



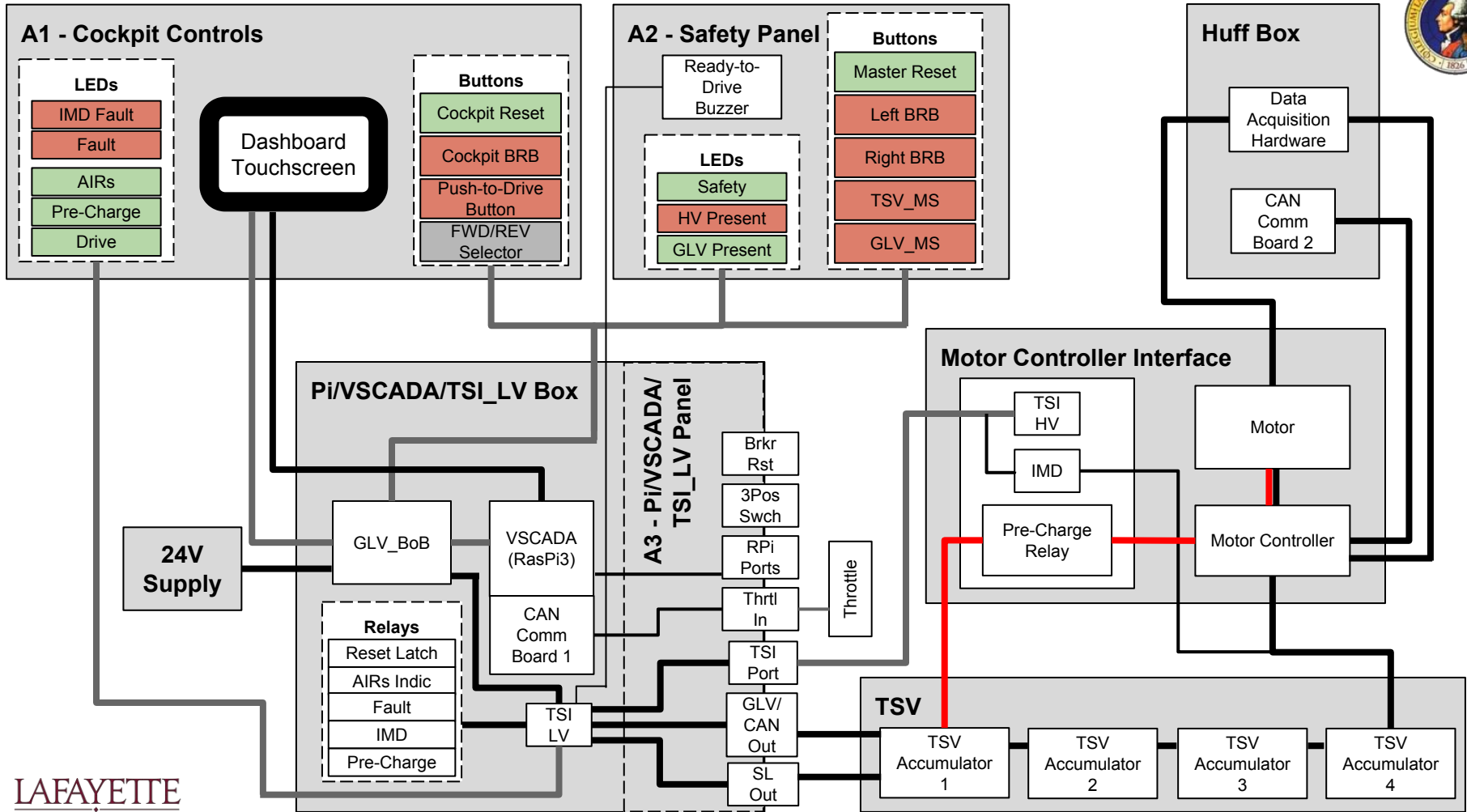
LFEV-Y4-2016

Lafayette Formula Electric Vehicle - Year 4
ECE 492 - Spring 2016

Final Presentation



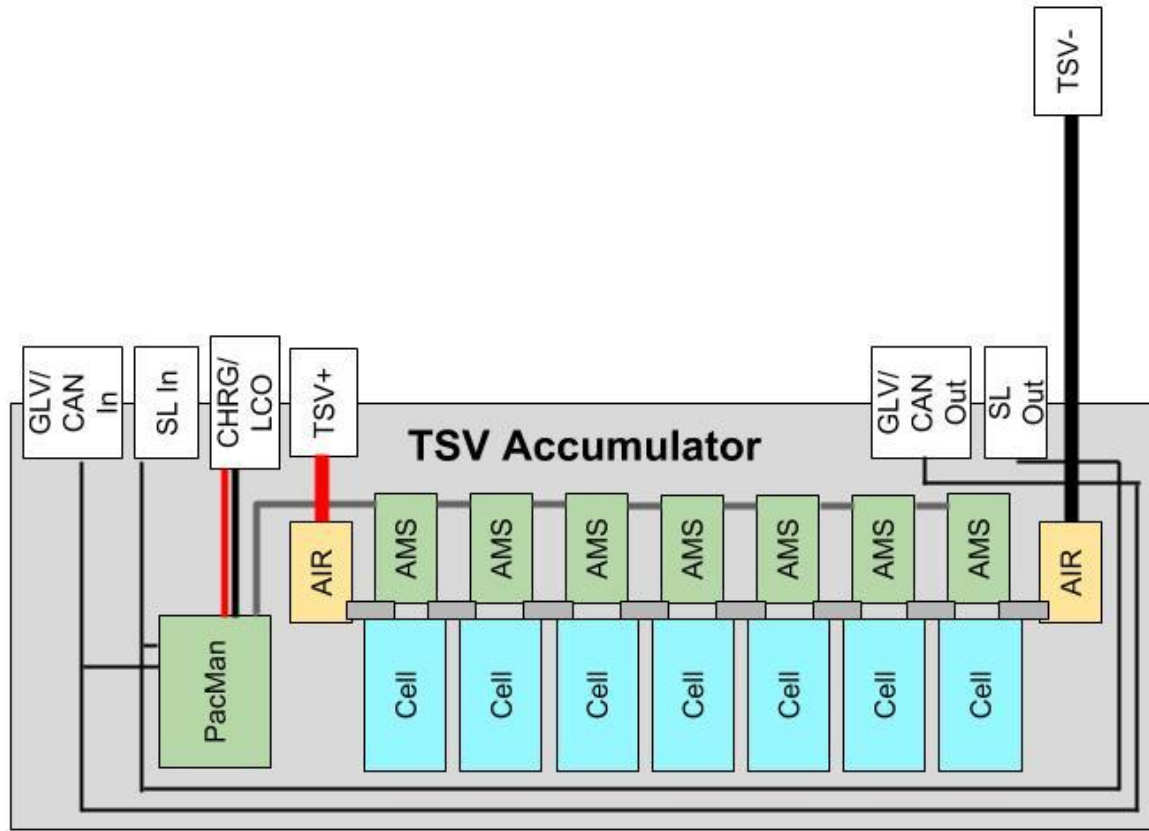
System Overview





TSV - Tractive System Voltage

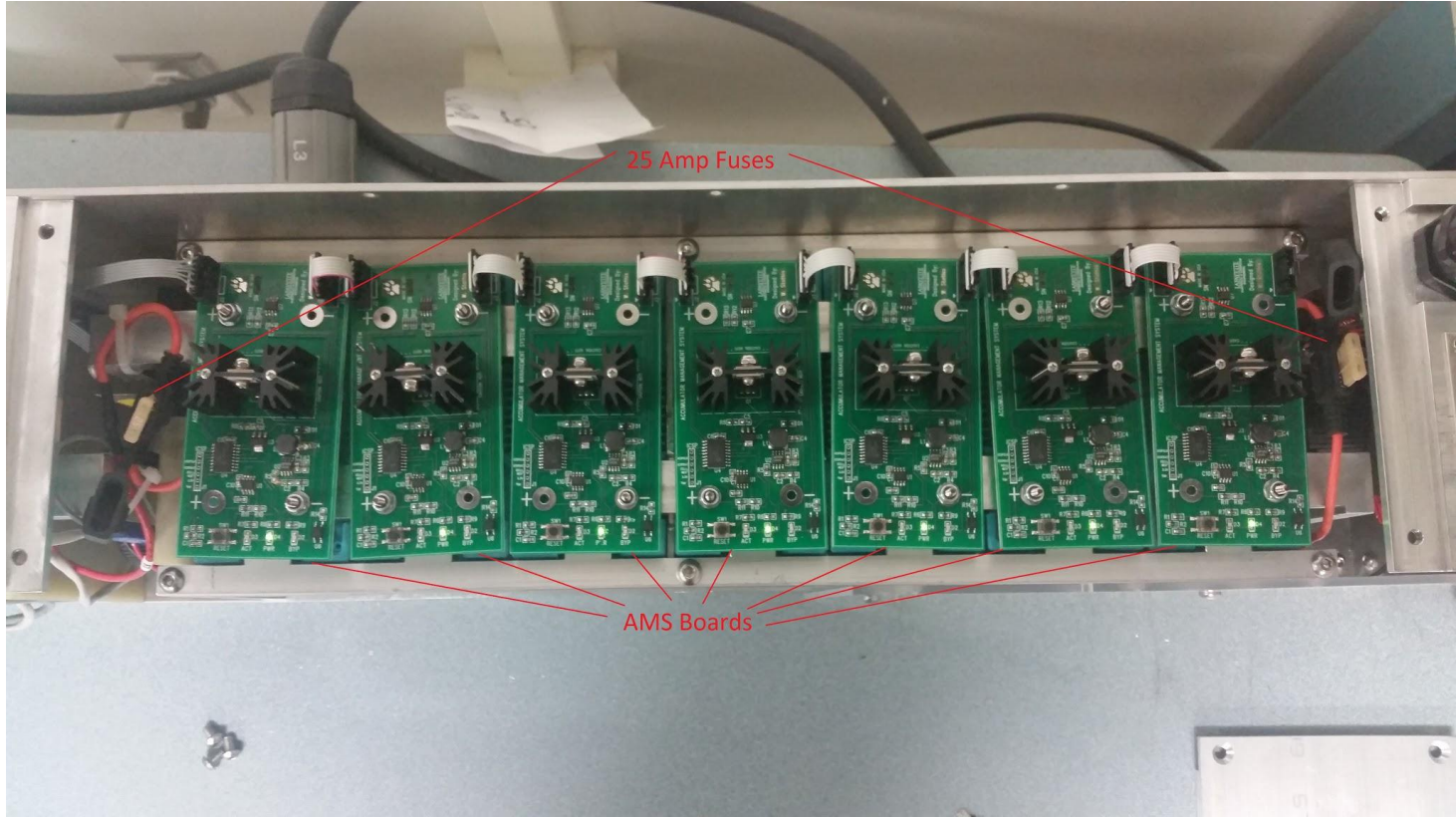
TSV



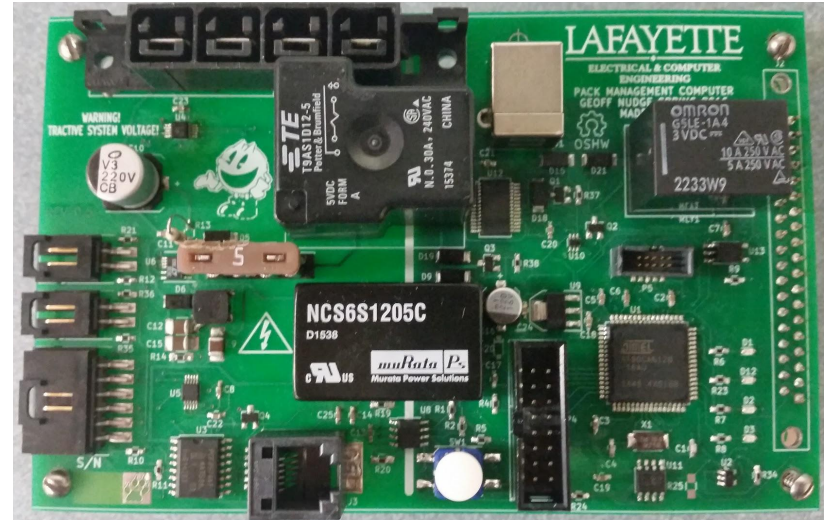
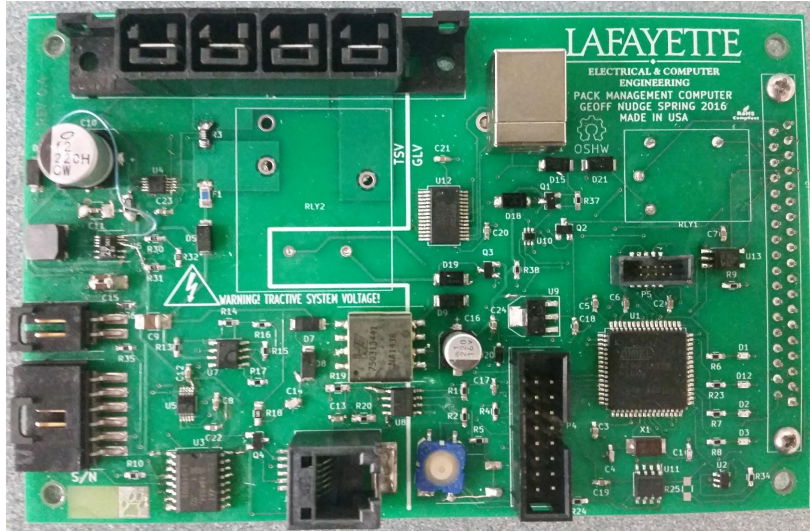
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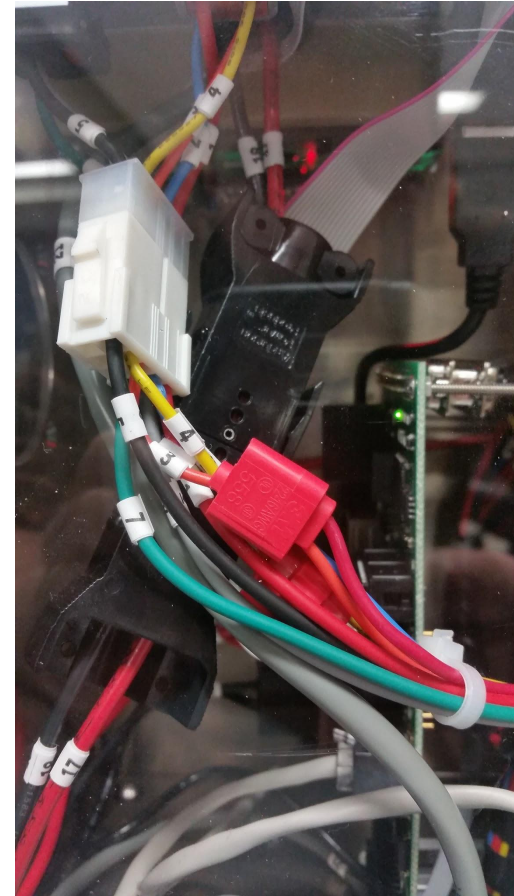
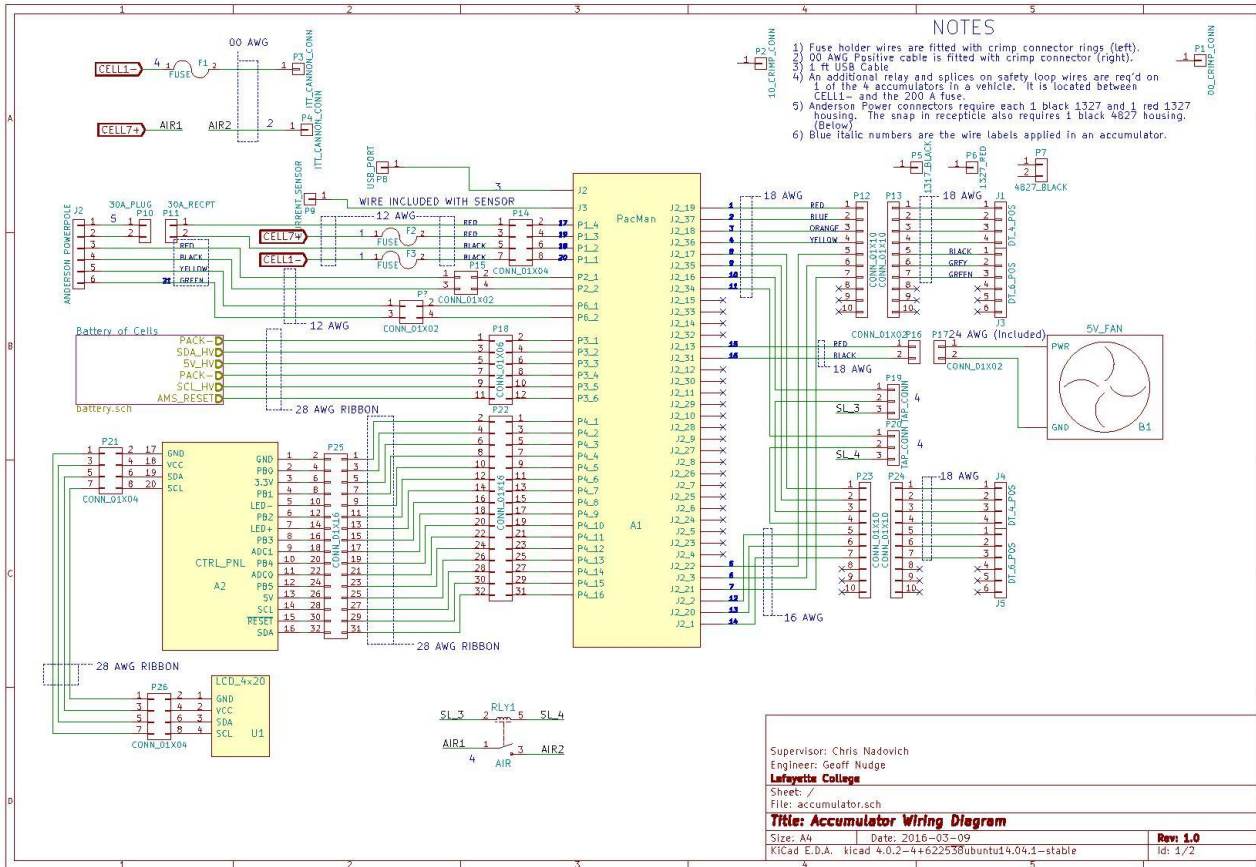
TSV



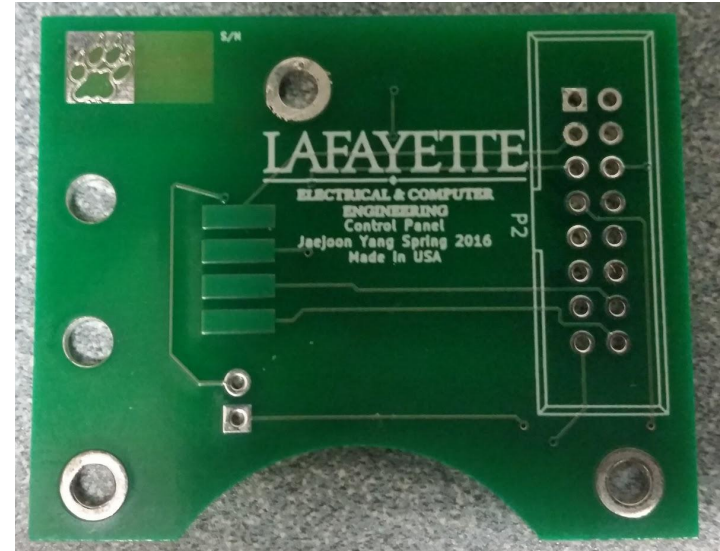
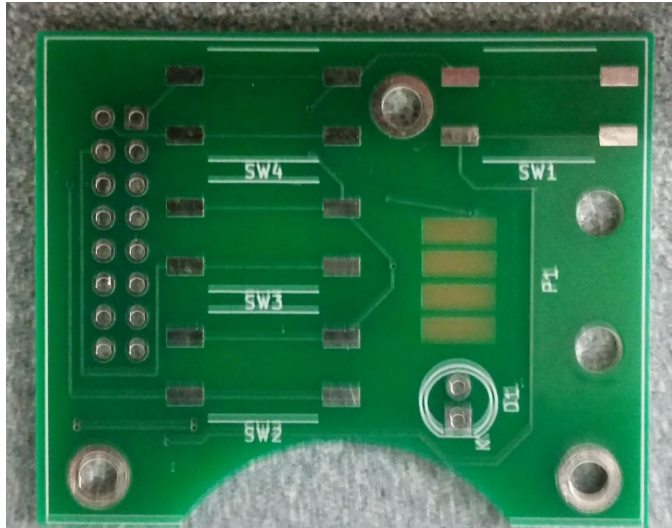
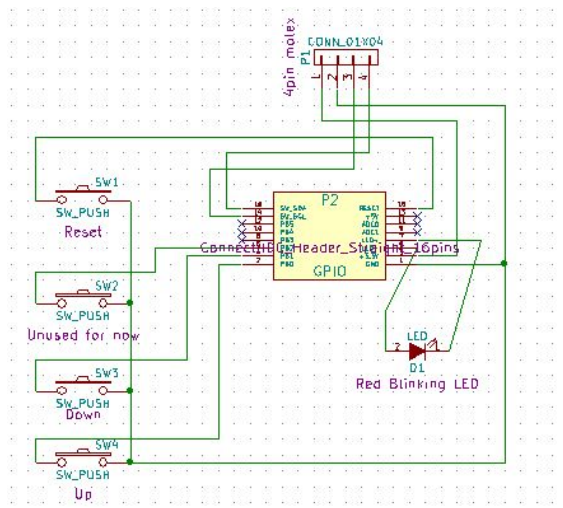
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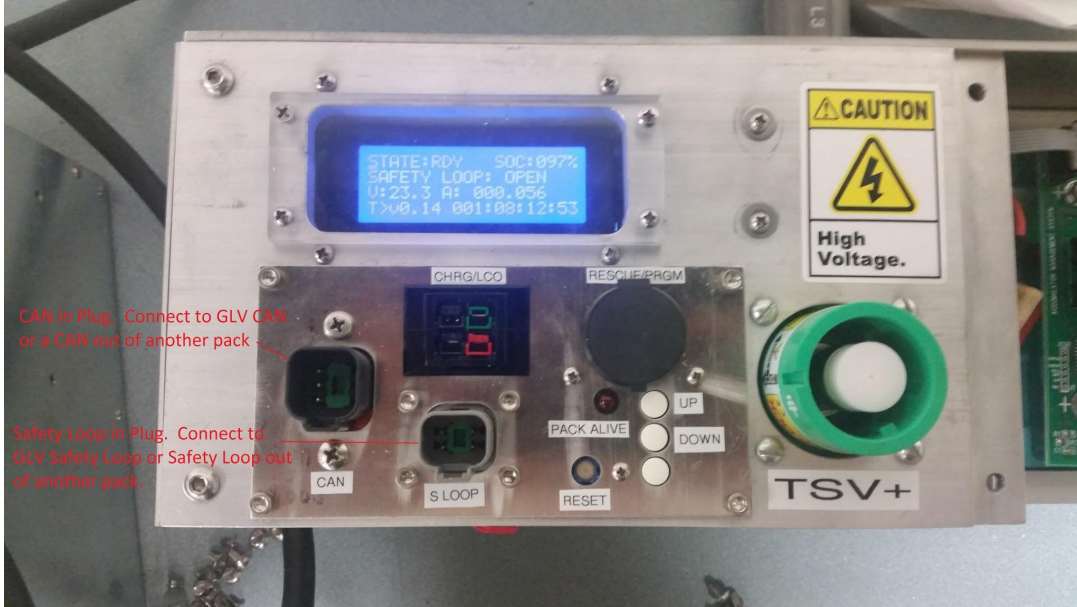
TSV



TSV

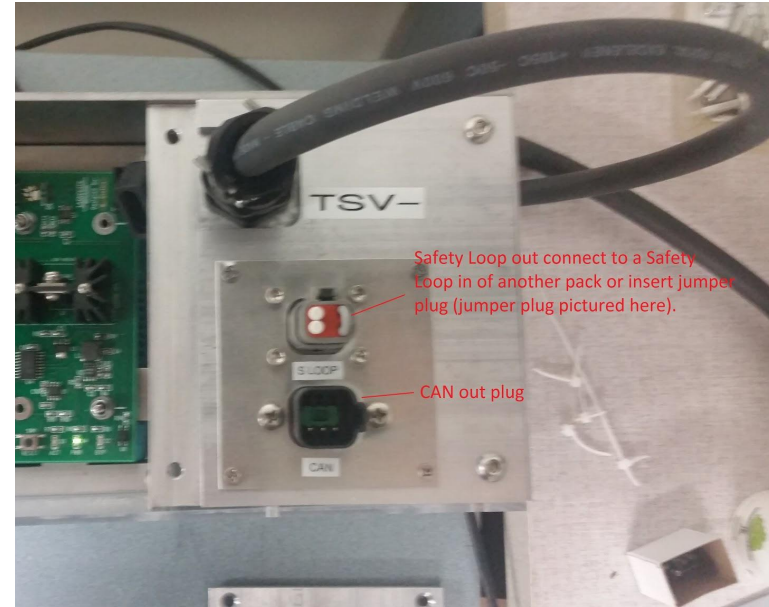


TSV



CAN in Plug. Connect to GLV CAN or a CAN out of another pack


Safety Loop in Plug. Connect to GLV Safety Loop or Safety Loop out of another pack.



Safety Loop out connect to a Safety Loop in of another pack or insert jumper plug (jumper plug pictured here).

CAN out plug


TSV

A close-up photograph of a TSV (Thermal Safety Valve) device. The device is a rectangular metal plate with a blue LCD screen in the center. The screen displays the following text: STATE:RDY SOC:100%, SAFETY LOOP: OPEN, U:23.4 A: 000.056, and T>0.14 000:02:47:02. Below the screen, there are two labels: "CHRG/LCO" and "RES".

STATE:RDY SOC:100%
SAFETY LOOP: OPEN
U:23.4 A: 000.056
T>0.14 000:02:47:02

CHRG/LCO

RES

A close-up photograph of a TSV (Thermal Safety Valve) device, similar to the one on the left. The blue LCD screen displays the following text: STATE:, C0_T:022.6, C0_U:3.342, and T/C0>. Below the screen, there are two labels: "CHRG/LCO" and "RESCUE".

STATE:
C0_T:022.6
C0_U:3.342
T/C0>

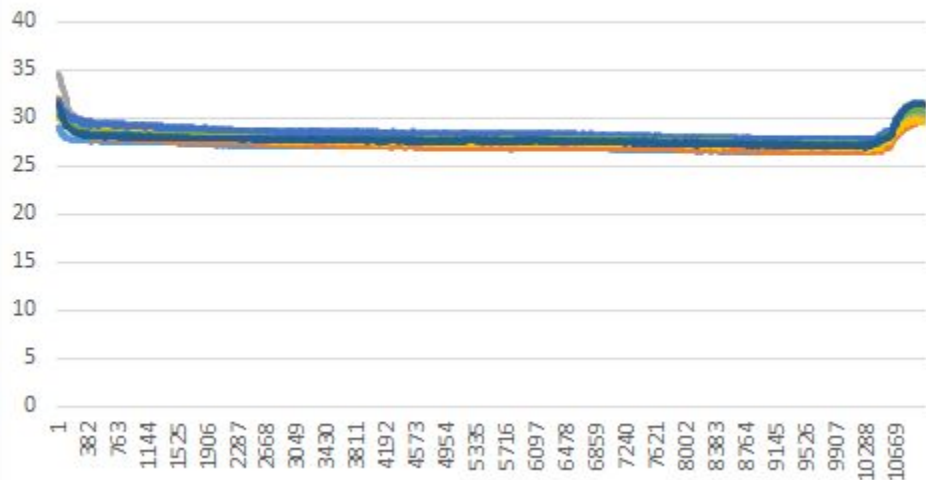
CHRG/LCO

RESCUE

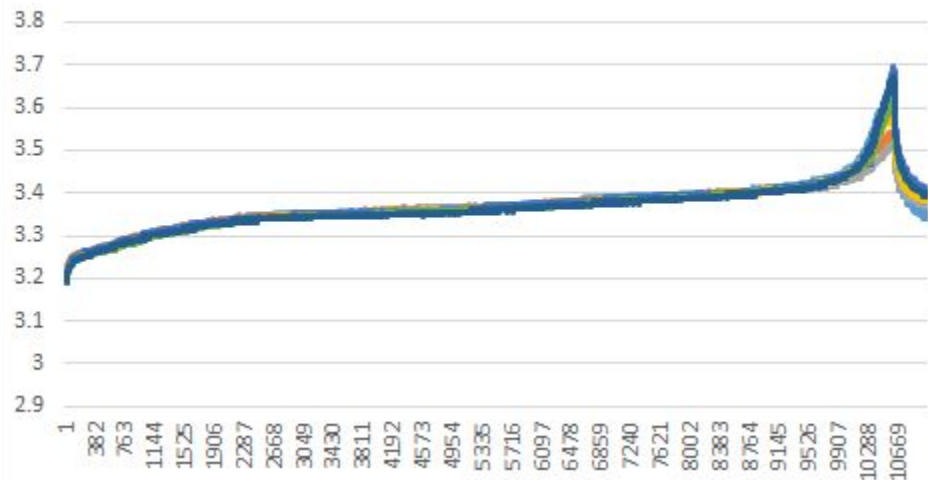
TSV



Initial Charge from 0 to 100: Cell Temp



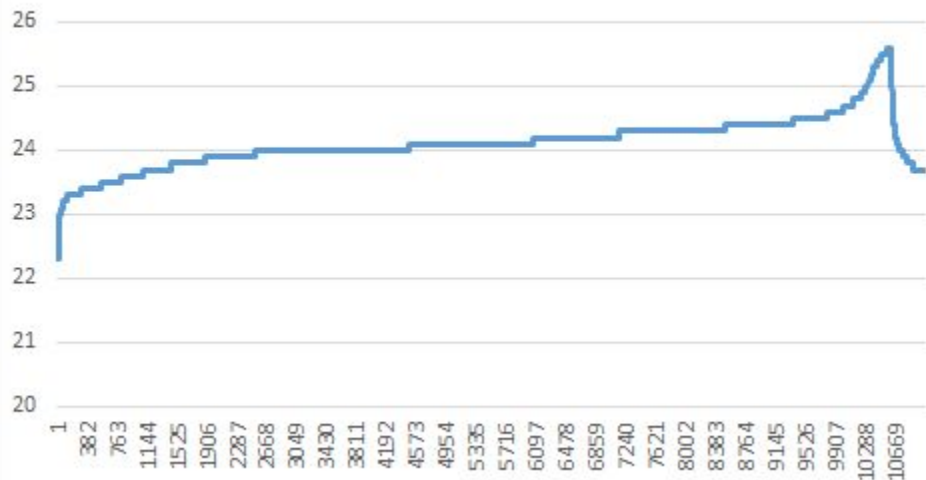
Initial Charge from 0 to 100: Cell Voltage



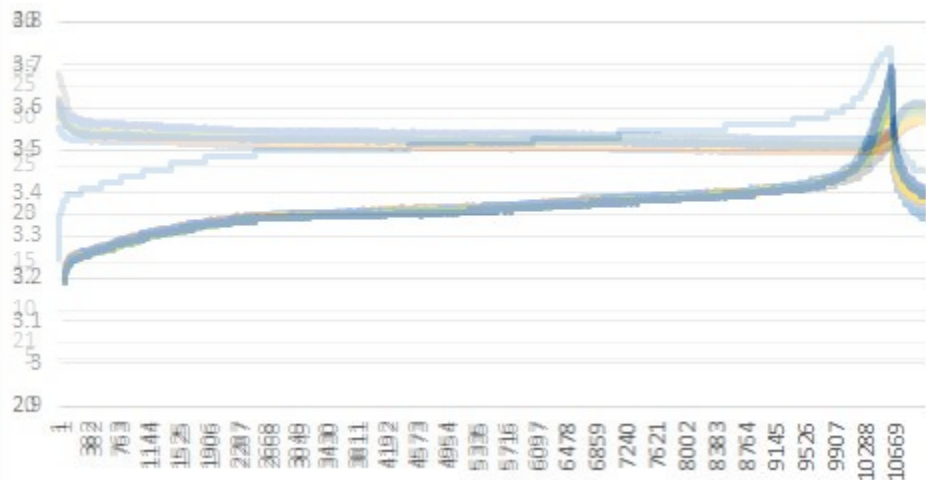
TSV



Initial Charge from 0 to 100: Pack Voltage



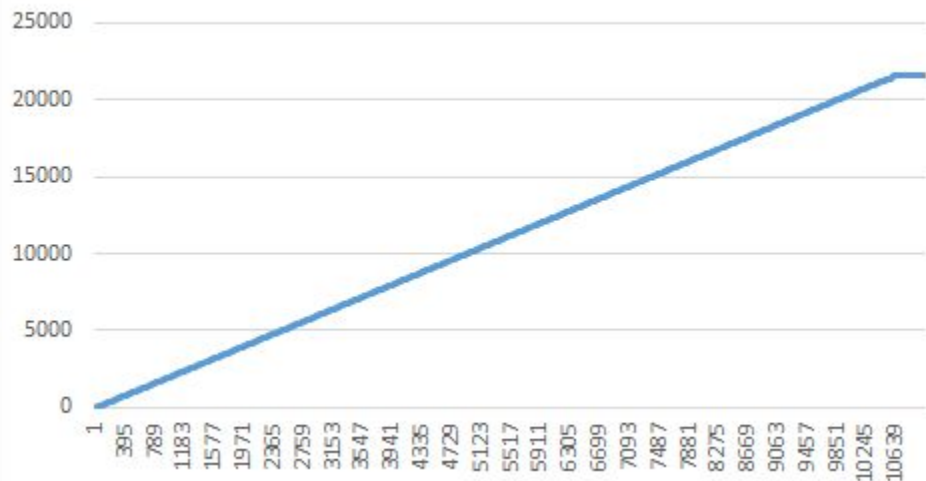
Initial Charge from 0 to 100: Cell Voltage



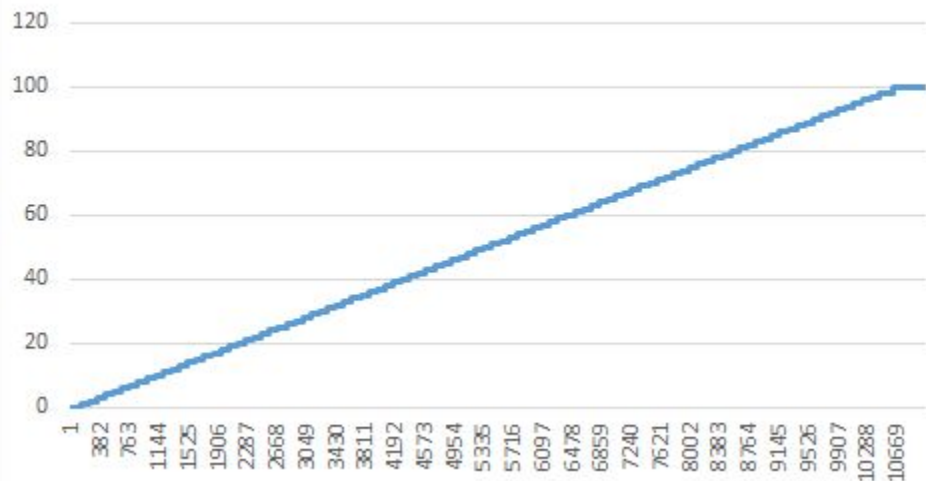
TSV



Initial Charge from 0 to 100: Coulombs



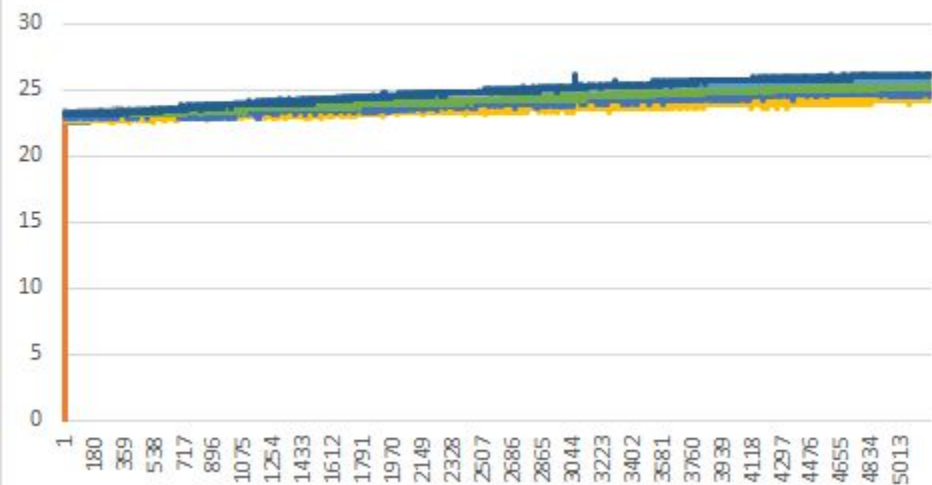
Initial Charge from 0 to 100: State of Charge



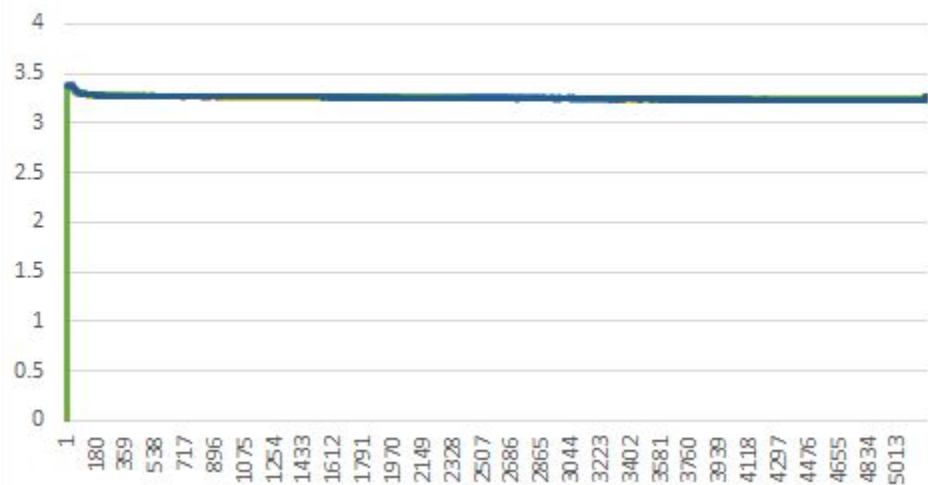
TSV



Low Current Discharge to 50: Cell Temp



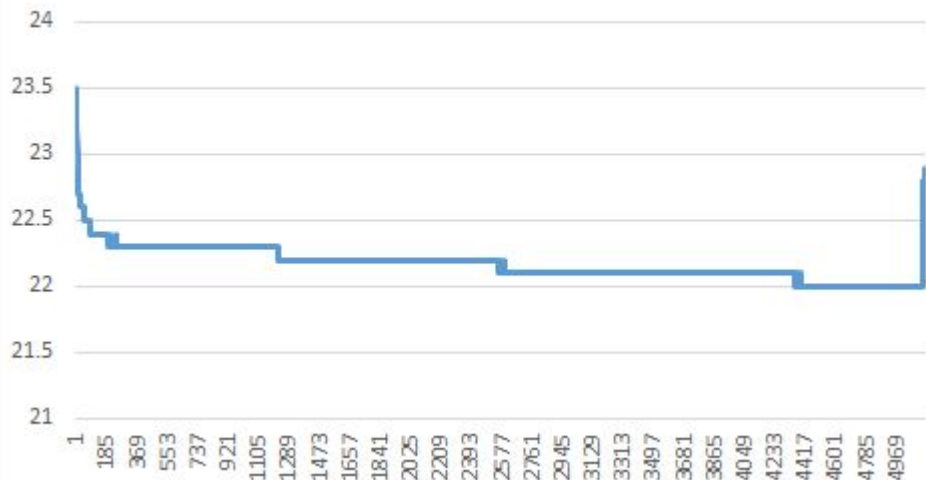
Low Current Discharge to 50: Cell Voltage



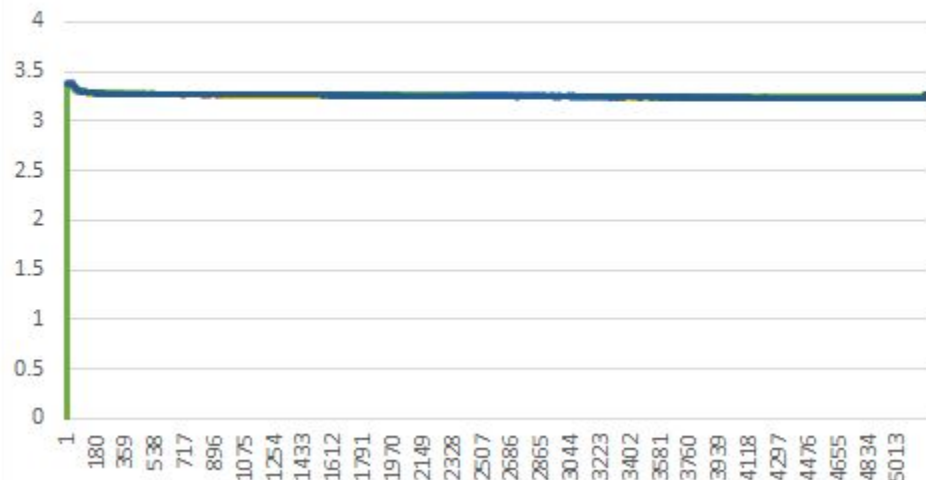
TSV



Low Current Discharge to 50: Pack Voltage



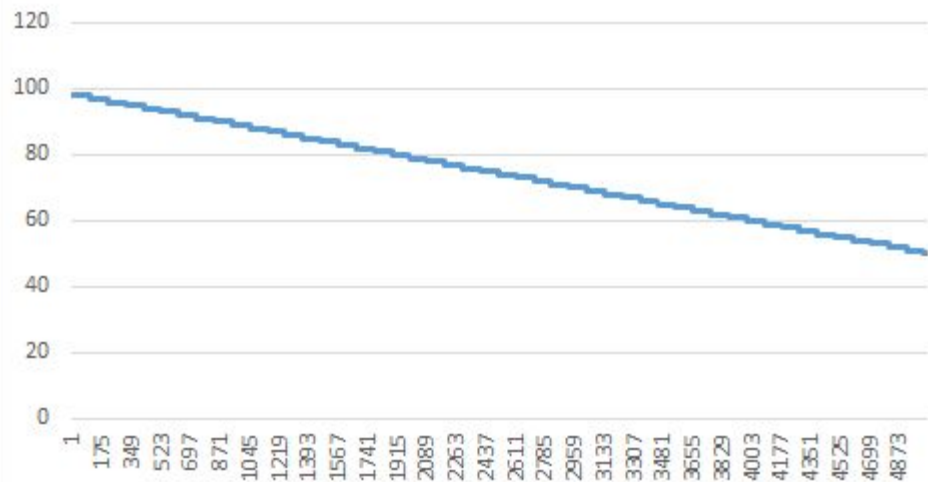
Low Current Discharge to 50: Cell Voltage



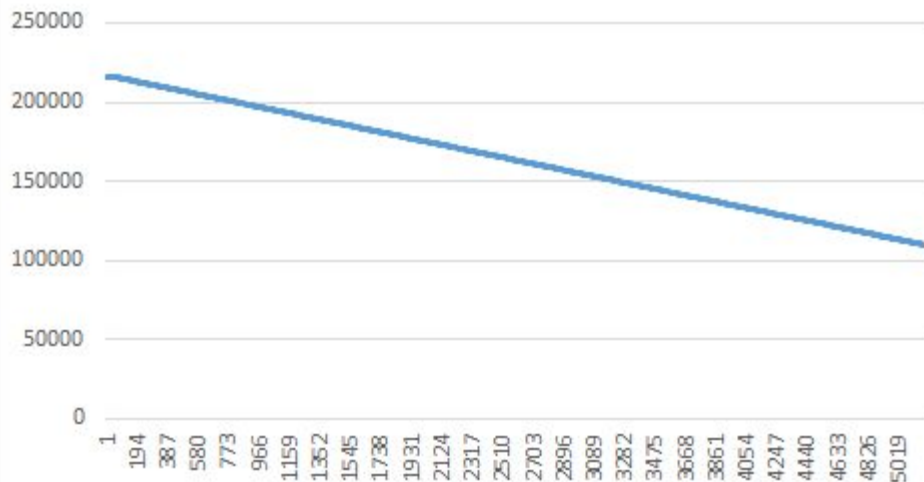
TSV



Low Current Discharge to 50: State of Charge



Low Current Discharge to 50: Coulombs



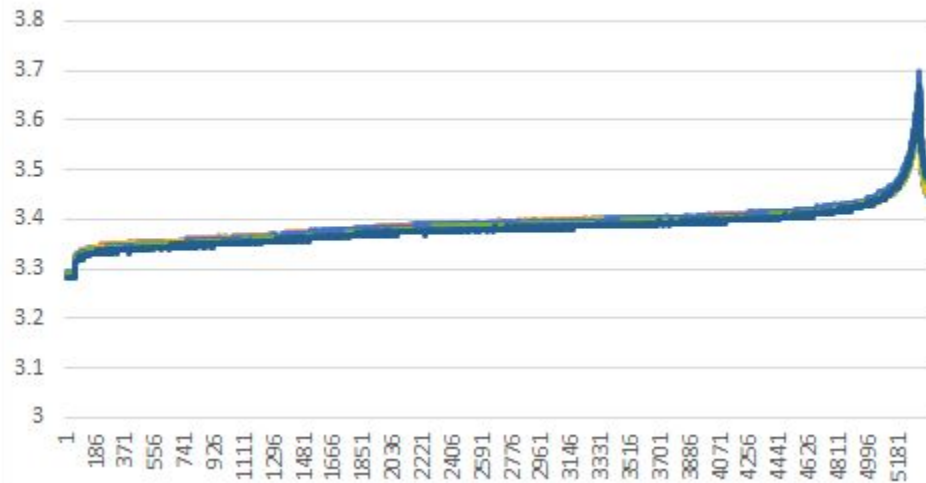
TSV



Charge from 50 to 100: Cell Temp



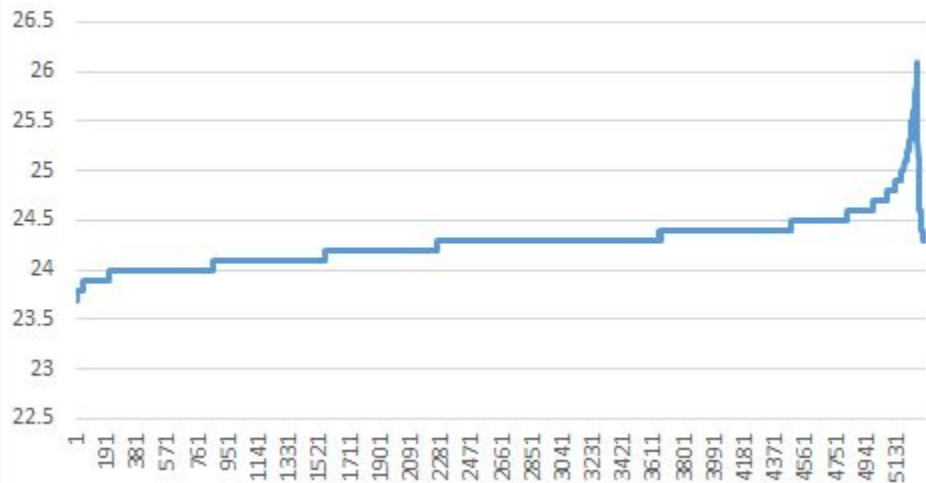
Charge from 50 to 100: Cell voltage



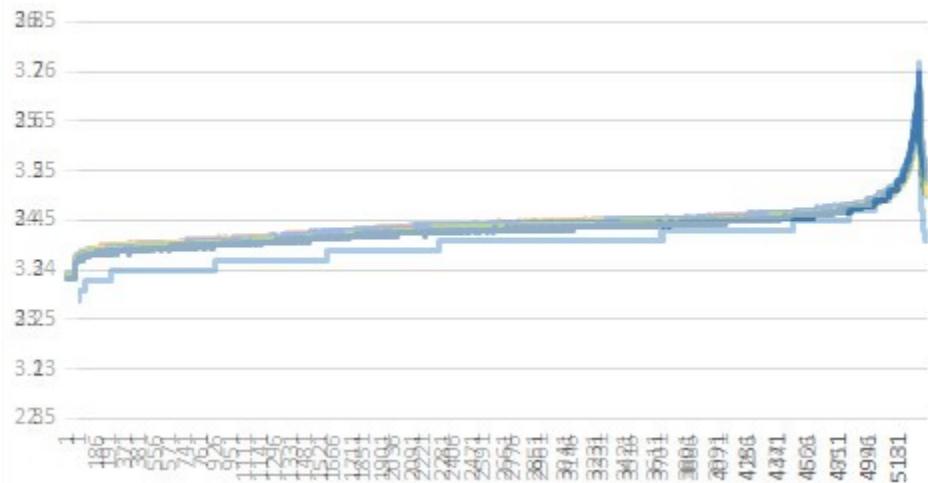
TSV



Charge from 50 to 100: Pack Voltage



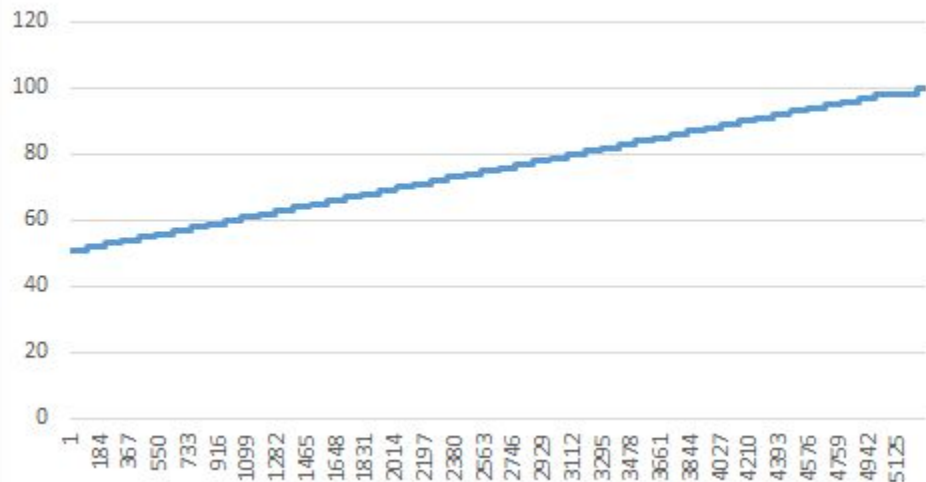
Charge from 500 to 1000: Pack Voltage



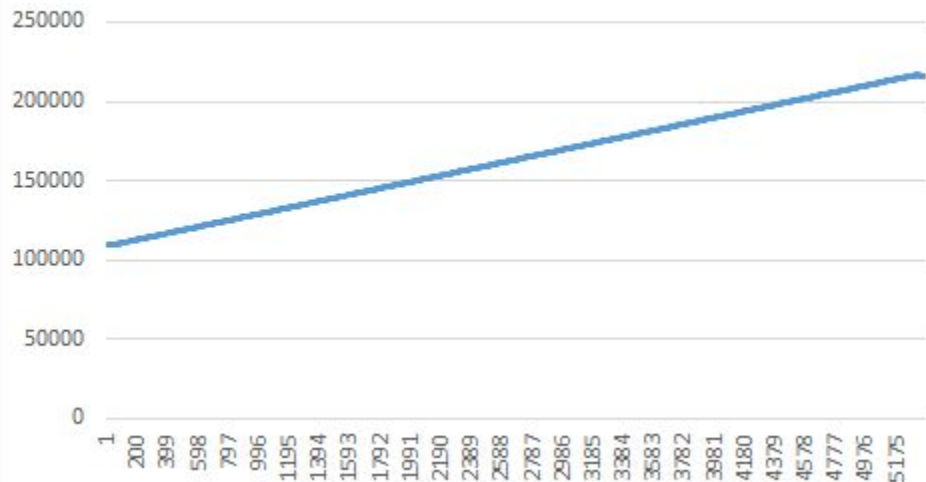
TSV



Charge from 50 to 100: State of Charge



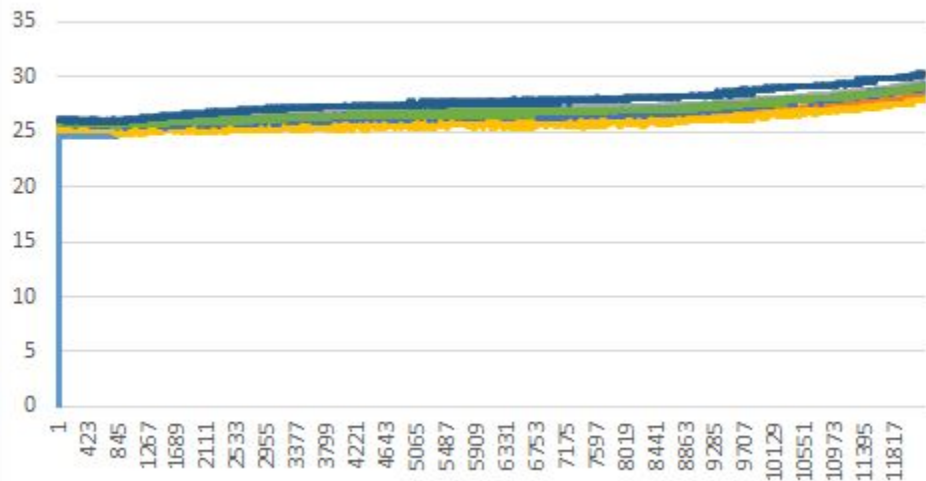
Charge from 50 to 100: Coulombs



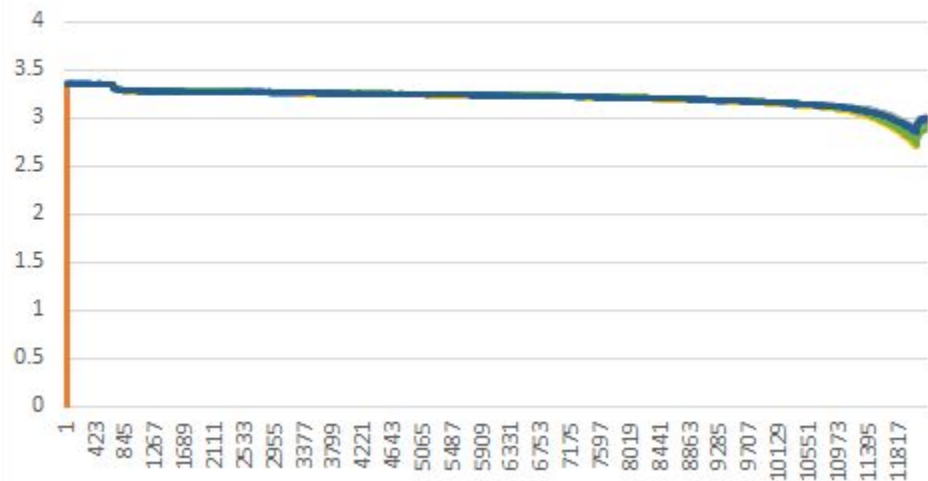
TSV



Low Current Discharge to 0: Cell Temp



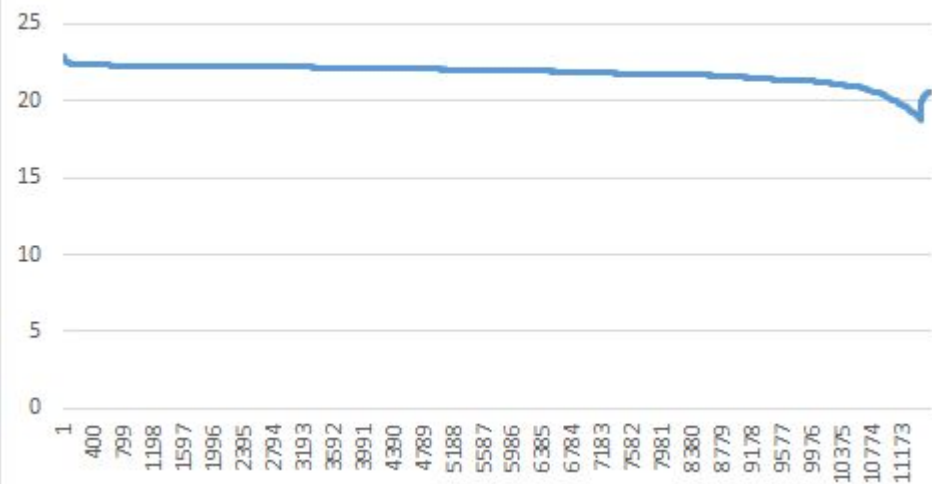
Low Current Discharge to 0: Cell Voltage



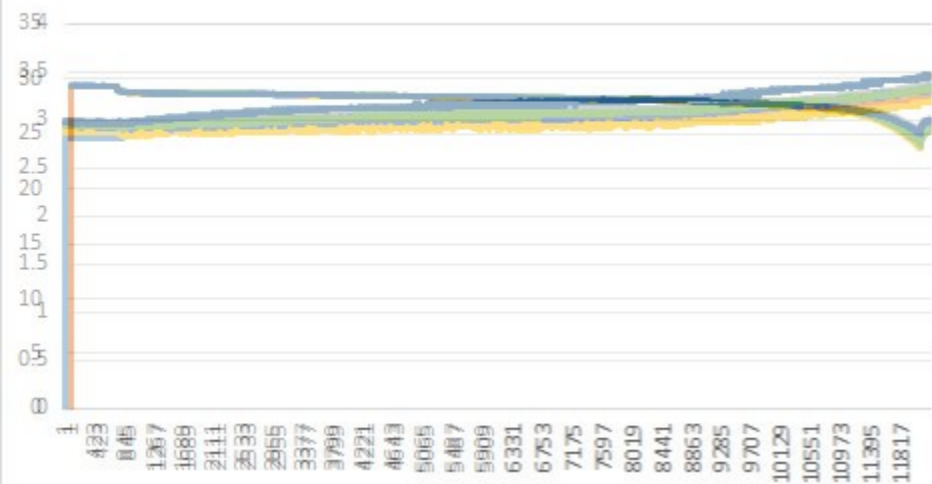
TSV



Low Current Discharge to 0: Pack Voltage



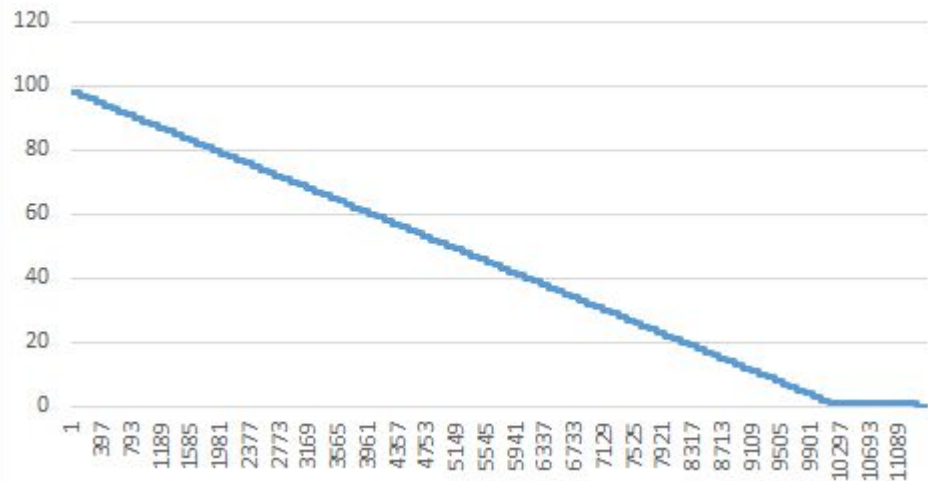
Low Current Discharge to 0 Cell Voltage



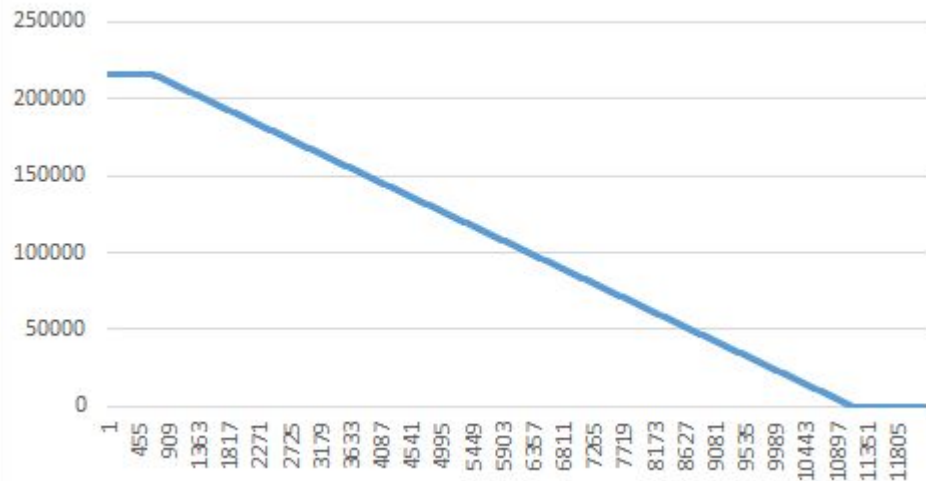
TSV



Low Current Discharge to 0: State of Charge



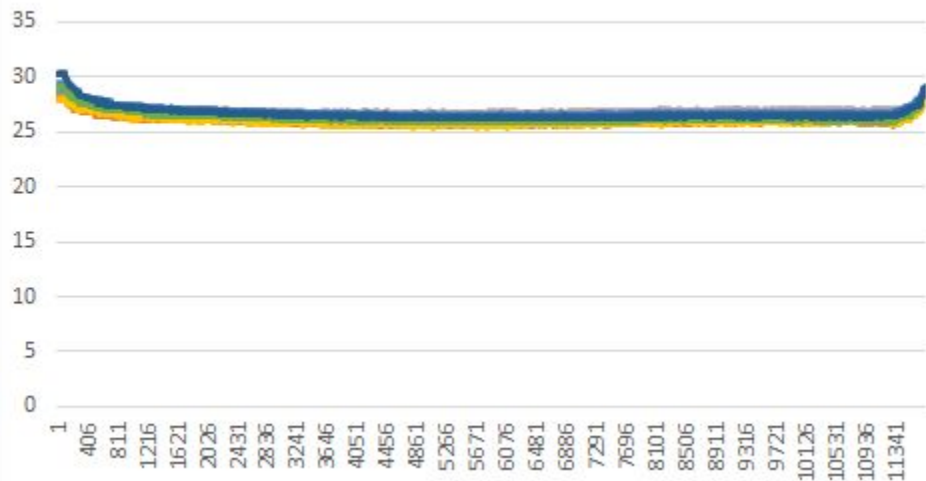
Low Current Discharge to 0: Coulombs



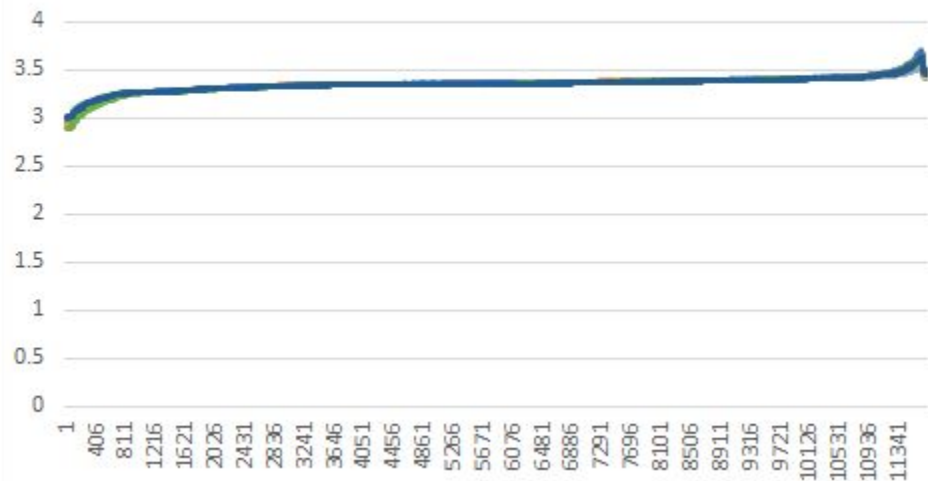
TSV



Second Charge from 0 to 100: Cell Temp



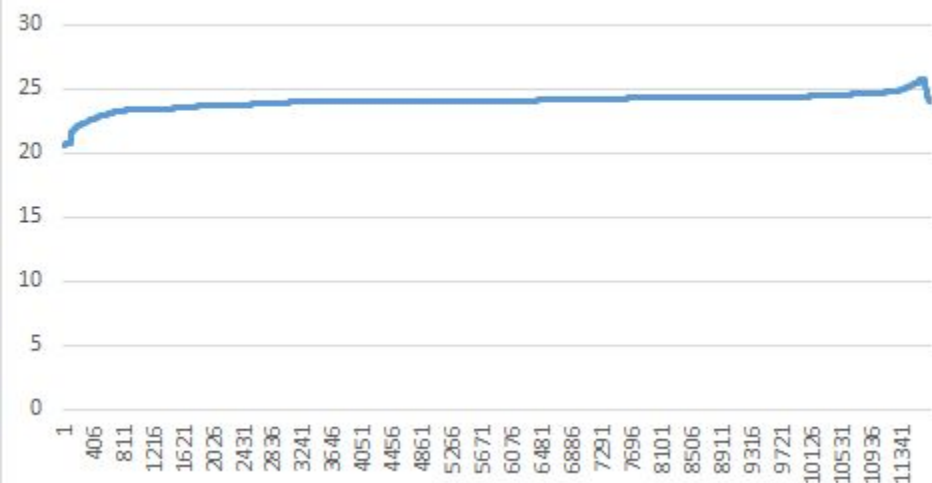
Second Charge from 0 to 100: Cell Voltage



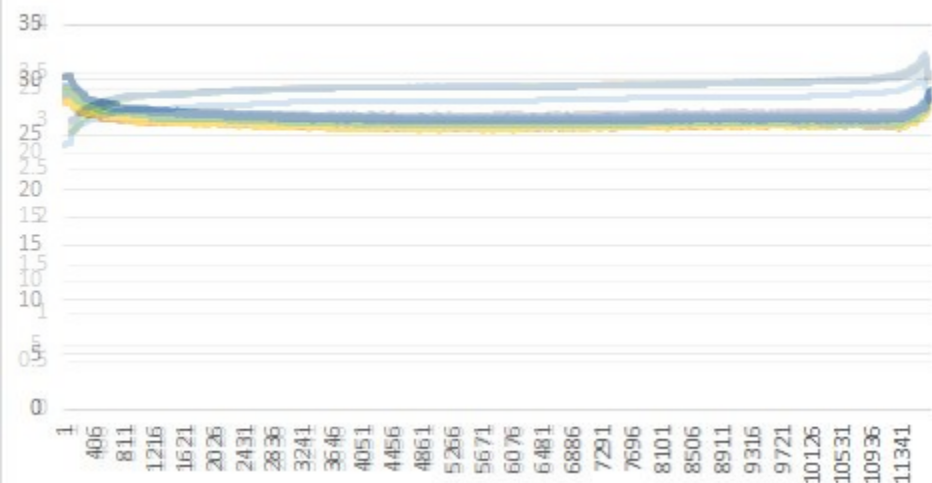
TSV



Second Charge from 0 to 100: Pack Voltage



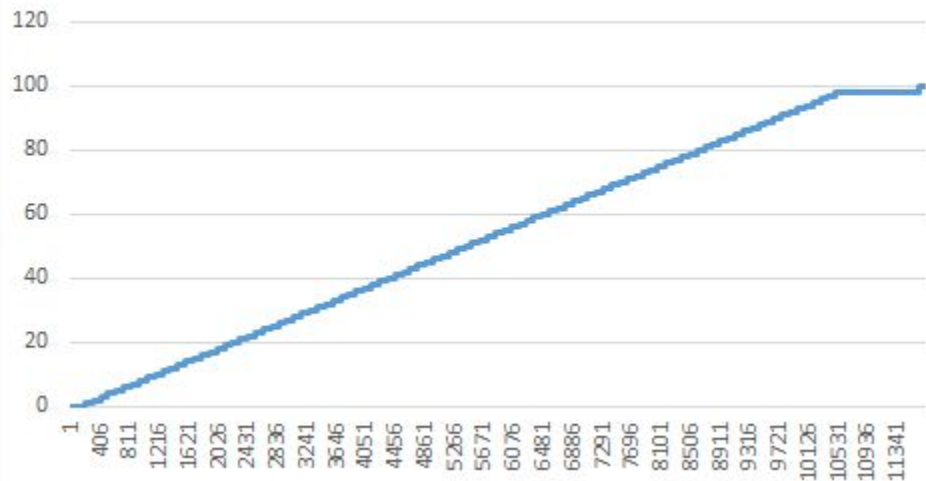
Second Charge from 0 to 100: Cell Temp



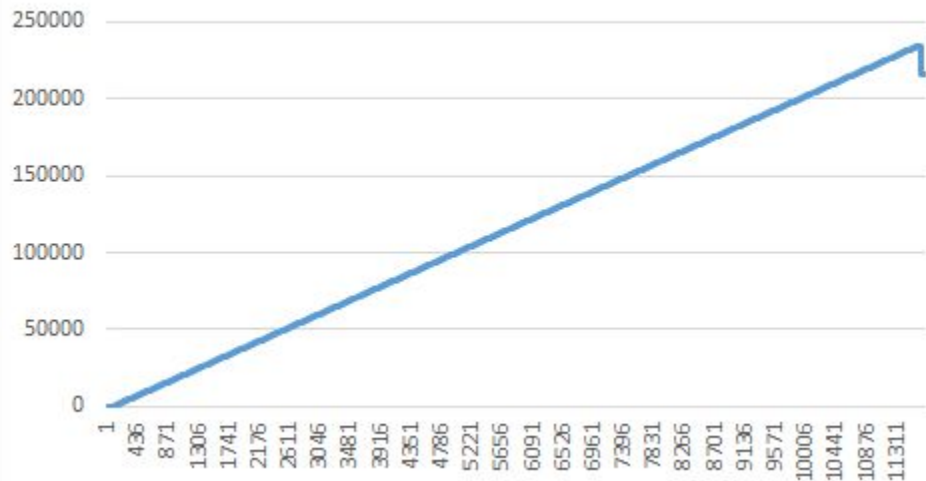
TSV



Second Charge from 0 to 100: State of Charge



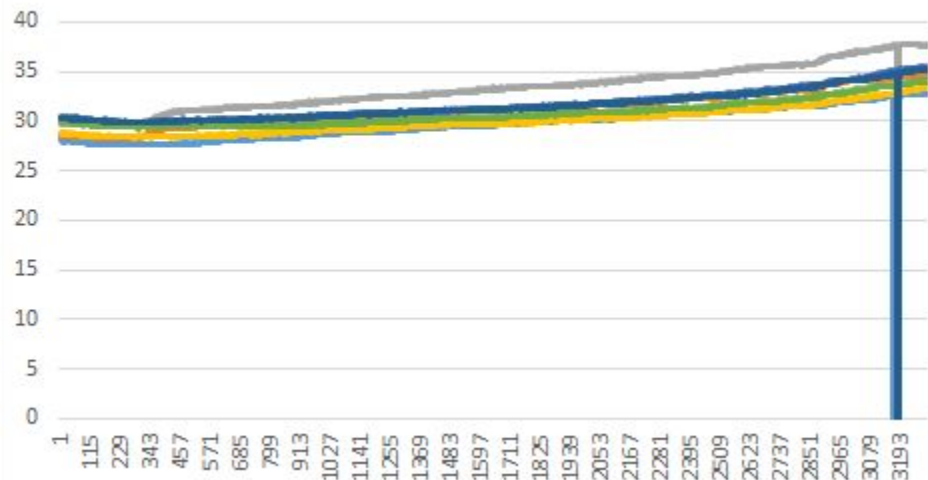
Second Charge from 0 to 100: Coulombs



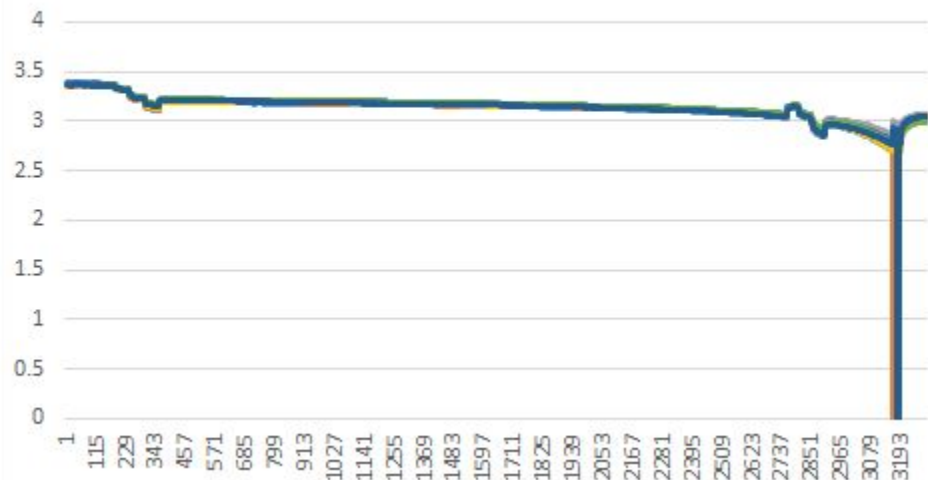
TSV



Varied High Current Discharge: Cell Temp



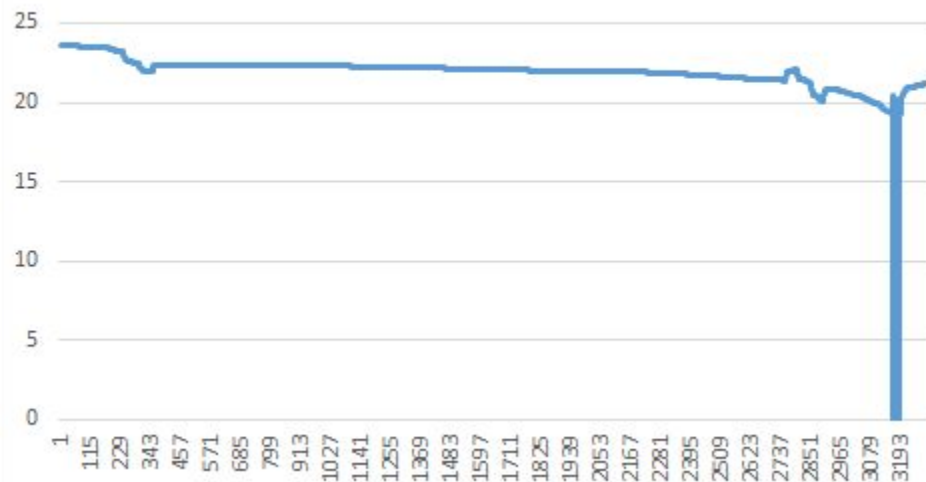
Varied High Current Discharge: Cell Voltage



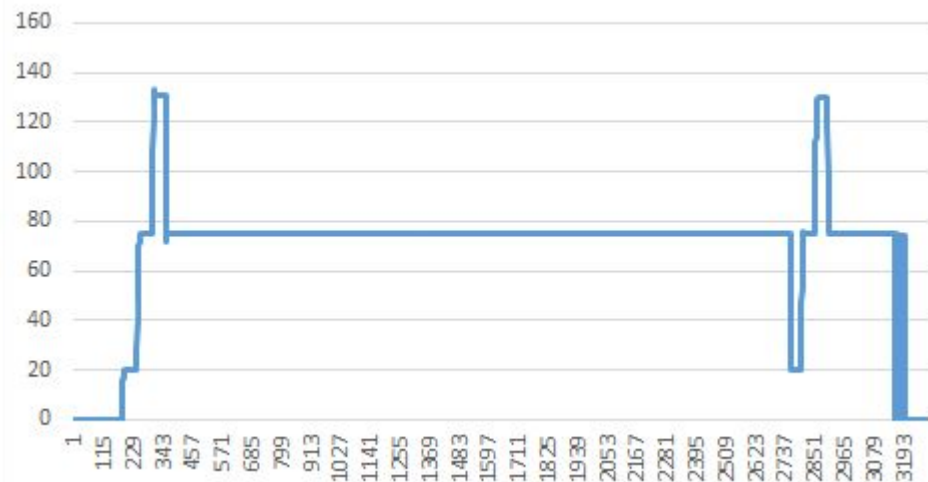
TSV



Varied High Current Discharge: Pack Voltage



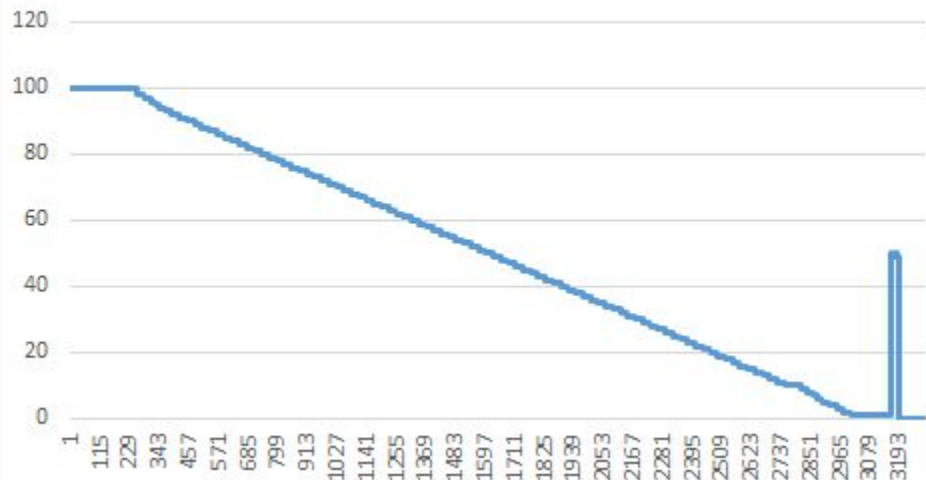
Varied High Current Discharge: Current



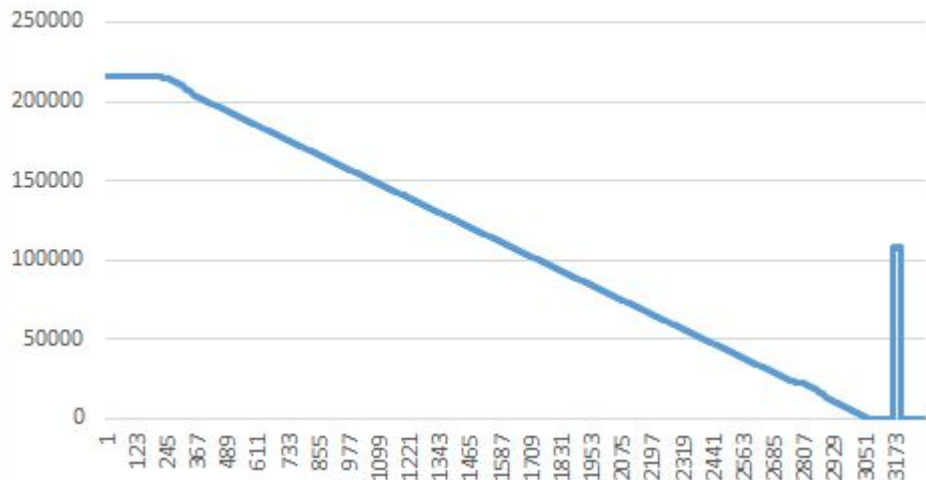
TSV



Varied High Current Discharge: State of Charge



Varied High Current Discharge: Coulombs





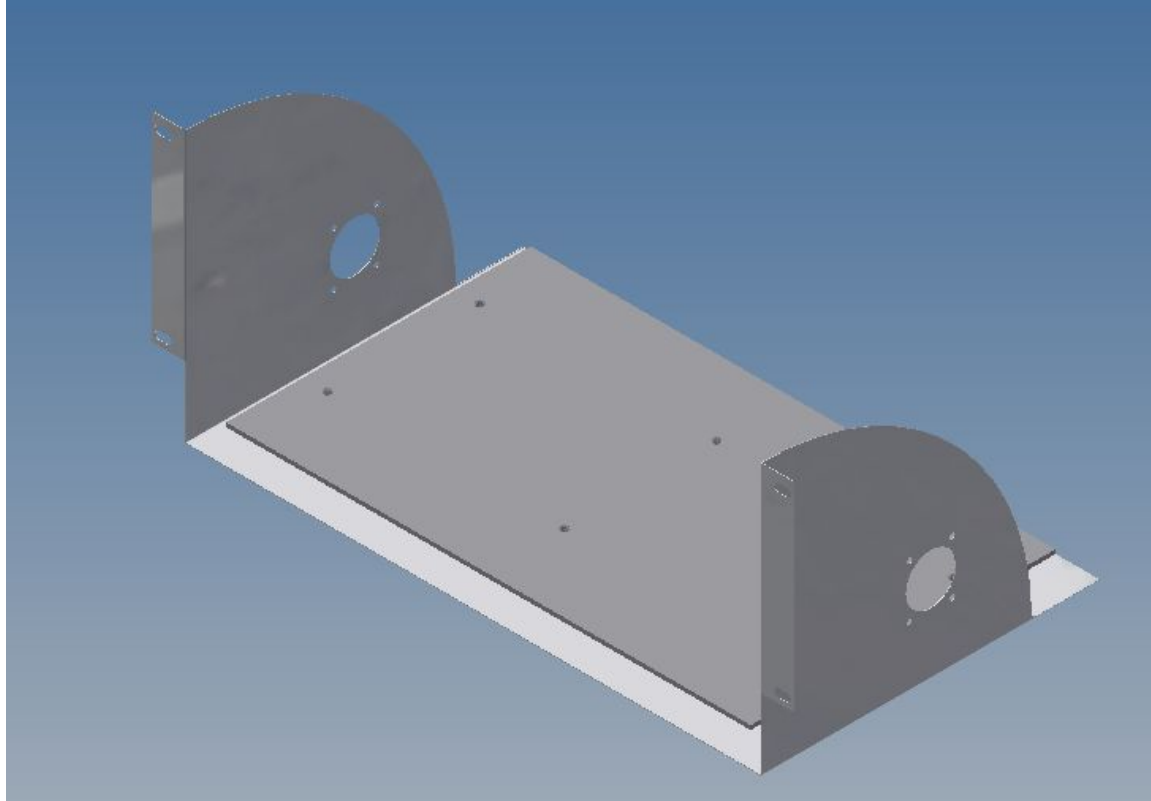
Mech E - Goals

1. Create continuity between years
 - a. Part numbers
 - b. Consolidation of 3D model
2. Physically make one battery pack
 - a. Changes minimized compared to 2015, mostly just electrical accommodations
3. Gathering data for future mechanical work
 - a. Dynamometer
 - b. Research current FSAE vehicle
4. Construction

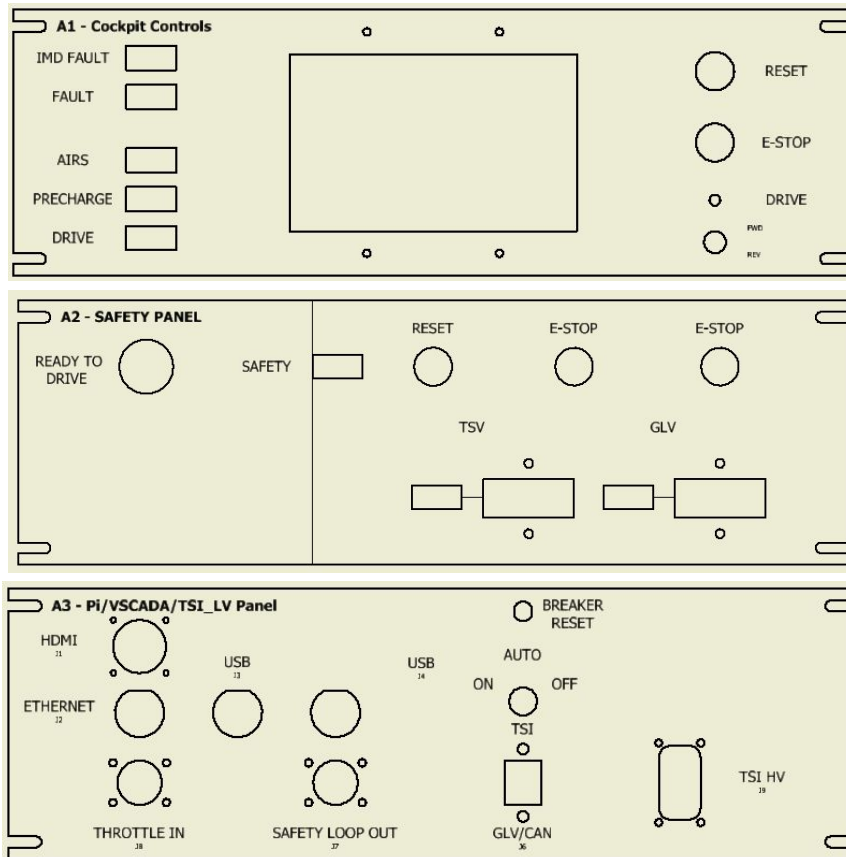
Mech E - Battery Pack



Mech E - Rack

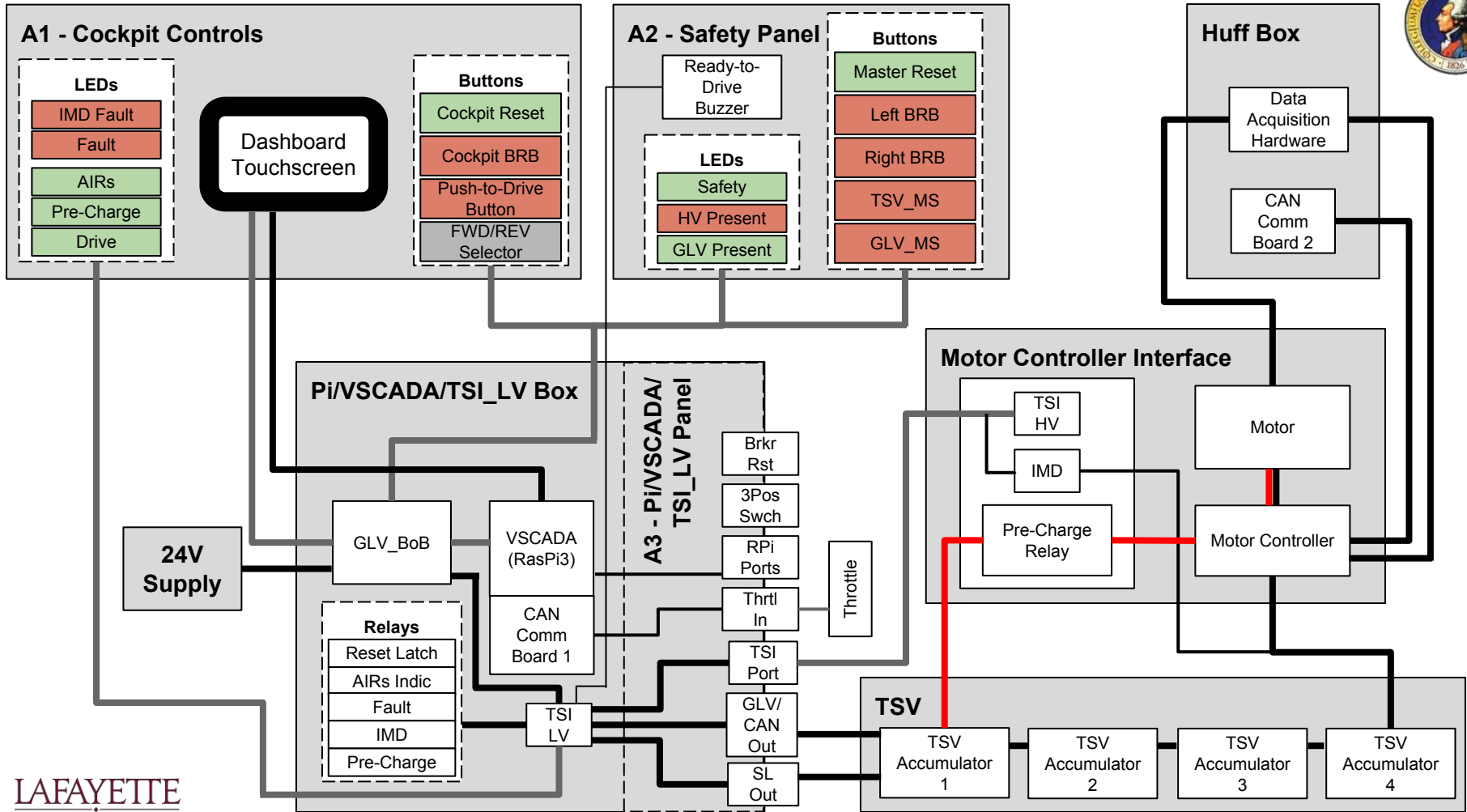


Mech E - Rack





GLV - Grounded Low Voltage



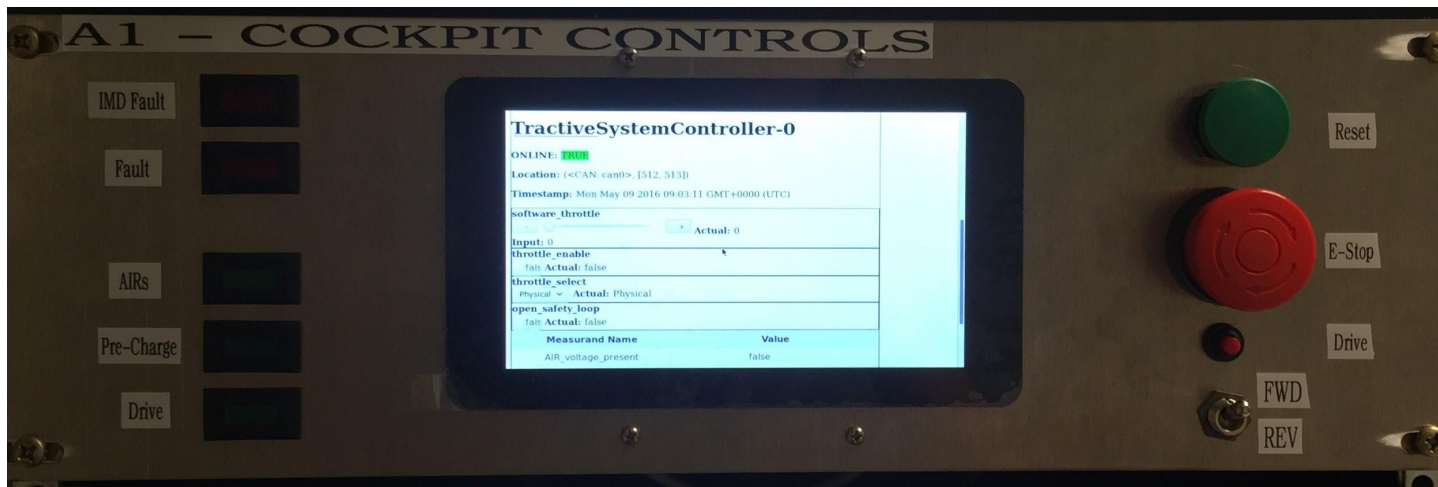


GLV - Purpose

- Provide DC voltage to power non-TSV systems
 - VSCADA, safety loop, insulation monitoring device, etc.
- Safety loop - allows VSCADA or the driver to disable the vehicle in case of emergency
 - Prevents AIRs from closing if there is any sort of fault present
- Indicators, switches, buttons, and cable interconnections that can be used both in the dynamometer test stand and the car
- Tractive System Interface (TSI) - monitors the TSV and GLV sections to ensure they remain isolated; if they are, it allows power to flow between the accumulator packs and the Curtis motor controller and, if not, it opens the safety loop
- Provide connections to allow throttle control and CAN communications between systems



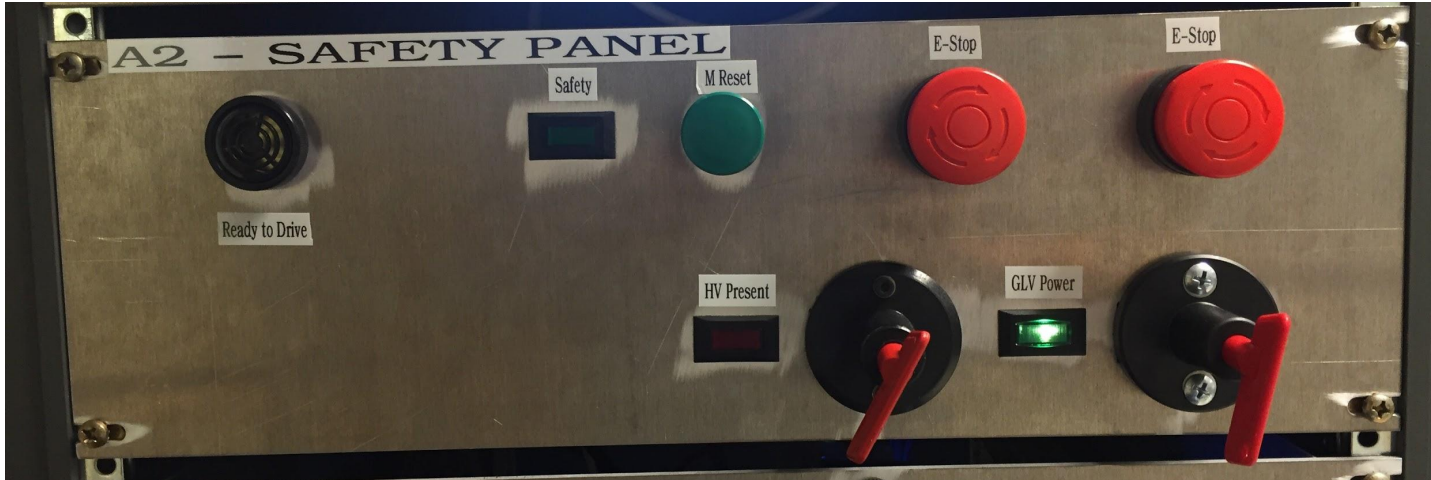
GLV-Cockpit Controls



- IMD FAULT*- Triggered by ground fault
 - FAULT*- General system fault
 - AIRs - AIRs Voltage Present
 - Pre-Charge - Precharge Voltage Present
 - FWD/REV
 - Drive - Car enters drive state
 - Reset - Driver Reset
 - E-STOP
 - Drive - Enter Drive mode
- *non-driver resettable



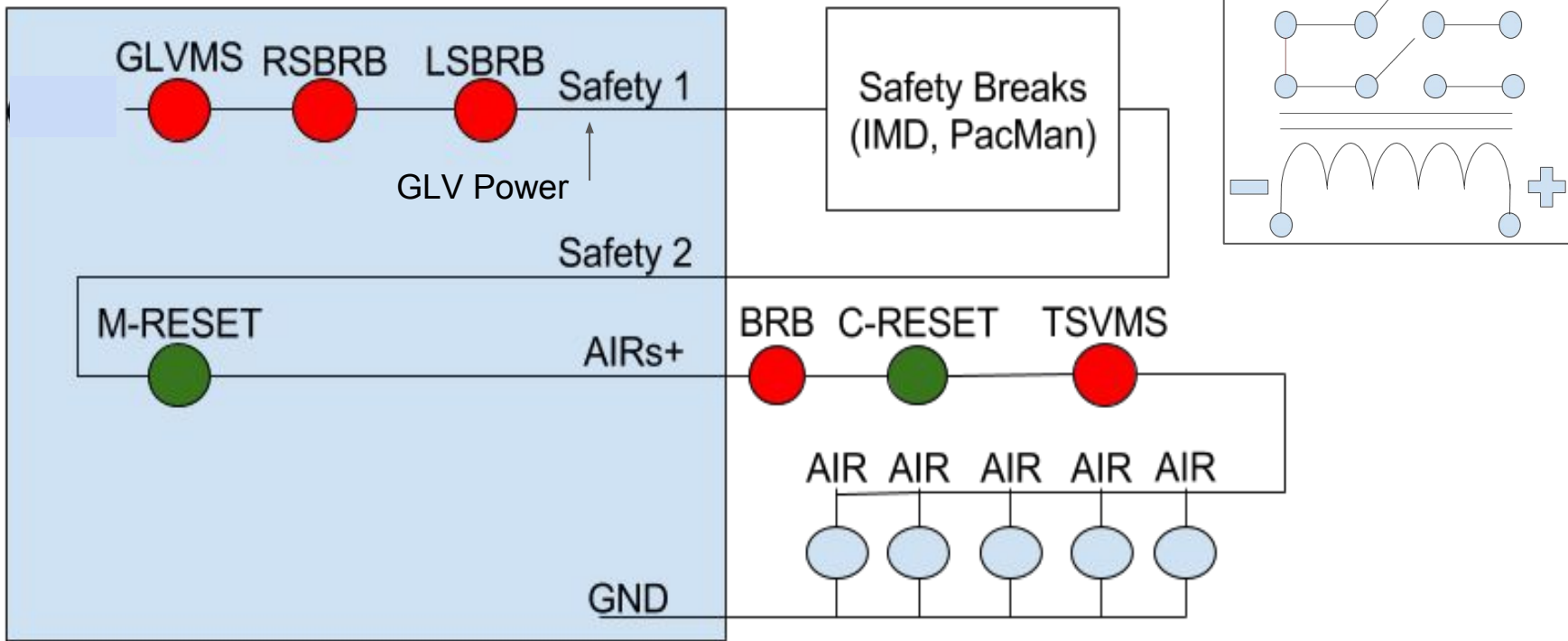
GLV-Safety Controls



- Ready to Drive- Sound indicating drive mode has been entered
- Safety- Safety loop voltage present
- M_Reset- Required reset for all faults
- HV Present- When HV is present at Motor Contr.
- GLV Master SW- Required for GLV Power
- GLV Power - 24 Volts
- E-STOP (Right)
- E-STOP (LEFT)
- TSV Master SW - Required for AIRs voltage to be present



GLV-Safety Loop





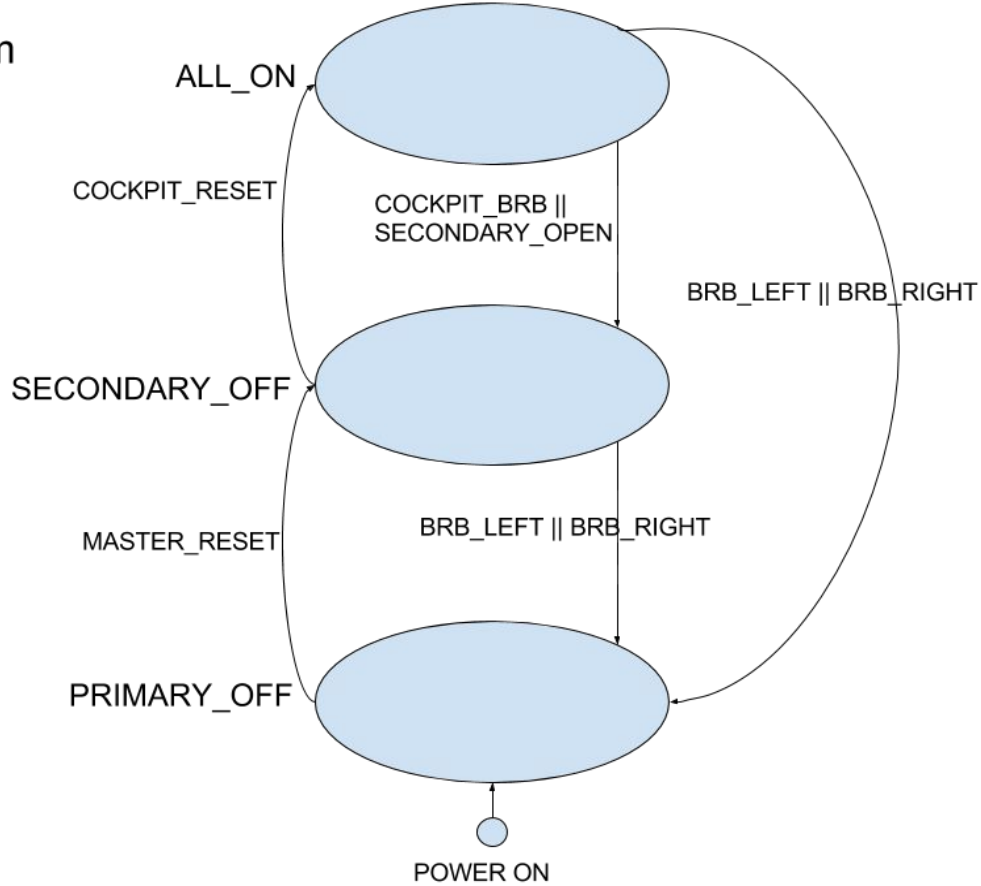
GLV-Safety Loop Cont.

Safety Loop State Diagram

In ALL_ON, the START button requests SCADA allow physical throttle.

Reset button will only cause transition if corresponding BRBs are closed.

These states are stored by the physical position of BRBs and Reset buttons.





GLV - VSCADA/TSI LV



- HDMI/USB 1/USB2/Ethernet - These are for using a mouse and keyboard with the Raspberry Pi, internet and an external monitor
- Throttle IN- External throttle connection (POT)
- Safety Loop Out
- GLV/CAN
- TSI Selector SW- ON (on when precharge is present) OFF (always off) AUTO (software defined)
- TSI-HV - Cable for connecting TSI-LV to TSI-HV



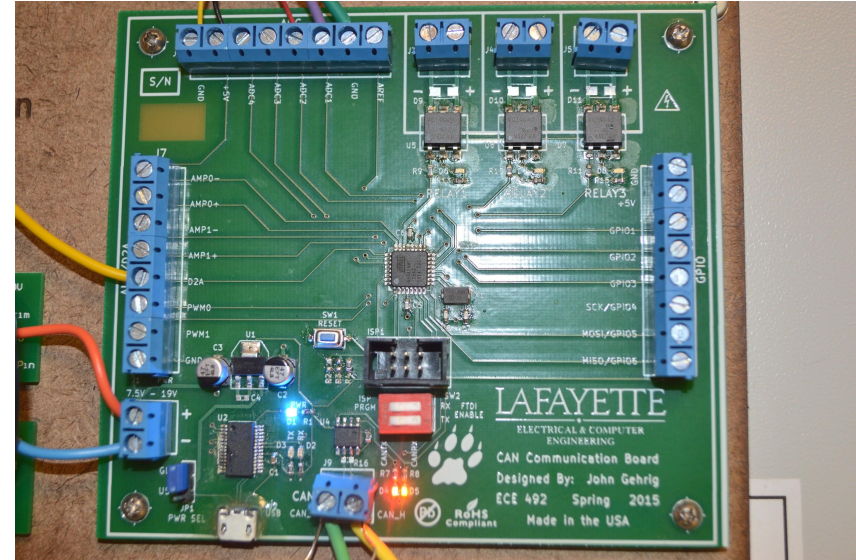
GLV-TSI (HV/LV) /VCI

- The GLV system is intended to run off of a 24V+ battery that is independent of the TSV battery
- GLV distributes +5V, +12V, +24V, CAN_H and CAN_L, and the four wire safety loop
- Safety Loop Safety1, Safety2, AIRs+, and GND
- GLV interfaces with the scada computer (Raspberry Pi 3)
- 2x USB, 1x Ethernet, 1xHDMI, and I2C from the Raspberry Pi 7" touch screen and CAN
- The traditional Tractive System Interface have been split into two sections TSI_LV and TSI_HV
- The TSI_LV contains a JGB, DIN rail relays and TSI prototype board
- The TSI_LV contains all of the logic for the TSI_HV
- The TSI_HV contains the HV voltage measuring point, the precharge relay, the current sensor, IMD, (Insulation monitoring device), the CAN bus isolator, and an Isolation board to isolate relevant signals living inside HV Land



GLV - JGB

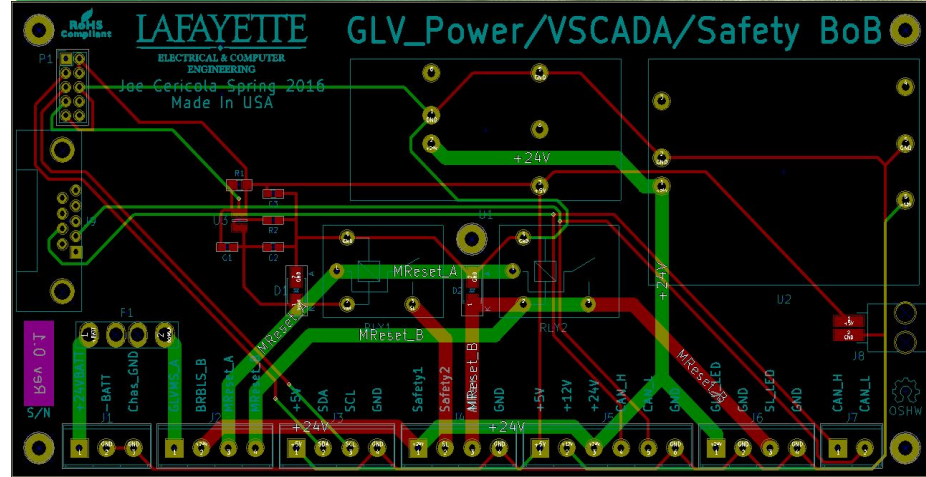
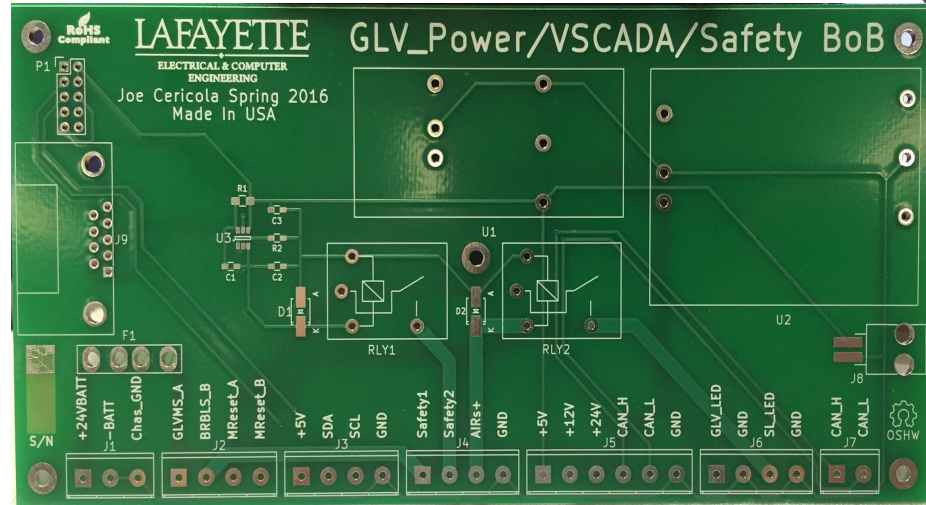
- Multi-mode board capable of analog-to-digital conversions, digital-to-analog conversions, GPIO, controlling onboard relays, and CAN communication with SCADA
- Mode is selectable based on voltage present on 4th ADC
 - Tractive System Controller - 0V present
 - Reads in drive button, physical throttle voltage, current meter output voltage, and AIR voltage
 - Controls relays for safety loop, precharge relay, and drive mode light
 - Outputs throttle voltages based on state of safety loop, SCADA controls, and input values
 - Huff Box DAQ - 5V present
 - Reads in torque valve voltage and oil temperature sensor voltage
 - Outputs load valve voltage based on values sent from SCADA





GLV_Power/VSCADA/ Safety BoB

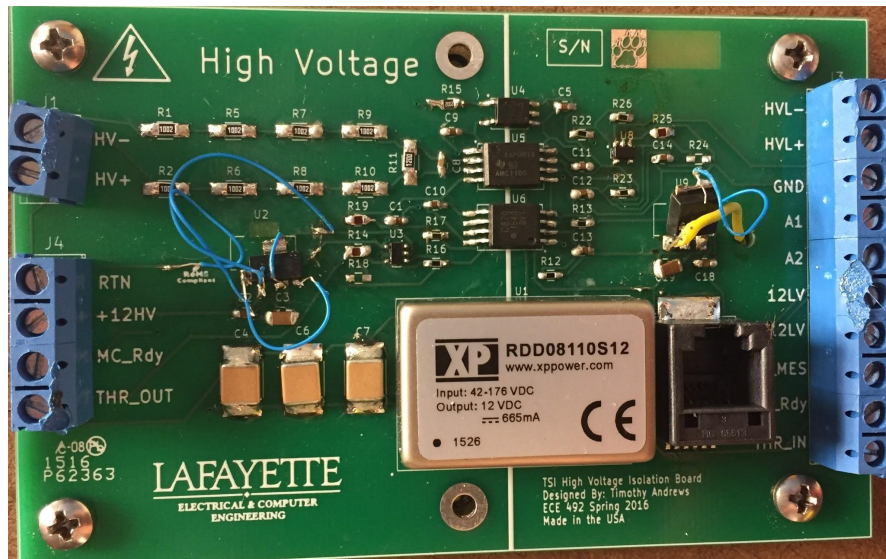
- Handles safety loop routing
- Handles GLV power routing
- Handles SCADA interfacing with the rest of the system
- Includes 1x Safety Loop break
- Includes Routing to the Raspberry Pi Touch Screen
- Two DC to DC converters for 12V and 5V for additional systems, Lights, and Relays





GLV-TSI HV Isolation Board

- The TSI_HV contains the HV voltage measuring point and isolation
- The precharge relay for the motor controller is routed through this board; the signal is isolated
- The current sensor plugs into the RJ-12 jack
- HV voltage light is bucked down and provides power to the HV voltage present light
- The throttle input from the SCADA computer or the driver is passed through and isolated





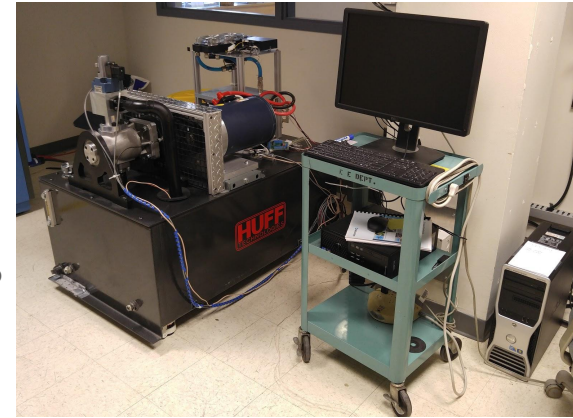
GLV - Errata

- Safety Loop
 - Refabricating revised TSI-HV board
 - Motor controller isolation and IMD
- Power
 - Migrate from power supply to battery system
- Miscellaneous
 - Precharge return line behavior
 - Forward and reverse switch wiring and safety mechanisms preventing its use in undesirable conditions such as when motor is spinning
 - HV measurement at TSI-HV untested/uncalibrated
 - Current measurement at TSI-HV untested/uncalibrated



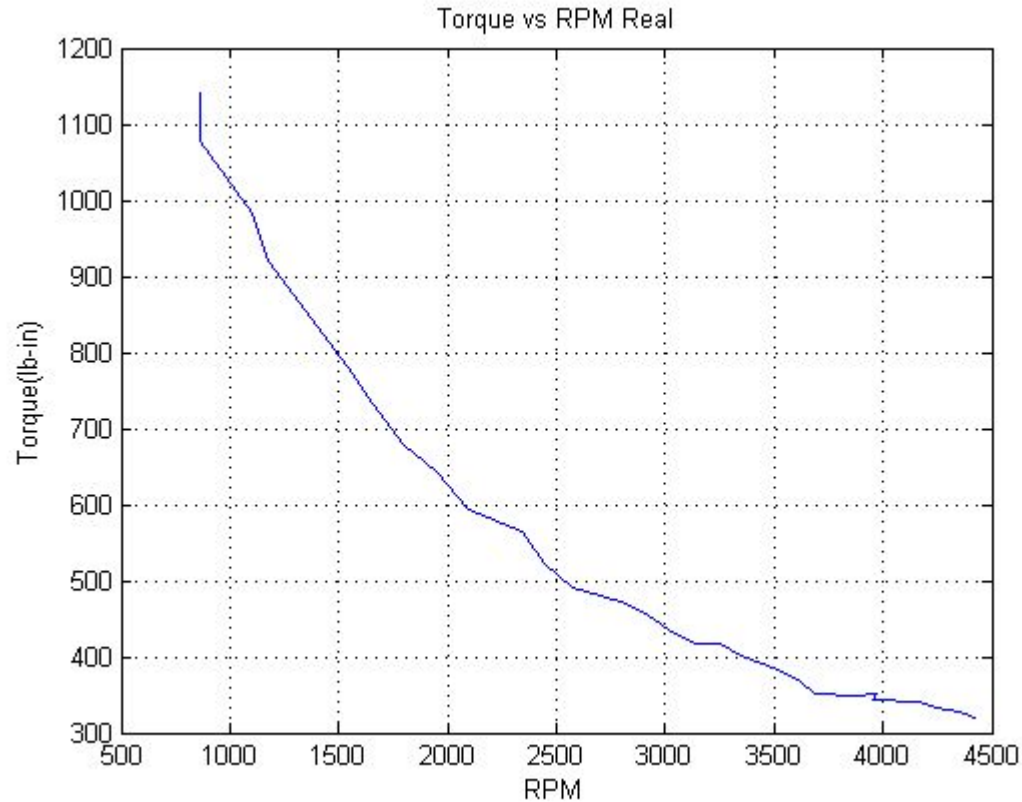
MCM - Purpose

- Static Characterization
 - Full Power curve Torque vs RPM
 - Determine the motors limits and best Gear ratio for use in the vehicle
- Dynamic Characterization
 - What is the max acceleration for the fully integrated car?
- Efficiency
 - What is the most efficient speed we can run the vehicle?
- Cooling
 - Does the car benefit from having cooling? Does it improve efficiency?





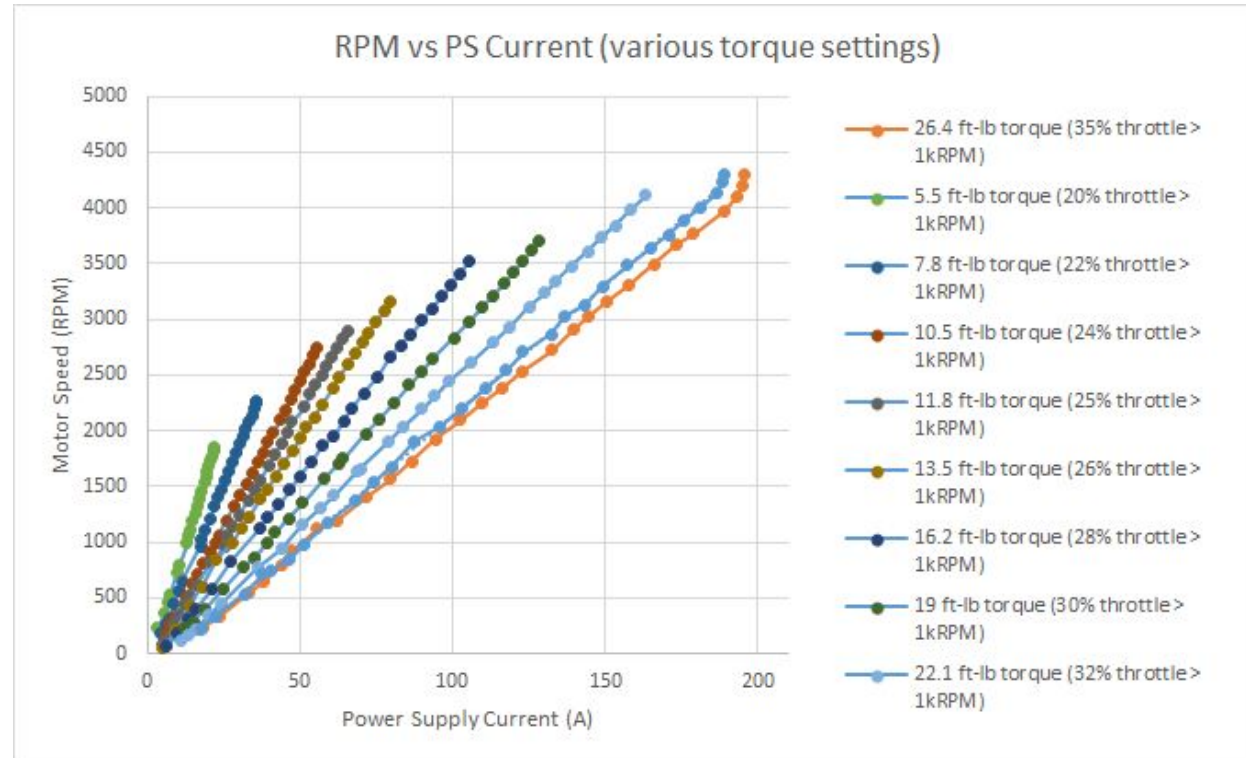
MCM- Static Characterization





MCM- Static Characterization

- Relationships determined between system inputs and measurable outputs
 - Controller corresponds throttle input with torque values
 - load only varies speed





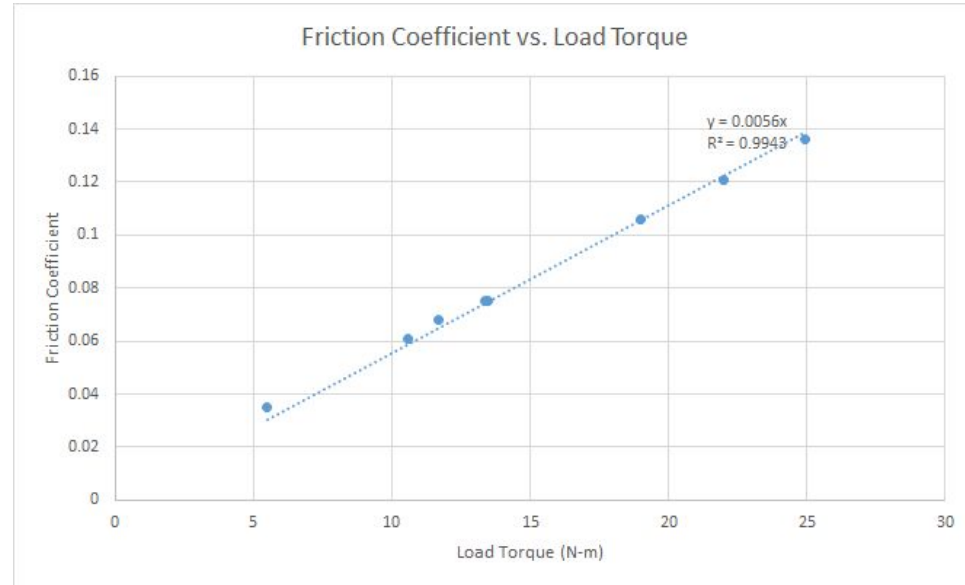
MCM- Static Characterization

Comparing the equation we produced

$$.0056T_L = \frac{4.305i}{w} - \frac{T_L}{w}$$

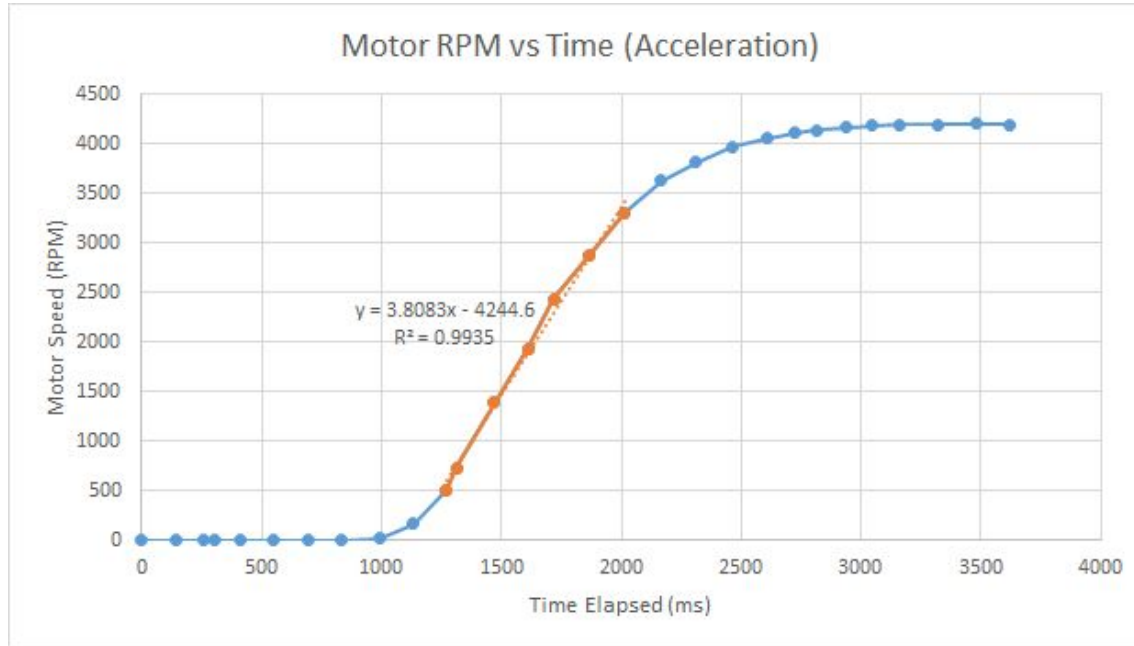
$$w = \frac{768.75i}{TL} - 178.57$$

With multiple experiments, within the operating range of 1000-4500 RPM there is a +/- 5.7% accuracy in our equations ability to predict motor RPMs





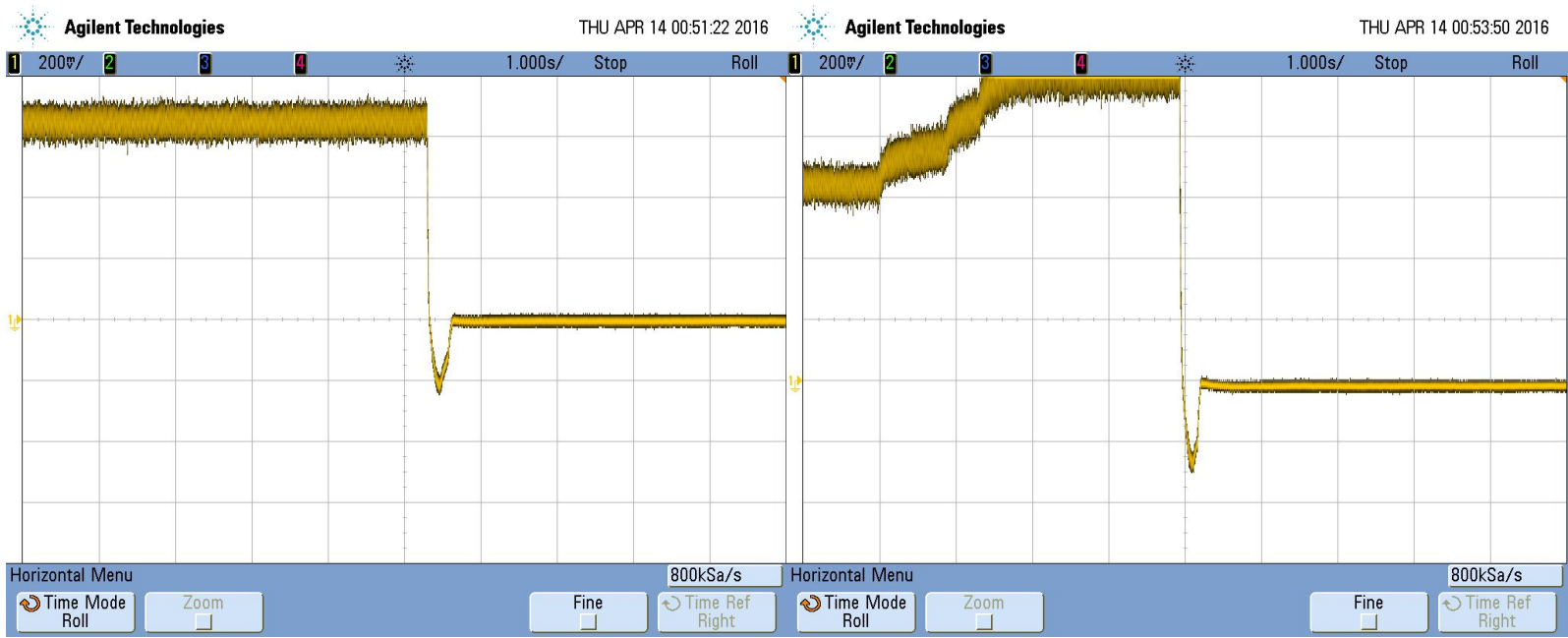
MCM- Dynamic Characterization





MCM- Dynamic Characterization

Regenerative Braking





MCM- Dynamic Characterization

$$w = \frac{768.75i}{TL} - 178.57$$

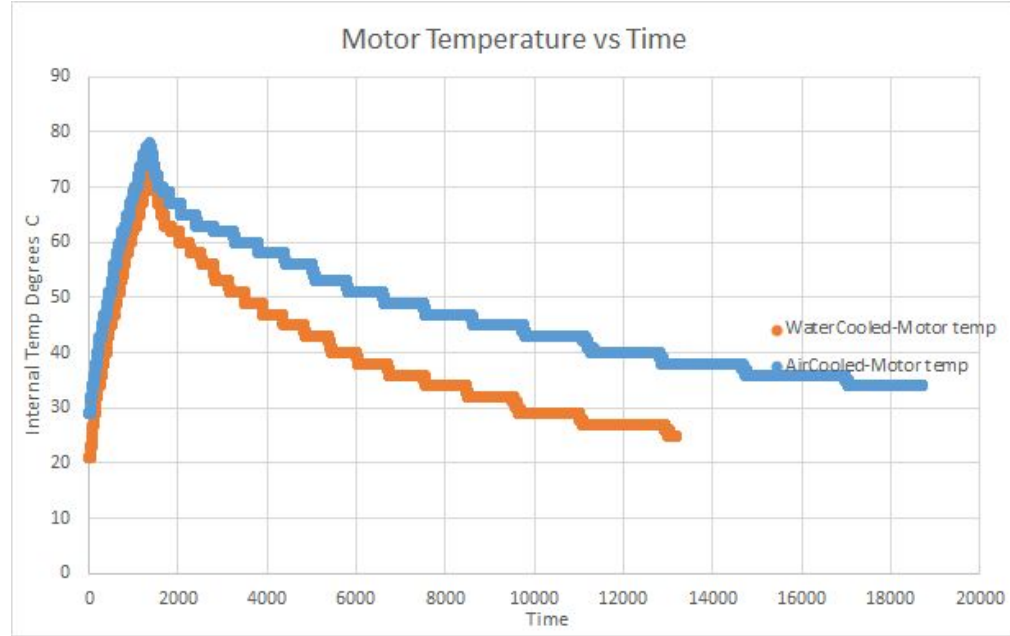
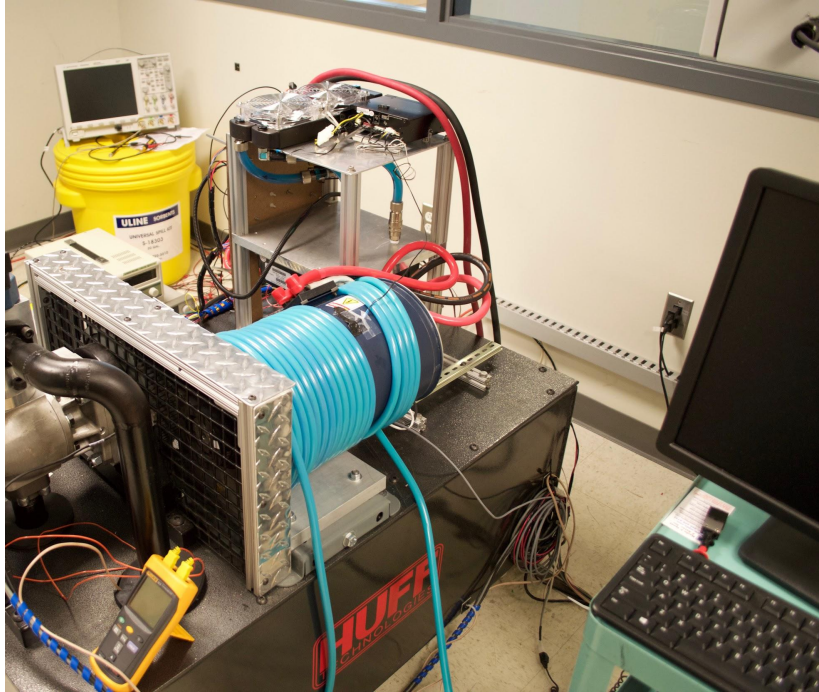


$$J \frac{dw}{dt} = K_T i - f w - T_L$$

- Calculations made using slope from acceleration vs RPM graphs
- Find that J is proportional to steady state torque of motor operation



MCM - Cooling & Efficiency

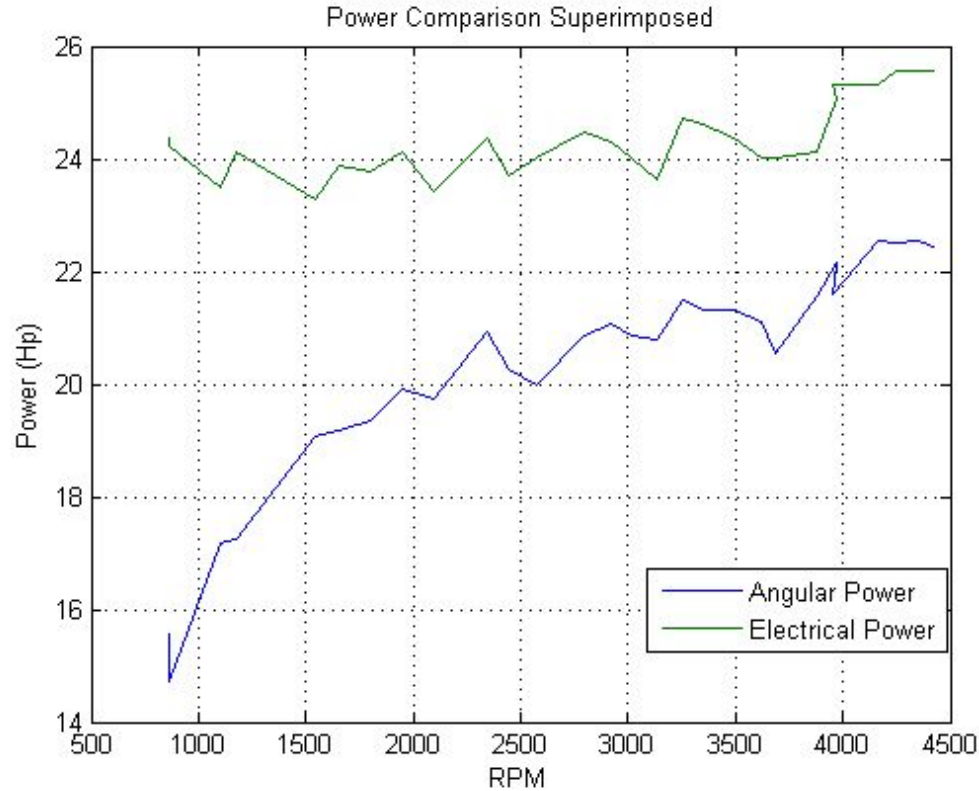


- 70 to 35 degC half life:
 - Air Cooled: 15430 s
 - Water Cooled: 6074 s
- 60.6% improvement in half life, 8% -> 18% duty cycle

MCM - Cooling & Efficiency



Power Loss = 9777 - 8306 = 1471 Watts

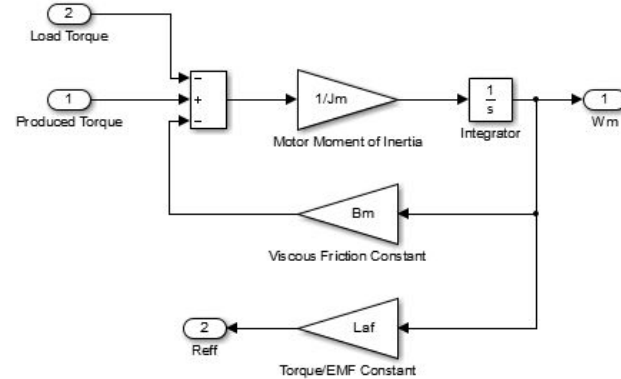
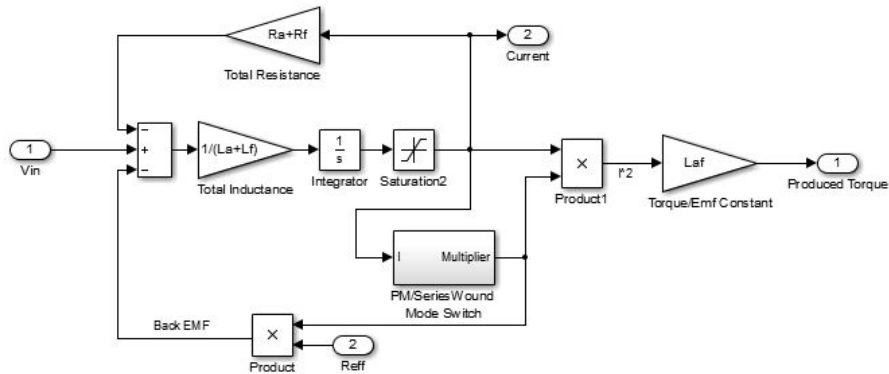
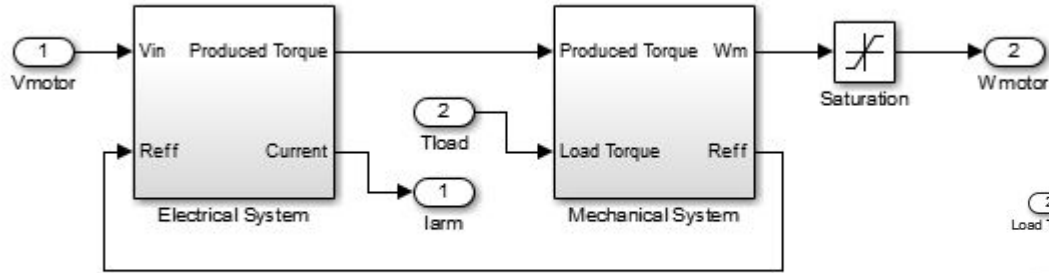


Heat	Watts
Oil	409.8625
Motor	767.7091
Controller	77.43279
Room Air	136.894
Total	1391.903

Heat	Watts
Mtr Cool	105.4501
Ctrlr Cool	103.082
Ht oil	348.689
Ht motor	784.8966
Ht Ctrl	86.54253
Hr Room	4.277938
Total HtPower	1432.938

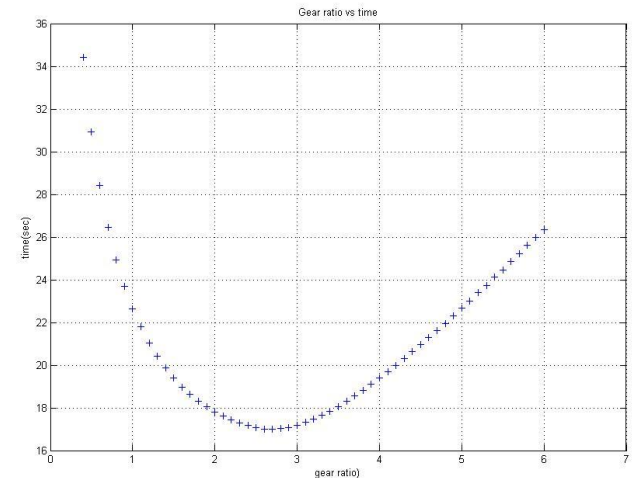
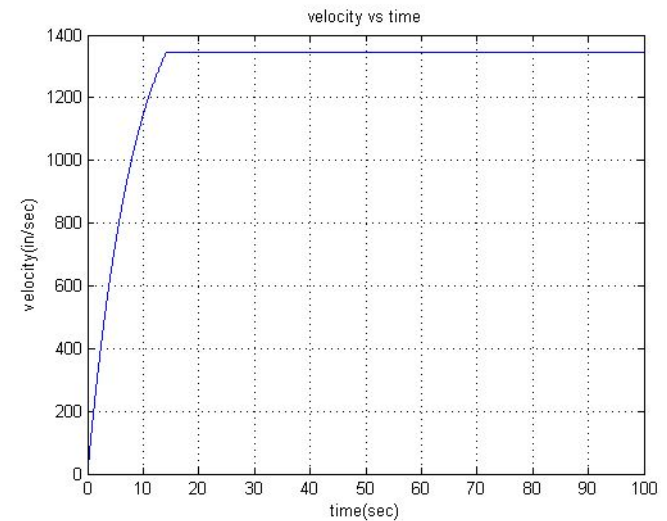


MCM - Modeling



MCM - Results

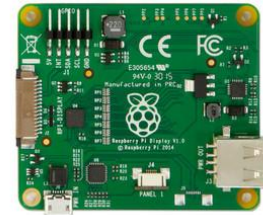
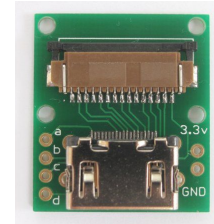
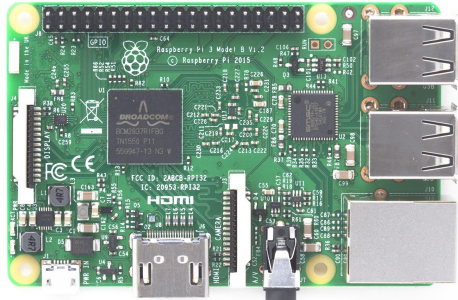
- Full Range of Speeds for the Car:
 - 0-4500 RPM for the motor corresponds with 0-1500 RPM at the wheels. Given 8 inch radius wheels, **max speed for car is about 76 mph**
- Speed for max Efficiency:
 - Determined that motor is electrically efficiency at and above 2500 RPM. At a motor speed of 2500 RPM, **the car is running at about 42 mph.**
- Time to dissipate battery:
 - Running at the efficient speed of 2500 RPM with steady state torque 15 ft-lb gives 71A current draw -> **51 minutes**
- Gear Ratio:
 - for straight line acceleration test **gear ratio determined to be 2.8**
- Max Acceleration:
 - Assuming car weight of 800lbs, **car max acceleration pulling max power is 0.27 Gs over 13 seconds**





VSCADA - Hardware

- Raspberry Pi 3
- CANbus communication via usb2can adaptor
- 7" display screen
 - Connected via hdmi





VSCADA - SCADAd

- Python-3.5 backend
- Does the heavy lifting
 - CAN communications
 - i. Receive data for logging
 - ii. Send data to JGB for controlling motor and dyno
 - Event logging
 - i. Event logs can be parsed by slog_parser and be turned into csv files
- Serves up the front end scada-ui which is react-js
- Designed with extendability in mind. It is straightforward to add subsystems with any knowledge of python
 - Includes useful pre-built components such as plot for making new subsystems



VSCADA - System Topology

```
"physical":  
  "vcan0":  
    "[0x601, 0x602]": "MotorController"  
    "[0x500, 0x0501, 0x0502]": "BatteryPack"  
    "[0x510, 0x0511, 0x0512]": "BatteryPack"  
    "[0x520, 0x0521, 0x0522]": "BatteryPack"  
    "[0x530, 0x0531, 0x0532]": "BatteryPack"  
    "[0x200, 0x201]": "TractiveSystemController"  
    "[0x250, 0x251]": "DynamometerController"  
  
  "fake0": "GPS"  
  
"virtual":  
  - ["Dashboard"]  
  - ["BatteryManager"]
```



VSCADA - Event Logger Raw

```
{ "calibrated": 472.0, "uncalibrated": 4720, "unit": "Volts", "location": ["BatteryPack-0", "pack_voltage"], "type": "measurand", "timestamp": 1462653402.564536 }
{ "calibrated": 4573.39, "uncalibrated": 457339, "unit": "s", "location": ["BatteryPack-0", "uptime"], "type": "measurand", "timestamp": 1462653402.567994 }
{ "calibrated": 14.895, "uncalibrated": 14895, "unit": "Coulombs", "location": ["BatteryPack-0", "total_coulombs"], "type": "measurand", "timestamp": 1462653402.567994 }
{ "calibrated": 0.798, "uncalibrated": 798, "unit": "Volts", "location": ["BatteryPack-0", "cells", 0, "voltage"], "type": "measurand", "timestamp": 1462653402.5692666 }
{ "calibrated": 4407.7, "uncalibrated": 44077, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 0, "temperature"], "type": "measurand", "timestamp": 1462653402.5692666 }
{ "calibrated": 27.274, "uncalibrated": 27274, "unit": "Volts", "location": ["BatteryPack-0", "cells", 1, "voltage"], "type": "measurand", "timestamp": 1462653402.5705724 }
{ "calibrated": 4847.6, "uncalibrated": 48476, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 1, "temperature"], "type": "measurand", "timestamp": 1462653402.5705724 }
{ "calibrated": 4.11, "uncalibrated": 4110, "unit": "Volts", "location": ["BatteryPack-0", "cells", 2, "voltage"], "type": "measurand", "timestamp": 1462653402.571856 }
{ "calibrated": 6078.5, "uncalibrated": 60785, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 2, "temperature"], "type": "measurand", "timestamp": 1462653402.571856 }
{ "calibrated": 6.941, "uncalibrated": 6941, "unit": "Volts", "location": ["BatteryPack-0", "cells", 3, "voltage"], "type": "measurand", "timestamp": 1462653402.5731318 }
{ "calibrated": 3234.5, "uncalibrated": 32345, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 3, "temperature"], "type": "measurand", "timestamp": 1462653402.5731318 }
{ "calibrated": 20.819, "uncalibrated": 20819, "unit": "Volts", "location": ["BatteryPack-0", "cells", 4, "voltage"], "type": "measurand", "timestamp": 1462653402.5746467 }
{ "calibrated": 3240.5, "uncalibrated": 32405, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 4, "temperature"], "type": "measurand", "timestamp": 1462653402.5746467 }
{ "calibrated": 14.102, "uncalibrated": 14102, "unit": "Volts", "location": ["BatteryPack-0", "cells", 5, "voltage"], "type": "measurand", "timestamp": 1462653402.5759284 }
{ "calibrated": 6478.7, "uncalibrated": 64787, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 5, "temperature"], "type": "measurand", "timestamp": 1462653402.5759284 }
{ "calibrated": 54.491, "uncalibrated": 54491, "unit": "Volts", "location": ["BatteryPack-0", "cells", 6, "voltage"], "type": "measurand", "timestamp": 1462653402.5772016 }
{ "calibrated": 1674.8, "uncalibrated": 16748, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 6, "temperature"], "type": "measurand", "timestamp": 1462653402.5772016 }
{ "calibrated": 1458332.385, "uncalibrated": 1458332385, "unit": "Amperes", "location": ["BatteryPack-0", "pack_current"], "type": "measurand", "timestamp": 1462653402.7655206 }
{ "calibrated": 2988.2, "uncalibrated": 29882, "unit": "Volts", "location": ["BatteryPack-0", "pack_voltage"], "type": "measurand", "timestamp": 1462653402.7655206 }
{ "calibrated": 4573.59, "uncalibrated": 457359, "unit": "s", "location": ["BatteryPack-0", "uptime"], "type": "measurand", "timestamp": 1462653402.7689815 }
{ "calibrated": 7.713, "uncalibrated": 7713, "unit": "Coulombs", "location": ["BatteryPack-0", "total_coulombs"], "type": "measurand", "timestamp": 1462653402.7689815 }
{ "calibrated": 23.923, "uncalibrated": 23923, "unit": "Volts", "location": ["BatteryPack-0", "cells", 0, "voltage"], "type": "measurand", "timestamp": 1462653402.7702641 }
{ "calibrated": 2333.7, "uncalibrated": 23337, "unit": "Celcius", "location": ["BatteryPack-0", "cells", 0, "temperature"], "type": "measurand", "timestamp": 1462653402.7702641 }
{ "calibrated": 43.314, "uncalibrated": 43314, "unit": "Volts", "location": ["BatteryPack-0", "cells", 1, "voltage"], "type": "measurand", "timestamp": 1462653402.7715514 }
```



VSCADA - CSV Log after parsing

time	BatteryPack-0.cells-0.status	BatteryPack-0.cells-0.temperature	BatteryPack-0.cells-0.voltage	BatteryPack-0.cells-1.status	BatteryPack-0.cells-1.temperature	BatteryPack-0.cells-1.voltage	BatteryPack-0.cells-2.status	BatteryPack-0.cells-2.temperature
0.1	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.291	n/a	n/a
0.2	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.291	n/a	n/a
0.3	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.6
0.4	NOT BYPASS	21.9	3.294	NOT BYPASS	22.2	3.291	NOT BYPASS	22.6
0.5	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.6
0.6	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.6
0.7	NOT BYPASS	21.9	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.5
0.8	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
0.9	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
1	NOT BYPASS	21.9	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
1.1	NOT BYPASS	21.9	3.3	NOT BYPASS	22.2	3.291	NOT BYPASS	22.6
1.2	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
1.3	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
1.4	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
1.5	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.6
1.6	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.6
1.7	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.291	NOT BYPASS	22.5
1.8	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.5
1.9	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
2	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
2.1	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
2.2	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
2.3	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
2.4	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.6
2.5	NOT BYPASS	22	3.294	NOT BYPASS	22.2	3.297	NOT BYPASS	22.5
2.6	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.5
2.7	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
2.8	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.5
2.9	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.5
3	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
3.1	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
3.2	NOT BYPASS	21.9	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
3.3	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6
3.4	NOT BYPASS	22	3.294	NOT BYPASS	22.3	3.297	NOT BYPASS	22.6



VSCADA - SCADA-ui

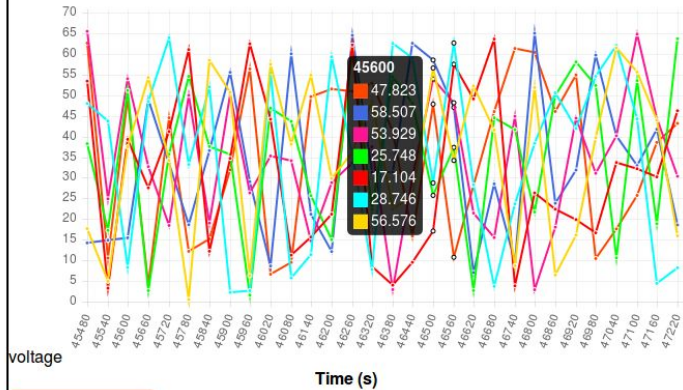
- Serves as the main user interface and is opened up in a web browser
- Replicates system state on client in Javascript
- Renders view of state using React-JS
- Can be accessed by any device on campus network with a web browser
- The dashboard screen auto-navigates to the ui on boot-up
- Designed with extendability in mind. It is straightforward to add subsystem views.
 - Includes useful pre-built components such as plot for making new subsystems displays



- MotorController-U
- TSC-0

total_coulombs	15.448000 Coulombs (15448)
uptime	1:07:33:18.780 (11359878)

BatteryPack-0cell_voltage



Play/Pause Graph

- BatteryPack-0cells0voltage
- BatteryPack-0cells1voltage
- BatteryPack-0cells2voltage
- BatteryPack-0cells3voltage
- BatteryPack-0cells4voltage
- BatteryPack-0cells5voltage
- BatteryPack-0cells6voltage

true Actual: true

ID	Voltage	Temperature	Status
0	58.999000 Volts (58999)	4.475700 K Celcius (44757)	NOT BYPASS Status (0)
1	12.140000 Volts (12140)	1.167900 K Celcius (11679)	NOT BYPASS Status (0)
2	4.173000 Volts (4173)	5.718200 K Celcius (57182)	NOT BYPASS Status (0)
3	53.198000 Volts (53198)	2.474000 K Celcius (24740)	NOT BYPASS Status (0)
4	54.626000 Volts (54626)	3.160300 K Celcius (31603)	NOT BYPASS Status (0)
5	60.223000 Volts (60223)	1.185800 K Celcius (11858)	NOT BYPASS Status (0)
6	34.064000 Volts (34064)	147.600000 Celcius (1476)	NOT BYPASS Status (0)

Tom Anderson & Sons



Soul-Machine

Virtual

- BatteryManager-0
- Dashboard-0
- SafetyManager-0
- TSM-0

Physical

- BatteryPack-0
- BatteryPack-1
- BatteryPack-2
- BatteryPack-3
- DC-0
- GPS-0
- MotorController-0
- TSC-0

TractiveSystemController-0

ONLINE: **TRUE**

Location: (<CAN: can0>, [512, 513])

Timestamp: Sun May 08 2016 22:55:30 GMT-0400 (EDT)

software_throttle

Actual: 127

Input: 127

throttle_enable

Actual: true

throttle_select

Actual: Physical

open_safety_loop

Actual: false

Measurand Name	Value
AIR_voltage_present	true (true)
current	4.882813 mAmperes (64)
drive_button	false (false)
mc_voltage_present	true (true)
physical_throttle	0 (0)
voltage	991.210938 mVolts (12992)



Soul-Machine

Virtual

- BatteryManager-0
- SafetyManager-0
- TSM-0

Physical

- BatteryPack-0
- BatteryPack-1
- BatteryPack-2
- BatteryPack-3
- DC-0
- GPS-0
- MotorController-0
- TSC-0

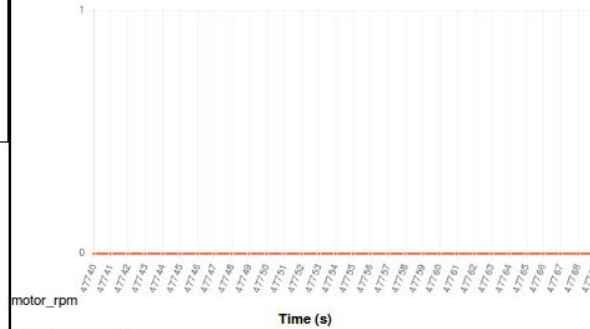
MotorController-0

ONLINE: **FALSE**

Location: (<CAN: vcan0>, [1537, 1538])

Timestamp: Not contacted.

MotorController-0motor_rpm_plot



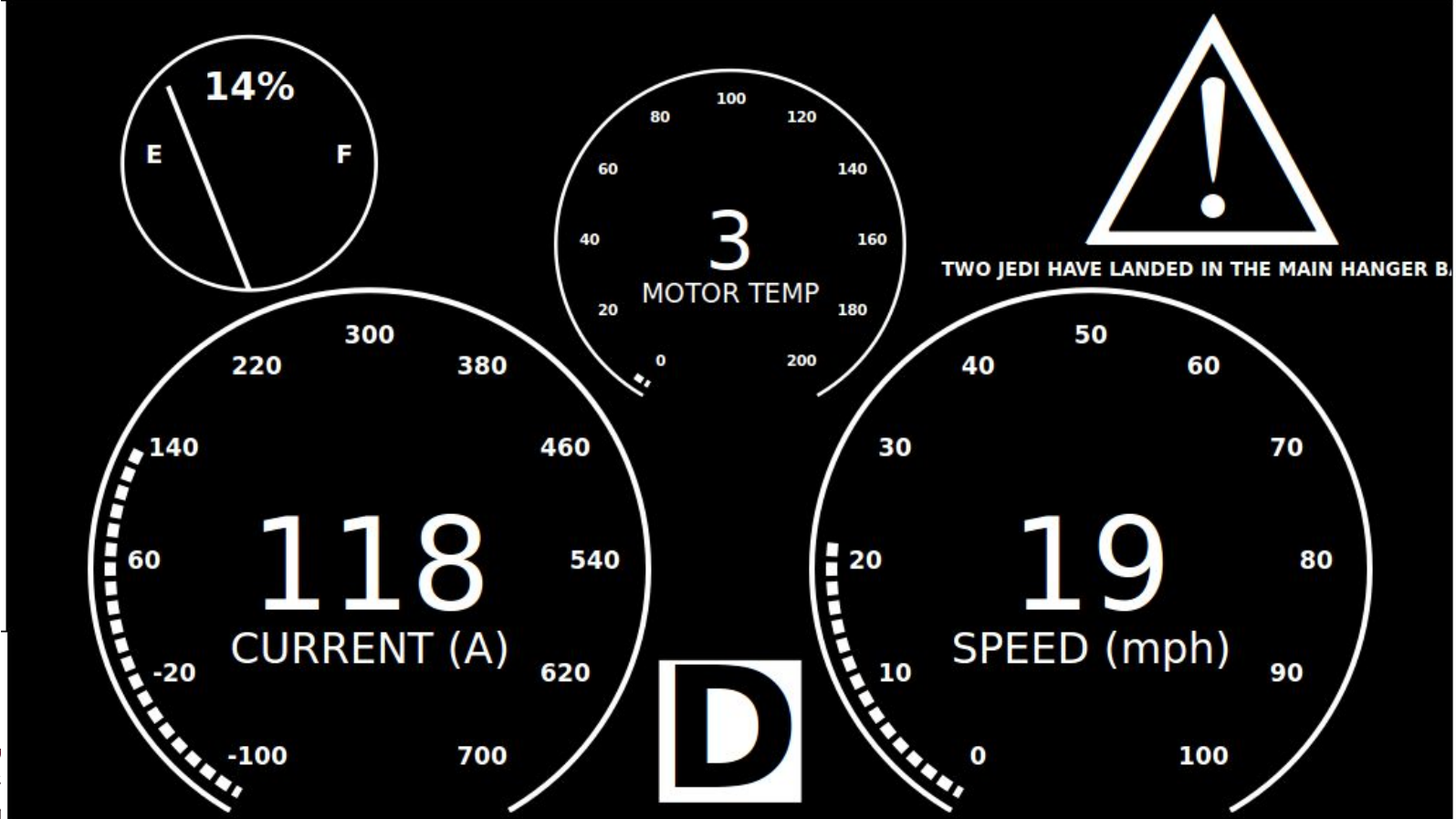
motor_rpm

MotorController-0motor_rpm

Play/Pause Graph
true | Actual: true

Measurand Name	Value
brake_input	no-data % (no-data)
brake_light	no-data Boolean (no-data)
cap_voltage	no-data Volts (no-data)
controller_fault1	no-data Fault (no-data)
controller_fault2	no-data Fault (no-data)
controller_temperature	no-data Celcius (no-data)
econo	no-data Boolean (no-data)
motor_rpm	no-data RPM (no-data)
motor_temperature	no-data Celcius (no-data)
regen	no-data Boolean (no-data)
reverse	no-data Boolean (no-data)
rms_current	no-data Amperes (no-data)
stator_frequency	no-data Hz (no-data)
throttle_input	no-data % (no-data)

Vscada - Dashboard



VSCADA - Safety Manager (Part of SCADA)



- Safety parameters are user defined and very simple to make
 - Chose parameter, set warning threshold, set failure threshold and you're done
- Communicates with Safetyd to keep safety loop closed.



VSCADA - Safetyd

- Serves as an intermediary between the Scada-daemon and the raspberry pi GPIO pins
- Listens for UDP traffic on localhost. Reading 1 bytes messages
- A 0x01 means close the safety loop. If it goes 200ms without receiving this message, the loop opens
- A 0x00 means open the loop immediately.
- If SCADAd goes down, the loop opens after a timeout. If the SafetyManager subsystem detects a fault it signals to open the loop immediately.



VSCADA - Safety-Dict

```
SAFETY_DICT = {  
    'pack_voltage':      {'location': ['BatteryPack-0', 'voltage'],  
                          'warning': '>3.7',  
                          'failure': '>4.0',  
                          'units' : 'Volts'  
                        },  
    'motor_temperature': {'location': ['MotorController-0', 'temperature'],  
                          'failure': '>80',  
                          'units' : 'Celcius'  
                        },  
    'cell_one_voltage':  {'location': ['BatteryPack-0', 'cells', 0, 'voltage'],  
                          'warning': '>50',  
                          'failure': '>65',  
                          'units' : 'Volts'  
                        },  
}
```




Soul-Machine

Virtual

- BatteryManager-0
- SafetyManager-0
- TSM-0

Physical

- BatteryPack-0
- BatteryPack-1
- BatteryPack-2
- BatteryPack-3
- DC-0
- GPS-0
- MotorController-0
- TSC-0

SafetyManager-0

ONLINE: **FALSE**

Location: virtual

Timestamp: Not contacted.

Measurand Name	Value	Warning	Warning Enabled	Failure	Failure Enabled	Reset Failure
cell one voltage	20.023000 Volts (20.023)	>50 false	<input type="checkbox"/> true Actual: true	>65 true	<input type="checkbox"/> true Actual: true	<input type="checkbox"/> false Actual: false
motor temperature	no-data Celcius (no-data)			>80 false	<input type="checkbox"/> true Actual: true	<input type="checkbox"/> false Actual: false
pack voltage	no-data Volts (no-data)	>3.7 false	<input type="checkbox"/> true Actual: true	>4.0 false	<input type="checkbox"/> true Actual: true	<input type="checkbox"/> false Actual: false

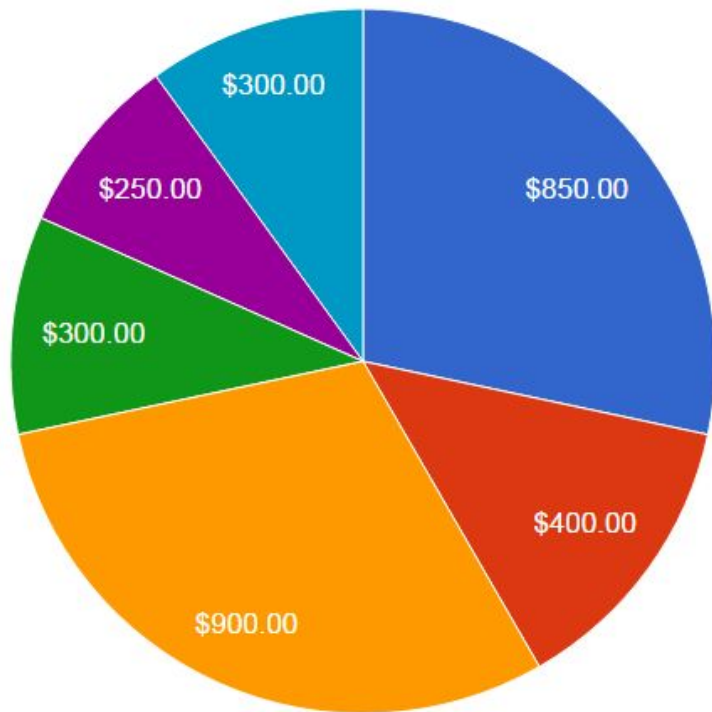


soulmachine.lafayette.edu:1428/index.html

Budget

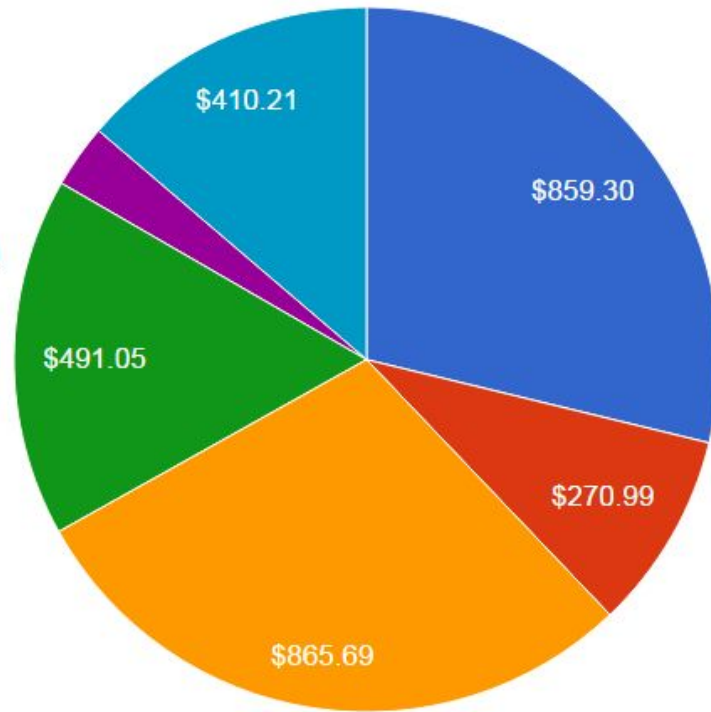


Original Budgeted Amounts



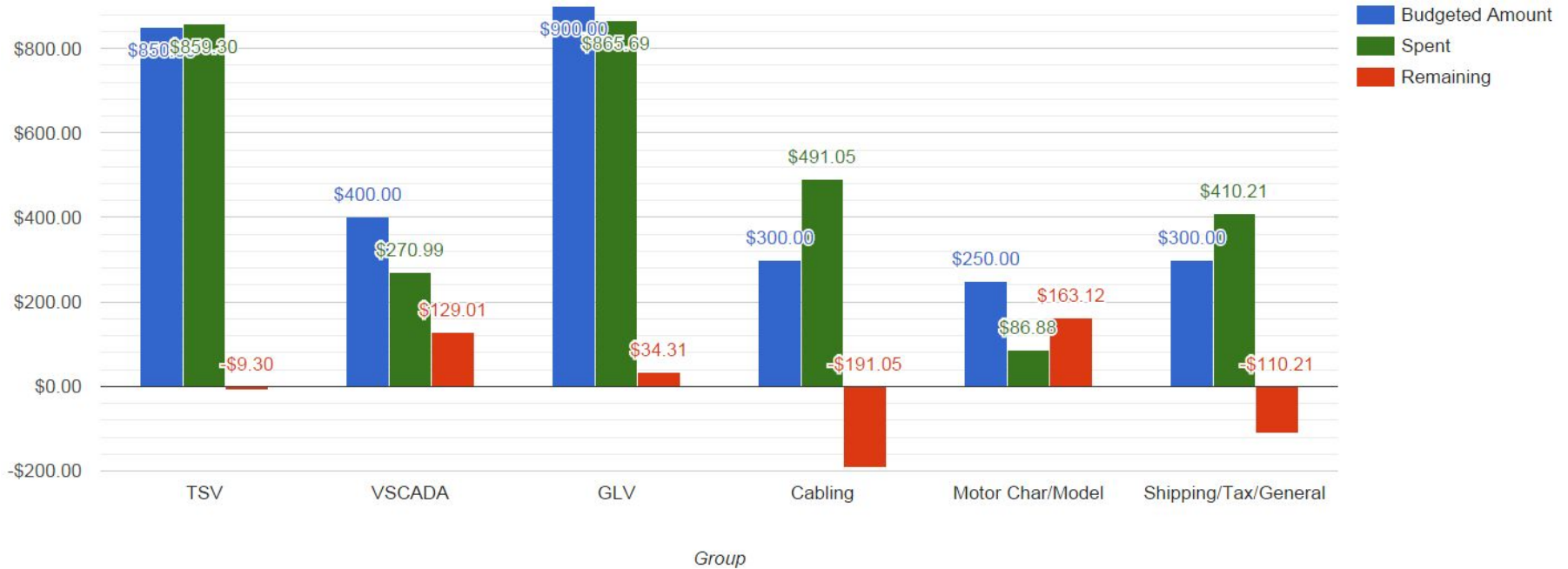
- TSV
- VSCADA
- GLV
- Cabling
- Motor Char/Model
- Shipping/Tax/General

Actual Budget Spending





Budget - Category Breakdowns



Budget - Overall Budgeted v. Spent Comparison





Budget - Weekly Spending



Budget - Table View



Group	TSV	VSCADA	GLV	Cabling	Motor Char/Model	Shipping/Tax/General	Project Total	Extra-Budgetary
Budgeted Amount	\$850.00	\$400.00	\$900.00	\$300.00	\$250.00	\$300.00	\$3,000.00	
Spent	\$859.30	\$270.99	\$865.69	\$491.05	\$86.88	\$410.21	\$2,984.12	\$1,336.47
Remaining	-\$9.30	\$129.01	\$34.31	-\$191.05	\$163.12	-\$110.21	\$15.88	



Questions

