Week	Tentative Course Topics	Programming Assignment	
1	Introduction to Course Intro to MATLAB Numerical Methods for Root Finding	Root-Finding Bisection Method Newton's Method	y solve f(x) =0 find 'roots' f(x) or zeros X
2	Advanced Programming - Variables - Control Statements - Plotting in 2D	Numerical Integration Trapezoidal Rule Simpson's Rule	y solve $I = \int_{a}^{b} f(x) dx$ find area under Curve f(x) k $ha$
3	Input/Output using the screen, files, and dialogs Advanced Graphics MATLAB functions	Manning's Equation	$Q(cfs) = \frac{1.49}{n} R_h^{2/3} S^{1/2} A$
Structures Application – Beam Deflection			
4	Systems of linear equations Arrays and Matrices Advanced Control	Solving Systems of Linear Equations Gaussian Elimination Pivoting	$3x_{1} + 2x_{2} = 3 \Rightarrow 5x_{1} \downarrow P_{1} \downarrow P_{2} [K] {\delta} = {P}$ $4x_{1} - 2x_{2} = 7 \Rightarrow 5x_{1} \downarrow P_{2} [K] {\delta} = {P}$ $(A] {x} = {b} $
5	Nonlinear ODEs Boundary Value Problems Basic GUI Development	Numerical Differentiation Forward/Backward/Central Difference Formulas Solving BVP ODEs using the Finite Difference Method	y + find eff(x;) y + find eff(x;) f(x)
Water Resources Application – Detention Basin Routing			
6	Nonlinear ODEs Initial Value Problems	Solving IVP ODEs Euler Method Runge- Kutta Method Routing Problems	Solve dy = f(t, y) w) y(t=0)= y. y yo yo y yo y y y y y y y y y y y y y
7	Detention Basin Routing Advanced GUI Callbacks	Beam Deflection Problems Routing Problems	$Q_{in}(t)$ $= 3$ $Q_{out}(t)$ $A(h) \frac{dh}{dt} = Q_{in}(t) - C_{uv}L_{uv}(h(t) - h_0)^{3/2}$