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Integrating Co-Robots and Machine Learning in **Engineering Lab Environments to provide personalized feedback CIE 2018 Graduate Research Poster**

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Abstract

A machine learning method for predicting students' performance prior to the start of a task in an engineering lab environment is presented. The method employs students' facial expressions captured while reading the instruction of a task to predict their performance. A case study is used to validate the method. Furthermore, this work explores how this method could be implemented in a Collaborative-Robot (Co-robot) system to aid students towards the successful completion of an engineering assignment by providing students with real-time feedback. This personalized intervention and real-time feedback have the potential to improve students' performance and learning, as well as to improve the retention of students in STEM fields.

Research Question

□ Can a machine learning model predict students' performance with accuracy greater than random chance, by using their facial expressions captured while reading the instruction of a task?

Findings: Models' performance (Support Vector Machine models with LOOCV)

1) **Student-Task model:** Task performance ~ *f*(Facial Expression, Tasks, Student)

-Accuracy= 80% , 95% CI: [69.2% - 88.4%] -F1-score: 85.2%

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Motivation

Grand Engineering Challenges of the 21st century: **Development of Personalized Learning***

In traditional learning environments, instructors are able to provide personalized and real-time feedback based on the facial or body language cues students project, as well as their performance on the task at hand.



Unfortunately, this personalized assistance and real-time feedback is **DIFFICUL TO ACHIVE** where **in-person interactions** are challenging, or the student to instructor ratio is high. (e.g., E-learning, Eng. Laboratories)

2) **General model:** Task performance ~ f(Tasks, Student) -Accuracy= 58.7% , 95% CI: [46.7% - 69.9%] -F1-score: 73.9%

Case Study

Participants: 40 freshmen engineering students enrolled in EDGSN-100 Introduction to Engineering Design at Penn State. (18 to 19 years of age, 27.5 % females)

Tasks and Lab workstations



(average of all students given a task)



Conclusion and Future Work

This work highlights the potential of using machine learning models and students' facial expression to predict their performance, prior to the start of a task. The next steps are to implement this method in a Co-Robot system to aid students towards the successful completion of engineering assignments by providing students with real-time feedback, which are step 3 and 4 of our Research Plan.

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