

### Formula Electric Vehicle

ECE 492- Spring 2017 Grounded Low Voltage (GLV)

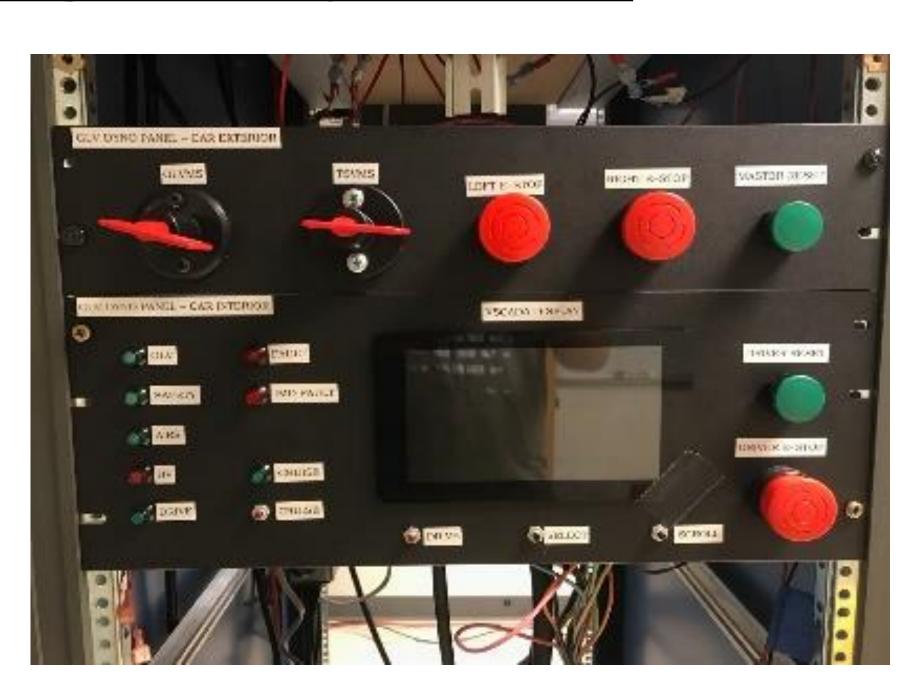


Project Website:

www.sites.Lafayette.edu/ece492-sp17 Engineers: Joe Sluke, Chris Bennett, Kyle Phillips

## Vehicle User Interface (VUI)

Integrated Dyno Room



#### Integrated on Vehicle







## Vehicle Computer Interface (VCI)

- -Deliver CANBUS communication to Pi
- -Deliver I2C communication line to Pi
- -Provide GLV Battery State of Charge
- -Provide safety loop monitoring

#### OVERVIEW

There are 4 main purposes of the Grounded Low Voltage (GLV) system:

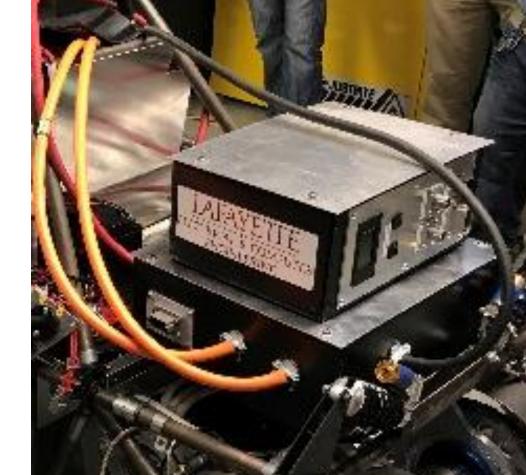
GLV Power – Provide 24VDC to all subsystems

Safety Loop – Manage the power line to energize Accumulator Isolation Relays

Vehicle Computer Interface – Provide hardware for the Raspberry Pi to communicate with subsystems Vehicle User Interface — Provide hardware for user interface of vehicle

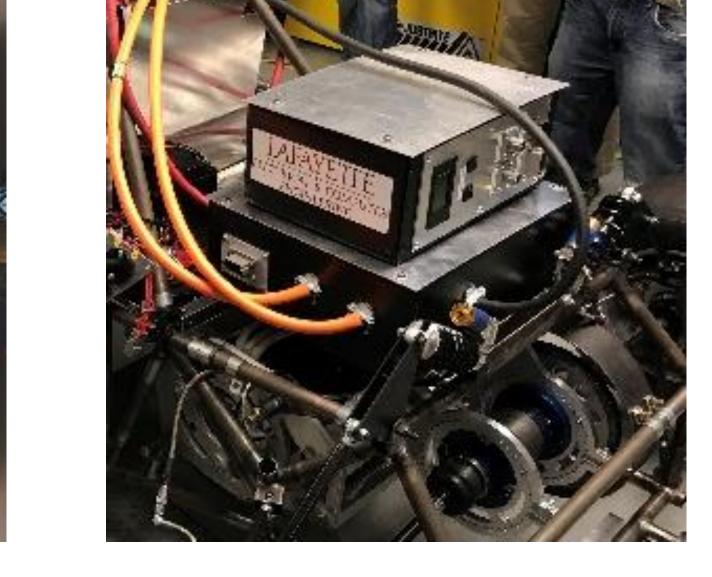
#### GLV Enclosure





Vehicle

# LAFAYETTE GLV



## SAFETY LOOP The Safety Loop's ultimate purpose is to energize the high voltage system by closing the Inertia (>>>>> AIRs.

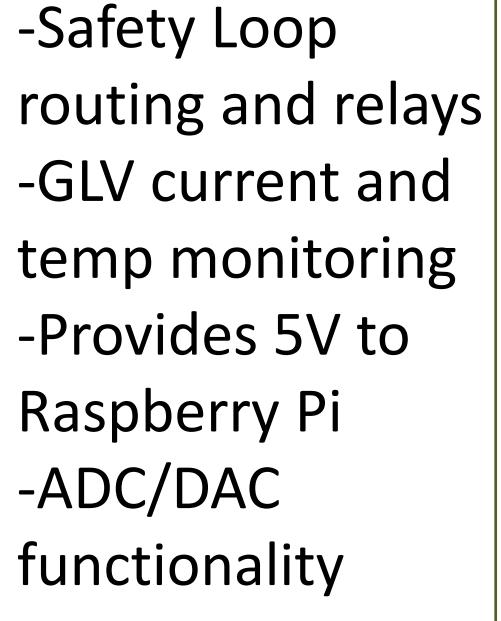
#### GLV POWER



GLV Power provides 24VDC to the Cooling controller and TSI. Protected with a 15A and 8A circuit breakers

#### GLV BoB





Acknowledgements: Past years 2015, 2016 work on GLV gave us the a great design base to work off of. Without their work this could not have been completed.