1 - Design Document
- EV2.11.2 - Test 9.1, Test 9.2
- EV2.11.4 - Design Document, Test 9.1, Test 9.2, Test 9.3
- EV2.11.5 - Design Document - High Level Block Diagram
- EV2.11.6 - Design Document
- EV2.11.7 - Design Document
- EV2.11.8 - Design Document
- EV2.11.9 - Design Document, Test 9.3.4

All other rules are outside the scope of the TSV/AMS prototype and will not be tested explicitly in this document. (Other rules may be checked through the rules walkthrough.)

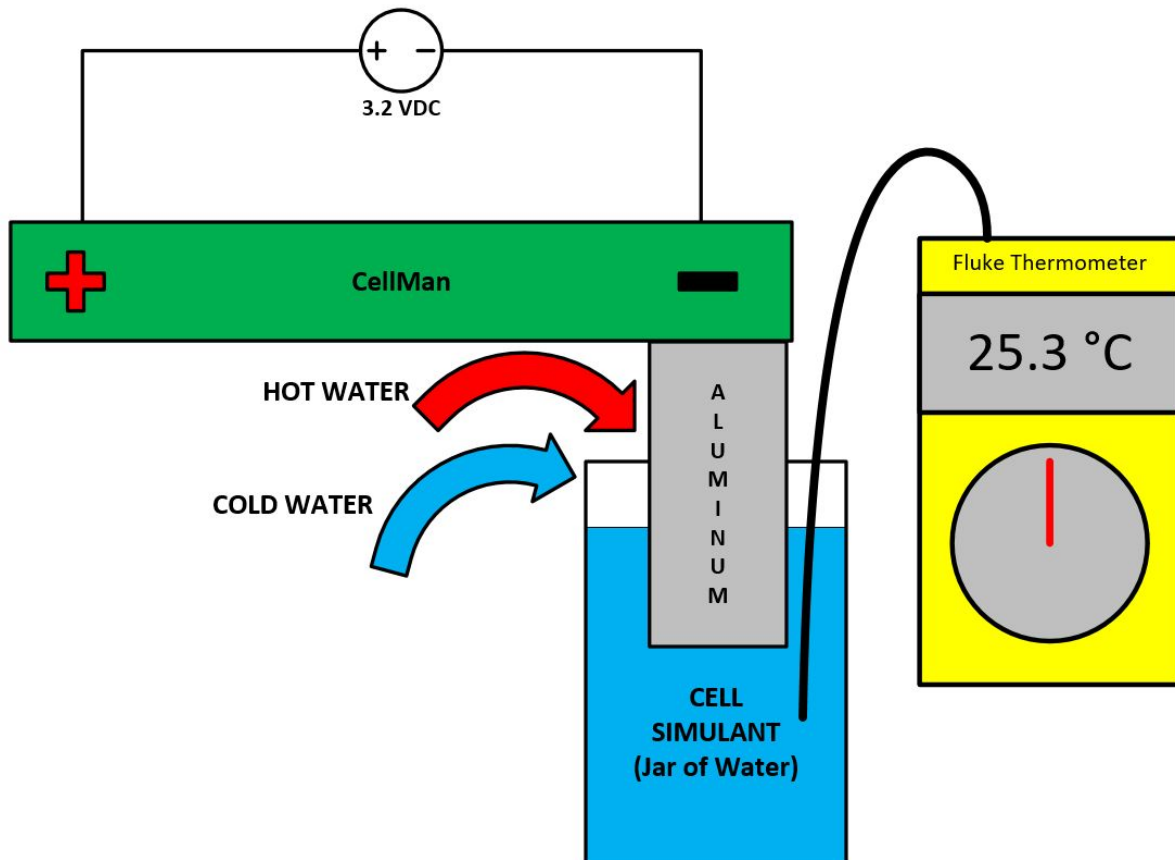


Figure 2 - TSV Prototype CellMan Configuration for Temperature Measurement Testing

9.1 Cell Voltages

- Summary: Measure 7 CellMan voltages on SCADA with the AMS with terminal voltages near 2.0 V, 3.2 V, 4.0 V and at least 3 different operating points between 2.0 V and 4.0 V.
- Requirements Met: EV2.11.2
- Measurement: CellMan voltage
- Materials: 3 DC Bench Power Supplies, voltmeter
- Pass Criteria:
 - a. CellMan voltage measurements have a standard uncertainty of at most 0.1 V

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

9.2 Cell Temperature

- Summary: Measure 7 CellMan temperatures on SCADA with the AMS with cell temperatures at ambient room temperature and near 40 °C and 60 °C. Set up each CellMan according to Figure 2.
- Requirements Met: EV2.11.2
- Measurement: CellMan temperature
- Materials: Fluke temperature, hot and cold water, 7 water containers
- Pass Criteria:
 - a. CellMan temperature measurements have a standard uncertainty of at most 0.5°C

Results:

- a. PASS / FAIL

Test Observed By: _____ Date: _____

9.3 AMS Faults

- Summary: If a sensor reading is out of the range specified by PackMan, the AMS relay will close and short the safety loop in (SLOOPIN) and safety loop out (SLOOPIN) signals on the PackMan board in less than 60 seconds
- Requirements Met: EV2.11.2, EV9.3.3, EV9.6, EV10.4
- Measurement: The AMS relay closes, timing before relay switches
- Materials: Oscilloscope, Voltmeter, time measurement device
- Pass Criteria:

- a. Observe the AMS relay opens when the measured cell voltage is above the threshold set by PackMan.
- b. Observe the AMS relay opens when the measured cell voltage is below the threshold set by PackMan.
- c. Observe the AMS relay opens when the measured cell temperature is above the threshold set by PackMan
- d. Observe the AMS relay open when the watchdog is timed-out.

Results:

- a. PASS / FAIL
- b. PASS / FAIL
- c. PASS / FAIL
- d. PASS / FAIL

Test Observed By: _____ Date: _____

10. Project Deliverables

D000: PDR

Completed in the Fall Semester.

D001: CDR

Waived. Team will instead complete two (2) weekly design reviews on individual components with detailed minutes recorded.

D002: User Manuals

Part	SCADA	GLV	TSI	TSV	Motor / Motor Controller / Dyno	Cooling	Interconnect
Annotated Drawing of Physical System							
Annotated Screenshots of all UI							
Annotated Drawings of any Physical Control Panels, Indicator Buttons, Power Switches, and other controls							
Simplified Block Diagram							
“Getting Started”							
“FAQ”							
Detailed Explanations of All Functions and Control							
User Level Troubleshooting, Calibration, and Maintenance							

D003: Final Report and Maintenance Manual

Final Report

Check	Completed
Maintenance Manual	
Static Copy of the Website	
Flash Drive Delivered in a Professional Quality Case	
Delivered to Advisors and Department Head on a Flash Drive	

Maintenance Manual

Part	SCADA	GLV	TSI	TSV	Motor / Motor Controller / Dyno	Cooling	Interconnect
Maintenance / Calibration							
Schematics / Layouts							
Connector Pinouts							
Cable Signal Assignment							
Interface Semantics							
Block Diagrams							
State Diagrams							
Source Code Trees							
Additional Low Level Information							

D004: Acceptance Test Plan

The ATP shall describe the inspections, analyses, and demonstrations that will be used to demonstrate the final project is compliant with the Statement of Work and FH Rules.

D005: Acceptance Test Report

The ATR shall document the results of the tests laid out by the ATP.

D007: Project Website

The project website shall be updated on a weekly basis with purchasing reports, project status letters, individual progress reports, source code, block diagrams, schematics, and layouts.

D008: Final Presentation and Delivery

Check	Completed
Project Posters Displayed	
Project Video Present	
Project Demonstrated	

D010: Project Posters

Part	SCADA	GLV	TSI	TSV	Motor / Motor Controller / Dyno	Cooling	Interconnect
Subsystem Summary							
47x35 inches							
High Resolution Text and Images							
Website URL Link							
Website QR Code							

D013: Purchasing Report

Check	Completed
Table for all Purchase Orders	

Purchasing Summary Organized by Week	
Purchasing Summary Organized by Team	

Website Budget Information: <https://sites.lafayette.edu/motorsports/finance/>

D014: Project Management and Status Letters

Check	Completed
Project Status Letters Delivered	
ATP Delivered	
Individual Progress Reports Delivered	
Work Breakdown Structure Delivered	

D015: Motor Characterization Curves

Check	Completed
Motor Characterization Curves Delivered	

D016: Rules Walkthrough

Check	Completed
Informal Competition Rules Walkthrough with Course Instructor(s)	

