

Acceptance Testing Plan - Fall 2018 Dyno Room

Revision 3

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Updates

11/14/2018 - Original

12/01/2018 - Addressed concerns in Professor Nadovich Comments
ATR in separate document

12/05/2018 - Corrected required equipment for ATP006 and ATP007
Added specificity to pass criteria for ATP017

Block Diagram

Below is a link to the block diagram of systems that will be delivered in the AEC 401 (Dyno room).

<https://sites.lafayette.edu/motorsports/dyno-room/>

Motor Tests

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
|-------------|----------------------------|---|--|--|
| ATP001 | Motor spinning | Motor is spinning at >100 RPM for longer than 1 minute (or until maximum motor operating temperature is reached). | N/A | timer |
| ATP002 | Motor RPM Measurements | RPM measurement verified against RPM sensor. <ul style="list-style-type: none"> • Dyno RPM • Motor encoder RPM • Handheld tachometer | RPM measurements are with $\pm 5\%$ of the handheld tachometer measurement. | handheld tachometer, reflective aluminum tape |
| ATP003 | Motor Torque Measurements | Observe motor torque reading for static known loads on torque gauge. | Measured torques are within $\pm 5\%$ of actual. | 2 objects with different known masses, fastener between weights and torque gauge |
| ATP004 | Motor Voltage Measurements | TSV voltage measurements verified against multimeter. Record 5 voltage measurements: <ul style="list-style-type: none"> • TSV before pre-charge • TSV after pre-charge • TSV at MC (MC) • TSV with multimeter • TSV power supply with the pre-charge relay closed. | Measurements are within $\pm 3\%$ of the voltage observed on the multimeter. | multimeter |

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| ATP005 | Motor Current Measurements | TSI current measurement verified against power supply reported current. | Measurement matches the reported dc current on the power supply with $\pm 5\%$ | |
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Pre-charge and Discharge Tests

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
|-------------|--|---|--|--------------------|
| ATP006 | Pre-Charge Circuit Test with Integrated Motor Controller | The TSI will charge the motor controller using 100V input voltage from the Dyno Room power supply. | The pre-charge relay should be closed when the motor controller input reaches a voltage between 94 V and 96 V. | Oscilloscope |
| ATP007 | Discharge Circuit Test with Integrated Motor Controller | The system should start with the motor controller charged to 100V and the pre-charge circuit should be bypassed. When the safety loop is broken, the discharge relay should turn on when AIRs open discharging the capacitor. | The motor controller should be discharged to under 30 V in less than 5 seconds. | Oscilloscope |

Throttle Plausibility

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
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| ATP008 | Pedal 1 Undervoltage Limit | Observe that the Throttle_PL signal goes high when Pedal 1 is too low. | Throttle becomes implausible at a Pedal 1 Voltage between 5.22 V and 5.26 V. | 2 lab bench power supplies |
| ATP009 | Pedal 1 Overvoltage Limit | Observe that the Throttle_PL signal goes high when Pedal 1 is too high. | Throttle becomes implausible at a Pedal 1 Voltage between 9.74 V and 9.78 V. | 2 lab bench power supplies |
| ATP010 | Pedal 2 Undervoltage Limit | Observe that the Throttle_PL signal goes high when Pedal 2 is too low. | Throttle becomes implausible at a Pedal 2 Voltage between 0.22 V and 0.26 V. | 2 lab bench power supplies |
| ATP011 | Pedal 2 Overvoltage Limit | Observe that the Throttle_PL signal goes high when Pedal 2 is too high. | Throttle becomes implausible at a Pedal 2 Voltage between 4.74 V and 4.78 V. | 2 lab bench power supplies |
| ATP012 | Pedal Voltage Difference Lower Limit | Observe that the Throttle_PL signal goes high when the pedal voltage difference is too low. | Throttle becomes implausible at a a pedal voltage difference (Pedal 1 - Pedal 2) between 0.4 V and 0.5 V. | 2 lab bench power supplies |
| ATP013 | Pedal Voltage Difference Upper Limit | Observe that the Throttle_PL signal goes high when the pedal voltage difference is too high. | Throttle becomes implausible at a a pedal voltage difference between -0.4 V and -0.5 V. | 2 lab bench power supplies |

Cooling

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
|-------------|--|---|---------------|---|
| ATP014 | Cooling system has no observable leaks | Run water through the cooling system for 10 minutes and observe to ensure there aren't any leaks. | N/A | |
| ATP015 | Cooling fan | Cooling fan spins at 100 RPM for longer than a minute | N/A | handheld tachometer, reflective aluminum tape |
| ATP016 | Coolant pumped at 5L/min | Run cooling system for 10 minutes and use flow meter to ensure that coolant flows at least 5 L/min | N/A | |
| ATP017 | Temperature data sent to SCADA | Connect Cooling to SCADA with CANBus. Verify reported motor controller temperature measurement is within $\pm 5\%$ of the temperature sensor measurement. | N/A | |

Drive State Tests

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
|-------------|-------------------------|------------------------------------|---------------|--------------------|
| ATP018 | SCADA UI displays drive | Displays current drive state while | N/A | SCADA |

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| | states. This can be tested while performing ATP020-ATP026 | following 2018 start-up procedure | | |
| ATP019 | SCADA logs why drive state changes. This can be tested while performing ATP020-ATP026 | Check SCADA logs after state change for reason. The log will be attached to the ATR. | N/A | SCADA |
| ATP020 | Ability to transition from IDLE state to PRECHARGE state | Close the safety loop | Observe on the SCADA rack display that the drive state begins in IDLE and moves to PRECHARGE when the safety loop closes | SCADA |
| ATP021 | Ability to transition from PRECHARGE state to DRIVE_SETUP state | Close the precharge relay | Observe on the SCADA rack display that the drive state begins in PRECHARGE and moves to DRIVE_SETUP when the precharge relay closes | SCADA |
| ATP022 | Ability to transition from DRIVE_SETUP state to DRIVE state | Push the drive button, Throttle is not implausible, Throttle is less than 0.5 V, brake pressed, and precharge circuit is 100% charged | Observe on the SCADA rack display that the drive state begins in DRIVE_SETUP and moves to DRIVE when all the conditions in the description column are met | SCADA |

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| ATP023 | Ability to transition from DRIVE state to DRIVE_SETUP state | Push the drive button, throttle is implausible, brake is pressed and throttle is above 0.5 V, turn off motor controller | Observe on the SCADA rack display that the drive state begins in DRIVE and moves to DRIVE_SETUP when any one of the conditions in the description column are met | SCADA |
| ATP024 | ABILITY to transition from DRIVE state to OVERCURRENT state | Increase the current | Observe on the SCADA rack display that the drive state begins in DRIVE and moves to OVERCURRENT when the current sensor measures a current within $\pm 5\%$ of value specified by SCADA | SCADA, current sensor |
| ATP025 | Ability to transition from OVERCURRENT state to DRIVE state | Lower the current, Throttle is less than 0.5 V | Observe on the SCADA rack display that the drive state begins in OVERCURRENT and moves to DRIVE when the current sensor measures a current within $\pm 5\%$ of value specified by SCADA and throttle is below 0.5 V | SCADA, current sensor |
| ATP026 | All states can transition back to the IDLE | Open the AIRs | Observe that the system transitions to the | SCADA |

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| | state. | | IDLE state when the AIRs are open | |
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Safety Loop Tests

| Test Number | Summary | Description | Pass Criteria | Required Equipment |
|-------------|--|---|---------------|--------------------|
| ATP027 | Left Side BRB breaks safety loop and de-energizes high voltage | Pressing the Left Side BRB turns off TSEL | N/A | |
| ATP028 | Right Side BRB breaks safety loop and de-energizes high voltage | Pressing the Right Side BRB turns off TSEL | N/A | |
| ATP029 | Driver BRB breaks safety loop and de-energizes high voltage but leaves GLV energized | Pressing the Driver BRB turns off TSEL but leaves GLV powered | N/A | |
| ATP030 | GLVMS completely de-energizes system when disengaged | Turning off GLVMS completely de-energizes system | N/A | |
| ATP031 | TSMS breaks safety loop and de-energizes high voltage | Turning off TSMS turns off TSEL | N/A | |
| ATP032 | Brake Over-Travel switch breaks safety loop and de-energizes | Pushing brake over-travel switch turns off TSEL | N/A | |

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| | high voltage | | | |
| ATP033 | Master Reset | Following the 2018 start up procedure, the SSOK lights up. | N/A | |
| ATP034 | IMD | When an IMD fault is detected the safety loop opens | N/A | |
| ATP035 | Safety Loop closed | Video showing all components of the safety loop working such that the AIRs close and TSEL turns on. | N/A | |
| ATP036 | Open safety loop | SCADA opens the safety loop when the user defined condition is met. | N/A | |

Other Status Indicators

| Test Number | Summary | Description | Pass Criteria | Equipment Needed |
|-------------|-------------------|--|---------------|------------------|
| ATP037 | GLV Present Light | Light turns on when GLV battery is connected | N/A | |
| ATP038 | HV Present Light | Light turns on when there is HV present. | N/A | |
| ATP039 | IMD Fault | Light turns on when there is IMD Fault. | N/A | |
| ATP040 | Fault | Turns on when the GLV and | N/A | |

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| | | TSV master switches and the BRBs are closed and safety loop 1 is open indicating an IMD fault or AMS fault. | | |
| ATP041 | AIRs Light | Light turns on after cockpit reset is pressed indicating that there is safety loop voltage before TSVMS | N/A | |
| ATP042 | Drive Light | Light turns on when in the Drive Mode | N/A | |
| ATP043 | Safety Light | Light turns on when SL1 to SL2 is connected | N/A | |
| ATP044 | Brake Light | Light turns on when brake is pressed | N/A | |
| ATP045 | Ready to Drive Sound (RTDS) | RTDS sounds when system enters drive state | N/A | |

Deliverables

| Item | Description |
|----------------------------|--|
| Graph of motor RPM vs time | Graph generated from data collected during motor tests |
| Graph of torque vs time | Graph generated from data collected during motor tests |
| Graph of power vs time | Graph generated from data collected during |

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| | motor tests |
| Graph of power in vs power out | Graph generated from data collected during motor tests |
| D000: PDR Report and Presentation | Slideshow presented to ECE faculty and guests. Slideshow, report, meeting minutes, and other supporting documents uploaded to website. |
| D001: CDR Materials | Slideshow and demonstrations presented to ECE faculty and guests. Slideshow, report, meeting minutes, and other supporting documents uploaded to website |
| D002: User Manuals | User manuals for each subsystem uploaded to the website with the following sections: getting started, FAQ, functions and controls, high level block diagram, annotated drawing of control panels/screenshots of UI screens, and troubleshooting, calibration, and maintenance. |
| D003: Final Report and Maintenance Manual | Maintenance manuals for each subsystem uploaded to the website with the following sections: maintenance, calibration, PCB schematic, PCB BoM, mechanical drawing, mechanical BoM, block diagram, wiring diagram. Final report delivered to the professors via a flash drive or DVD with a high level project summary report and maintenance manuals. |
| D004: Acceptance Test Plan | List of system tests that includes pass/fail criteria, observed results, and an indication of whether or not each test was successful. |
| D005: Acceptance Test Report | Report delivered after all tests have been conducted which shows which tests were successfully completed, when, and who witnessed or performed the test. |
| D007: Project Website | All project documentation uploaded to the website as portable static documents (PDF, TXT, XML) with the original version present as well as links to relevant Cloud storage. |
| D008: Final Presentation and Delivery | Final presentation including project video |

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| | delivered to ECE faculty and guests. Integrated hardware, software, and firmware will be installed in AEC 400 and 401. All supporting documentation will be delivered as per D003 and uploaded to the website. |
| D010: Project Posters | Soft and hard copies of the project poster delivered. Poster will contain a QR code and URL to the project website. |
| D013: Purchasing Report | Table containing all purchases delivered. The report will also include spending summaries based on category, week, and subsystem group as well as statistics for items of interest (e.g. delivery elapsed time, delivery cost, sales tax, etc) |
| D014: Project Management and Status Letters | Weekly project status letters delivered and uploaded to the website. Weekly status reports delivered on Mondays during class. Management will deliver project wide documents such as the ATP, Work Breakdown Structure, and competition documentation |
| CD001: Registration | Competition registration fee of \$2300 will be paid to SAE |
| CD002: Project Management Report | Document delivered to the SAE outlining project management plan, project schedule, and risk assessment |
| CD003: Structural Equivalency Spreadsheet (SES) | Demonstrate structural integrity of the proposed frame design to the SAE |
| CD004: Electrical Systems Form - Part 1 (ESF-1) | Deliver high level electrical designs to the SAE |
| CD005: Program Submission | Deliver high level car specifications to the SAE for the competition program |
| CD006: Team Picture | Deliver a picture of the team to the SAE |