

# VSCADA Errata

ECE 492 Spring 2017

Assembled by Craig Lombardo and Austin Wiles

1. Move from Raspberry PI to device with native CAN
  - a. This may cause problems with the WAP setup so be aware of this
2. Remove USB2CAN device from equation
3. Add data trimming for SQLite DB
4. Add automatic backups for SQLite DB
5. Add I2C support
6. Get data from GLV via I2C
7. Control Dyno by sending I2C commands to GLV
8. Add UART support
9. Get data from TSI via UART
10. Control Dyno by sending UART commands to TSI
  - a. This varies from above as it TSI will check for plausibility
11. Integrate cruise control
12. Set up X11 forwarding
13. Add support for remote (desktop app) configuration changes
14. Change .bash\_profile to only run script upon start up, and not for new ssh connections