Acceptance Test Report ECE 492 – Spring 2014

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Abstract

The Acceptance Test Report (ATR) contains the summary of results obtained from executing the Acceptance Test Plan to verify the system meets all necessary requirements to satisfaction. For requirements being proven through analysis, required memos and additional documents are included in the ATR. For requirements being proven by inspection, a collection of numbered and annotated photographs is included to conclusively demonstrate the meeting of each requirement. Results of all tests run during ATP are also included to prove those requirements being met through testing.

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Deliverables

The following items are expected to be delivered as part of successful completion of this project.

Item	Description and URL (if applicable)	P/F	Date
D000	PDR Materials	Р	5/8/14
D001	CDR Materials	Р	5/8/14
D002	User's Manual	Р	5/14/14
D003	Final Report and Maintenance Manual	Р	5/14/14
D004	Acceptance Test Plan	Р	5/8/14
D005	Acceptance Test Report	Р	5/14/14
D006	QA Audit Report	F	5/13/14
D007	Project Website	Р	5/14/14
D008	LFEV-Y2-2014 Integrated System	Р	5/14/14
D009	Conference Paper, Presentation, and Video	Р	5/8/14
D010	Project Poster	Pending	
D011	Calibration and Accuracy Analysis	Р	5/14/14
D012	Software Maintainability Plan	F	5/14/14
D013	Request for Non-Budget Funding		
	Additional Documents		
D014	EMI/EMC Analysis Memo	F	5/14/14
D015	Hazmat Analysis Memo	Р	5/14/14
D016	LFEV-Y2-2014 Safety Plan	Р	5/14/14
D017	Reliability Report	Р	5/13/14
D018	Maintainability Report	Р	5/13/14
D019	System Bill of Materials	F	5/13/14
D020	LFEV-Y1-2013 Subsystem Compliance Memo	Р	5/13/14
D021	Accumulator Container FEV Compliance Memo	F	5/13/14
D022	GLV/HV Isolation FEV Compliance Memo	Р	5/13/14
D023	TSV/AIR FEV Compliance Memo	P(75%)	5/13/14
D024	Fusing FEV Compliance Memo	Р	5/13/14

Analysis Requirements

The table below lists the analysis documents that will be delivered with the ATR as well as the criteria that each document must present in order to be considered complete. Documents listed below are available on the project website.

Document	Description	P/F
D011	Measurement Calibration and Accuracy Memo	
	Measurand Calibration and Accuracy - The AMS design must be	Р
R004-5	analyzed by a Calibration and Error Analysis document (D011)	
	that states the uncertainties associated with all AMS measurands	
D012	Software Maintainability Plan	
R002-6	Software written shall be maintainable as specified in GPR007	F
D014	EMI/EMC Analysis Memo	
GPR003	All designs being considered for production will undergo research to determine if any components or the completed system will breach the EMI/EMC limit as specified in US CFR Title 47 Part 15 subpart B regulations for Class A digital equipment. If infractions are found, an alternative design in compliance with this requirement will be proposed before proceeding with production	F
D015	Hazmat Analysis Memo	
GPR004	System designs will be analyzed for the inclusion of hazardous material before production or procurement of the hazardous substances being used. If a design includes a hazardous material and no alternative design solution is feasible, the Safety officer will update the team's safety plan and system User Manual to include specific instructions for handling these materials both in the lab and in the integrated system.	Р
D016	LFEV-Y2-2014 Safety Plan	
GPR005	Safety and Good Practice	Р
D017	Reliability Report	
GPR006	Reliability - During subsystem design, all components involved will undergo testing and/or research to determine an accurate MTBF and therefore obtain an overall MTBF for the whole system. This report will be included on the website and in the set of deliverables for CDR and final system submission.	Р
D018	Maintainability Report	
GPR006	Maintainability - Subsystem designs will be completed with the maintainability procedures in mind. A full maintenance manual for the system and MTTR reports will be submitted with the fully integrated system and to the website for reference purposes.	Р
R001-6	A backup system or recovery strategy must be developed to all the VSCADA system to be promptly repaired after a hardware failure in less time than the MTTR given in GPR007	Р
D019	System Bill of Materials	
GPR008	Manufacturability - A BOM will be provided for each subsystem at	F

	CDR. Analysis of parts on the BOM will ensure they meet	
	tolerance standards as outlined and are available from at least two	
	manufacturers.	
D020	LFEV-Y1-2013 Subsystem Compliance Memo	
2020	Parts of the 2013 project that do adequately meet LFEV	Р
R003-1	requirements may not be discarded and replaced with new parts	1
1005 1	that do not meet those requirements	
D021	Accumulator Container FEV Compliance Memo	
D021	Cooling - The AMS requires a simple, small, manufacturable heat	Р
	sink cooling system for the bypass switch. Performance of cooling	P
R004-6	system shall be proved by computer modeling and empirical	
	measurements	
		D
	All batteries or capacitors that make up the accumulator must be divided into accumulator	Р
	divided into accumulator segments. Maintenance plugs, additional	
	contactors or similar measures must be taken to allow electrical	
	separation of the internal accumulator segments such that the	
EV 3.3.3	separated segments contain a maximum voltage of less than 120	
	VDC fully charged and a maximum energy as specified in Table.	
	This separation method must be used whenever the accumulator	
	containers are opened for maintenance and whenever accumulator	
	segments are removed from the container. Maintenance separation	
	requiring tools to isolate the segments will not be accepted.	D
EV 3.4.3	All accumulator containers must lie within the surface envelope as	Р
	defined by IC1.5.1	D
EV 3.5.5	The fuse protecting the accumulator circuit must have a rating	Р
EV 3.6.3	10wer than the voltage and current ratings of the isolation relays.	
EV 3.0.3	The AMS must continuously measure the temperatures of critical points of the accumulator to keep the cells below the allowed	Р
	maximum cell temperature bound stated in the cell data sheet.	
	Team-Designed Accumulator Management Systems: Teams may	Р
	design and build their own Accumulator Management Systems.	P
	However, microprocessor-based accumulator management systems.	
	are subject to the following restrictions: (a) The processor must be	
	dedicated to the AMS function only. However it may communicate	
	with other systems through shared peripherals or other physical	
	links. (b) The AMS circuit board must include a watchdog time	
	(Maxim MAX6373 or similar) which is physically separate from	
	the CPI. (c) The external watchdog time must be hardwired to the	
	AIRs through an electro-mechanical relay such that a watchdog	
EV 3.6.8	timeout or lost of power to the circuit board will result in the AIRs	
	opening (d) The watchdog "tickle" input must be driven high and	
	low in separate routines (i.e. no "compliment port pin" code) At	
	least one watchdog input transition must be driven inside a	
	foreground routine, i.e. both transitions may not be contained in	
	timer or externally-triggered interrupt routines. (e) The code that	
	drives the watchdog input may not be located such that a	
	malfunction resulting in continuous internal watchdog timeouts	
	could prevent the external watchdog timer from timing out. (f) The	
	external watchdog time must be demonstrable.	
D022		
D022	GLV/HV Isolation FEV Compliance Memo	

	Any GLV connection to the AMS must be galvanically isolated	Р
EV 3.6.5	from the TSV, including any connections to external devices such	
	as laptops. This isolation must be documented in the ESF.	
	Traction system and GLV circuits must be physically segregated.	Р
EV 4.1.3	I.e. they may not run through the same conduit or connector, except	
	for interlock circuit connections.	
	GLV circuits must not be present in the accumulator container	Р
EV 4.1.4 except for required purposes, for example the AMS and AIR. This		
	must be demonstrated in the ESF submission.	
	Where both tractive system circuits and GLV circuits are present	Р
	within an enclosure, they must be (a) separated by electrical	
	insulating barriers rated for 150 C or higher (e.g. Nomex based	
EV 4.1.5	electrical insulation), or (b) separated by the spacings shown in	
	Table 13 through air, or over a surface (similar to those defined in	
	UL1741):	
	All electrical insulating material must be appropriate for the	Р
EV 4.5.5	application in which it is used.	1
D023	TSV/AIR FEV Compliance Memo	
D025	Resistance - An effort shall be made to lower the series resistance	Р
R006-2	of the pack. The resistive connections in the 2013 design should be	r
K000-2	eliminated.	
	The accumulator voltage indicator (see EV3.3.6) must be directly	F
	controlled by voltage being present at the connectors using hard-	Г
EV 3.3.7	wired electronics. (No software control is permitted). Activating	
LV 3.3.7		
	the indicator with the control signal which closes the Accumulator	
EV 2 2 0	Isolation Relays (AIRs) is not sufficient.The accumulator voltage indicator must always work, e.g. even if	
EV 3.3.8	EV 3.3.8 The accumulator voltage indicator must always work, e.g. even if the container is removed from the car.	
		D
	All tractive system connections must be designed so that they use	Р
EV A = 11	intentional current paths through conductors such as copper or	
EV 4.5.11	aluminum and should not rely on steel bolts to be the primary	
	conductor. The connections must not include compressible material	
	such as plastic in the stack-up.	XX 7 • 1
	It is allowed to pre-charge the intermediate circuit for a	Waived
EV 4.9.2	conservatively calculated time before closing the second AIR. A	
	feedback via measuring the current intermediate circuit voltage is	
	not required.	D
EV 5.1.1	The shutdown circuit must directly carry the current driving the	Р
	accumulator isolation relays (AIRs).	
D024	Fusing FEV Compliance Memo	
	All voltage sense wires to the AMS must be either protected by	F
	fuses as defined in ARTICLE EV6 or must be protected by	
	resistors so that they cannot exceed their current carrying capacity	
	in the event of a short circuit. Any fuse or resistor must be located	
EV 3.6.4	as close as possible to the energy source. If any of these fuses are	
L, J.U.T	blown or if the connection to measure the cell voltage is interrupted	
	in any other way then this must be detected by the AMS and must	
	be reported as a critical voltage problem. If the AMS monitoring	
	board is directly connected to the cell, it is acceptable to have a	
	fuse integrated into the monitoring board.	

EV 6.1.1	All electrical systems (both tractive system and grounded low voltage system) must be appropriately fused.	Р
EV 6.1.2	The continuous current rating of a fuse must not be greater than the continuous current rating of any electrical component, for example wire, busbar, battery cell or other conductor that it protects.	Р
EV 6.1.3	All fuses and fuse holders must be rated for the highest voltage in the systems they protect. Fuses used for DC must be rated for DC, and must carry a DC rating equal to or greater than the system voltage of the system in which they are used.	
EV 6.1.4	All fuses must have an interrupt current rating which is higher than the theoretical short circuit current of the system that it protects.	Р

Inspection Guide

This guide lists all the system requirements that will be met by inspection.

Requirement	Description	P/F	Date
R000	Formula Hybrid Competition Rules		
R000	The Formula Hybrid Competition rule sections relating to electrical and power subsystems of the completed car will be analyzed to determine what rules are applicable to the scope of the proposed design. All rules determined to be within the proposed scope will become constraints and requirements within the design of the integrated system in order to produce a competition ready and compliant product at the completion of the project	Р	5/13/14
R001	VSCADA		
R001-8	All VSCADA application software must be written in conformance with a documented API using a delivered SDK	Р	5/13/14
R002	VSCADA API, SDK, and Applications		
R002-1	Scope of the API must be sufficient to support both low level debugging applications and high-level automated applications on all hardware platforms in use. Same API must be used for all applications running on or off-car	80%	5/13/14
R002-2	SDK must include a complete tool chain with compilers, linkers, libraries, include files, utilities, and developer level documentation. All tools shall be actively supported and mature	Р	5/13/14
R002-3	All sources must be maintained under configuration control	Р	5/13/14
R002-4	The complete SDK, including API and application source under configuration control shall be delievered to or linked by the project website	Р	5/13/14
R002-5	API, SDK, and applications shall be copyrighted using open source practices. The team shall identify and GPL all software written by the team	Р	5/13/14
R003	Use of the 2013 Design		
R003-2	The pack design must not be altered significantly, except for AMS improvement required by R004	Р	5/13/14
R005	MCS and Test Stand Requirements		
R005-1	Motor and Controller system shall be provided to meet the requirements of the IEEE FEV competition and should be sized suitably to achieve a reasonably competitive entry	Waived	5/9/14
R005-2	An MCS test stand shall be provided to permit the safe testing and demonstration of motor and controller performance over the operation parameters(RPM and torque profiles) implied by the IEEE FEV competition	Waived	5/9/14
R005-3	The MCS test stand shall be instrumented with sensors that are interfaced to the VSCADA, reporting relevant performance parameters measured at the Test Stand	Waived	5/9/14
R006	Battery Pack Requirements		

R006-1	Voltage - The system design requires a 7-cell pack, with nominal voltage of 24 VDC. The 3-cell pack design from 2013 should be extended to 7 cells	Р	5/13/14
R006-3	Charger Interface - The charging interface shall be reliable, maintainable, and contain safety features that meet requirements. This includes an improved fusing of the charger path from the 2013 design	Р	5/13/14
GPR	General Project Requirements		
GPR001	Documentation - Block Diagrams and schematics for all subsystems being designed will be completed using computer aided drawing programs and will be posted upon completion. Two members of the team have been designated as "Editors" and will review submitted technical memos, manuals, and drawings for accuracy, professionalism, and formatting.	Р	5/13/14
GPR005	Safety and Good Practice	F - No Proof Given	5/13/14
GPR011	Project Demonstration - Upon complete system integration, QA, and fulfillment of the Acceptance Test Plan, a live demonstration will be presented to the ECE faculty and students. The completed battery pack and related systems will be self contained and able to operate for at least 50 days without the need of being charged, thus becoming a maintenance free display for ECE visitors.	Р	5/14/14
GPR012	Final disposal of project will take place the week of May 5th. System should be completed and demonstrated by this date, so final disposal is the final step to completion of the project. If adequate room is available, the battery pack can be displayed in the ECE hallway for visitors. Charger, MCS and test stand, and left over materials will be stored in AEC 402 or 400 in an orderly and inventoried fashion. All trash or disorder in AEC 400 which was a result of this project will be disposed over.	Р	5/14/14
EV 1.2	Grounded Low Voltage and Tractive System Voltage		
EV 1.3.1	All Electrical insulating materials used must: (a) Be UL recognized (i.e, have an Underwriters Laboratories (www.UL.com) or equivalent rating and certification). (b) be rated for the maximum expected operating temperatures at the location of use or (c) have a minimum temperature rating of 90C. (Whichever is greater)	Р	5/13/14
EV 1.3.2	Vinyl electrical insulating tape and rubber-like paints and coatings are not acceptable electrical insulating materials.	Р	5/13/14
EV 3.1	Allowed Tractive Systems		
EV 3.1.1	The following accumulators are acceptable; batteries (e.g. lithium- ion batteries, NiMH batteries, lead acid batteries and many other rechargeable battery chemistries) and capacitors, such as super caps or ultra caps. The following accumulators are not permitted; molten salt batteries, thermal batteries, fuel cell, atomic and flywheel mechanical batteries.	Р	5/13/14
EV 3.2	Tractive System Accumulator Container – General Requirements		
EV 3.2.1	All batteries or capacitors which store the tractive system energy must be enclosed in (an) accumulator containers	Р	5/13/14

EV 3.2.3	If the accumulator container(s) is not easily accessible during	Р	5/13/14
	Electrical Tech Inspection, detailed pictures of the internals taken		
	during assembly must be provided. If the pictures do not		
	adequately depict the accumulator, it may be necessary to		
	disassemble the accumulator to pass Electrical Tech Inspection.		
EV 3.3	Tractive System Accumulator Container		
	If the container is made of electrically conductive material, the	F	5/13/14
	poles of the accumulator stack(s) and/or cells must be electrically		
	insulated from the inside wall of the accumulator container by		
	insulating material rated for the maximum voltage of the tractive		
EV 3.3.1	system. All conductive surfaces on the outside of the container		
	must have a low-resistance connection to the GLV system ground.		
	All conductive penetrations (mounting hardware, etc.) must be located outside of the insulation and configured such that there is		
	no possibility that they could penetrate the insulating barrier.		
EV 3.3.2	Every accumulator container must contain at least one fuse	Р	5/13/14
	Contacting / interconnecting the single cells by soldering in the	P	5/13/14
EV 3.3.5	high current path is prohibited.	1	5/15/14
	Each accumulator container must have a prominent indicator, such	F	5/13/14
	as an LED, that will illuminate whenever a voltage greater than 30	1	5/15/11
EV 3.3.6	VDC is present at the vehicle side of the AIRs. Alternatively, an		
	analog voltmeter may be used.		
EV 3.4	Tractive System Accumulator Container – Mechanical		
EV 3.4	Configuration		
	Holes in the container are only allowed for the wiring-harness,	Р	5/13/14
EV 3.4.8	ventilation, cooling or fasteners. These holes must be sealed		
	according to EV4.5.		
	A sticker with an area of at least 750mm ² and a red or black	Р	5/13/14
EV.2.4.10	lightning bolt on yellow background or red lightning bolt on white		
EV 3.4.10	background must be applied on every accumulator container. The		
	sticker must also contain the text "High Voltage" or something		
EV 2 5	similar if the accumulator voltage is greater than 30 VDC.		
EV 3.5	Accumulator Isolation Relay(s) (AIR)	D	5/10/14
EV 3.5.1	At least two isolation relays must be installed in every accumulator container.	Р	5/13/14
EV 3.5.4		Р	5/13/14
	The isolation relays must be of a "normally open" type.		
EV 3.5.6	Accumulator isolation relays containing mercury are not permitted.	Р	5/13/14
EV 3.6	Accumulator Management System (AMS)	D	5/10/14
$EV 2 \in 1$	Each accumulator must be monitored by an accumulator	Р	5/13/14
EV 3.6.1	management system whenever the tractive system is active or the		
	accumulator is connected to a charger. The AMS must monitor the temperature of the minimum number	Р	5/13/14
	of cells in the accumulator as specified in Table 12 below. The	r	3/13/14
EV 3.6.6	monitored cells must be equally distributed over the accumulator		
	container(s).		
	Team-Designed Accumulator Management Systems: Teams may	Р	5/13/14
	design and build their own Accumulator Management Systems.	_	
EV 3.6.8	However, microprocessor-based accumulator management systems		
	are subject to the following restrictions: (a) The processor must be		
	dedicated to the AMS function only. However it may communicate		

	with other systems through shared peripherals or other physical		
	links. (b) The AMS circuit board must include a watchdog time (Maxim MAX6373 or similar) which is physically separate from		
	the CPI. (c) The external watchdog time must be hardwired to the		
	AIRs through an electro-mechanical relay such that a watchdog		
	timeout or lost of power to the circuit board will result in the AIRs		
	opening (d) The watchdog "tickle" input must be driven high and		
	low in separate routines (i.e. no "compliment port pin" code) At		
	least one watchdog input transition must be driven inside a		
	foreground routine, i.e. both transitions may not be contained in		
	timer or externally-triggered interrupt routines. (e) The code that		
	drives the watchdog input may not be located such that a		
	malfunction resulting in continuous internal watchdog timeouts		
	could prevent the external watchdog timer from timing out. (f) The		
	external watchdog time must be demonstrable.		
EV 4.1	Separation of Traction System and Grounded Low Voltage System		
	Spacing must be clearly defined. Components and cables capable	F	5/13/14
EV 4.1.6	of movement must be positively restrained to maintain spacing.	-	5/15/11
	If tractive system circuits and GLV circuits are on the same circuit	Р	5/13/14
	board they must be on separate, clearly defined areas of the board.	-	0,10,11
EV 4.1.7	Furthermore, the tractive system and GLV areas must be clearly		
	marked on the PCB.		
EV 4.2	Positioning of Tractive System Parts		
511 (2 7	There must be a layer of an electrically insulating material between	F	5/13/14
EV 4.2.5	any tractive terminal or connection and the firewall or frame if they		
	are within 50 mm (2 inches) of one another.		-
EV 4.5	TSV Insulation, Wiring, and Conduit		
	All parts especially live wires, contacts, etc. of the tractive system	Р	5/13/14
	need to be isolated by non- conductive material or covers to be		
EV 4.5.1	protected from being touched. In order to achieve this, it must not be possible to touch any tractive system connections with a 10 cm		
	long, 0.6 cm diameter insulated test probe when the tractive system		
	long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place.	D	5/12/14
	long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place. Non-conductive covers must prevent inadvertent human contact	Р	5/13/14
	long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place. Non-conductive covers must prevent inadvertent human contact with any tractive system circuit. This must include crew members	Р	5/13/14
EV 4.5.2	long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place.Non-conductive covers must prevent inadvertent human contact with any tractive system circuit. This must include crew members working on or inside the vehicle. Covers must be secure and	Р	5/13/14
EV 4.5.2	long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place.Non-conductive covers must prevent inadvertent human contact with any tractive system circuit. This must include crew members working on or inside the vehicle. Covers must be secure and adequately rigid. Body panels that must be removed to access	Р	5/13/14
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	 long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place. Non-conductive covers must prevent inadvertent human contact with any tractive system circuit. This must include crew members working on or inside the vehicle. Covers must be secure and adequately rigid. Body panels that must be removed to access other components, etc. are not a substitute for enclosing tractive system connections. All wires and terminals and other conductors used in the tractive system must be sized appropriately for the continuous rating of the fuse which protects them. Wires must be marked with wire gauge, temperature rating and insulation voltage rating. Alternatively a manufacturers part number printed on the wire is sufficient if this 		
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	vibration etc. Conductors and terminals cannot be modified from their original size/shape and must be appropriate for the connection being made.		
EV 4.5.13	If external, un-insulated heat sinks are used, they must be properly grounded to the GLV system ground	Р	5/13/14
EV 4.6	Tractive System Enclosures		
EV 4.6.1	Every housing or enclosure containing parts of the tractive system except motor housings must be labeled with (a) reasonably sized sticker(s) with a red or black lightning bolt on yellow background or red lightning bolt on white background. The sticker must also contain the text "High Voltage" or something similar if the voltage is more than 30 VDC or 25 VAC.	Р	5/13/14
EV 4.7	High Voltage Disconnect(HVD)		
EV 4.7.4	The Disconnect must be clearly marked with "HVD".	Р	5/13/14
EV 4.7.6	If no tools are needed to open the HVD, an interlock must open up the shutdown circuit when the HVD is removed.	Р	5/13/14
EV 5.1	Shutdown Circuit		
EV 5.1.2	The shutdown circuit consists of at least 2 master switches, 3 shut- down buttons, the brake-over- travel-switch, the insulation monitoring device (IMD), all required interlocks and the accumulator management system (AMS).	Р	5/13/14
EV 8.2	Charging		
EV 8.2.5	Only chargers presented and sealed at Electrical Tech Inspection are allowed. All connections of the charger(s) must be isolated and covered. No open connections are allowed.	Р	5/13/14
EV 8.2.10	High Voltage wiring in an off board charger does not require conduit; however it must be a UL listed flexible cable that complies with NEC Article 400; double insulated.	Р	5/13/14
EV 8.2.11	All chargers must be UL (Underwriters Laboratories) listed. Any waivers of this requirement require approval in advance, based on documentation of the safe design and construction of the system, including galvanic isolation between the input and output of the charger. Waivers for chargers must be submitted at least 30 days prior to the start of the competition.	P	5/13/14

Inspection Photos

This section includes the photographs taken to prove compliance with inspection related requirements that required verification with pictures. Each photo will be annotated as necessary to prove compliance of the heading requirement.

R000

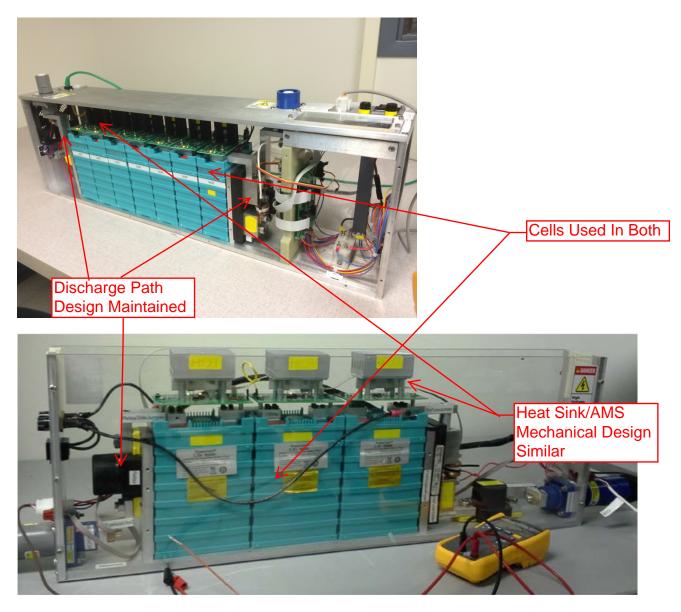
The Formula Hybrid Competition rule sections relating to electrical and power subsystems of the completed car will be analyzed to determine what rules are applicable to the scope of the proposed design. All rules determined to be within the proposed scope will become constraints and requirements within the design of the integrated system in order to produce a competition ready and compliant product at the completion of the project

EV 1.2	the ECE nam left over mat and inventor was a result Grounded	T000			
EV 1.2.4	The tractive				
EV 1.2.6	The tractive system motor(s) must be connected to the accumulator through a motor controller. Bypassing the control system and connecting the tractive system accumulator directly to the motor(s) is prohibited.			Ι	
		This is a short section from the ATP traceability matrix showing EV requirements which			Γ
		relate to our system			
		gathered from analysis of the Formula Hybrid Rules	ACCEPTAN	CE TEST PLAN	32

EV 1.3.1	All Electrical insulating materials used must: (a) Be UL	I
	recognized (i.e. have an Underwriters Laboratories	
	(www.UL.com) or equivalent rating and certification). (b) be	
	rated for the maximum expected operating temperatures at the	

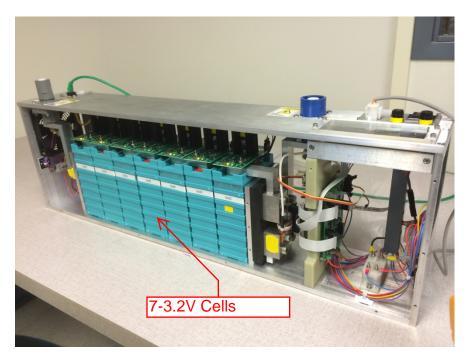
R003-2

The pack design must not be altered significantly, except for AMS improvement required by R004.



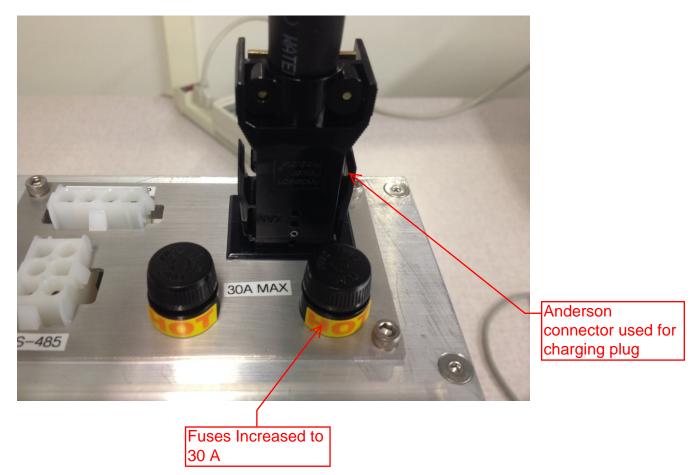
R006-1

Voltage - The system design requires a 7-cell pack, with nominal voltage of 24 VDC. The 3-cell pack design from 2013 should be extended to 7 cells



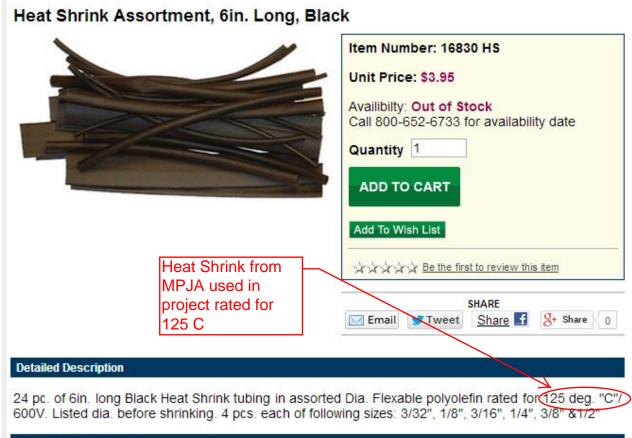
R006-3

Charger Interface - The charging interface shall be reliable, maintainable, and contain safety features that meet requirements. This includes an improved fusing of the charger path from the 2013 design



EV 1.3.1

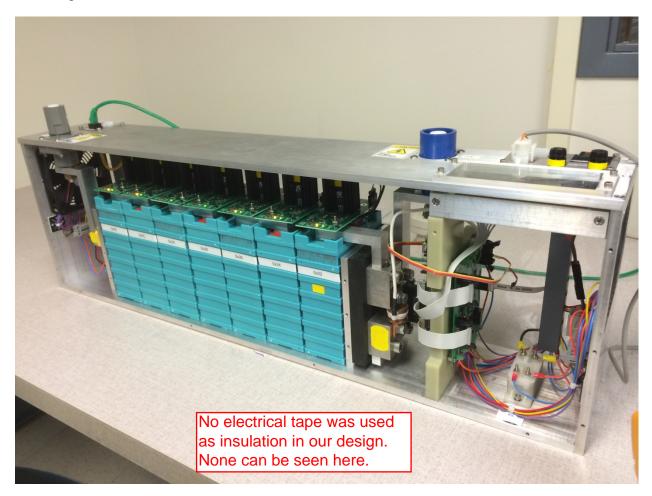
All Electrical insulating materials used must: (a) Be UL recognized (i.e, have an Underwriters Laboratories (www.UL.com) or equivalent rating and certification). (b) be rated for the maximum expected operating temperatures at the location of use or (c) have a minimum temperature rating of 90C. (Whichever is greater)



Recently Viewed Items

EV 1.3.2

Vinyl electrical insulating tape and rubber-like paints and coatings are not acceptable electrical insulating materials.



EV 3.1.1

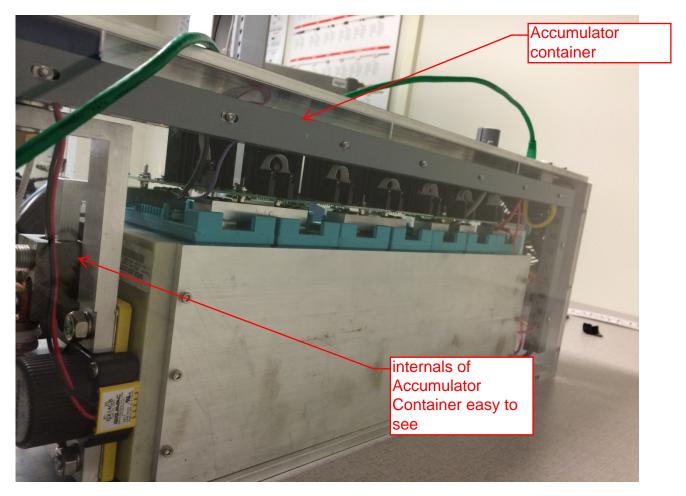
The following accumulators are acceptable; batteries (e.g. lithium-ion batteries, NiMH batteries, lead acid batteries and many other rechargeable battery chemistries) and capacitors, such as super caps or ultra caps. The following accumulators are not permitted; molten salt batteries, thermal batteries, fuel cell, atomic and flywheel mechanical batteries.



EV 3.2.1 and EV 3.2.3

3.2.1 - All batteries or capacitors which store the tractive system energy must be enclosed in (an) accumulator containers

3.2.3 - If the accumulator container(s) is not easily accessible during Electrical Tech Inspection, detailed pictures of the internals taken during assembly must be provided. If the pictures do not adequately depict the accumulator, it may be necessary to disassemble the accumulator to pass Electrical Tech Inspection.

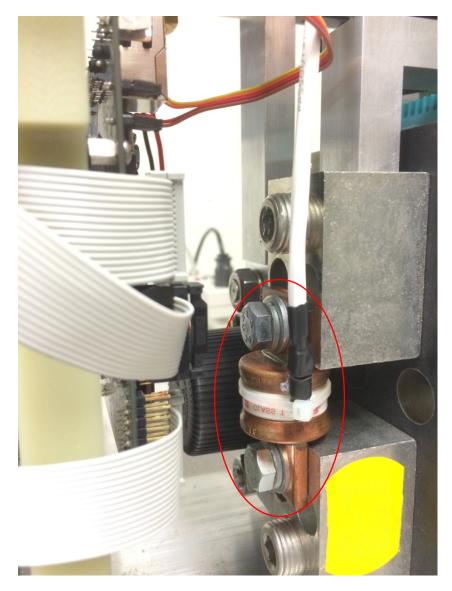


EV 3.3.1 (Failed)

If the container is made of electrically conductive material, the poles of the accumulator stack(s) and/or cells must be electrically insulated from the inside wall of the accumulator container by insulating material rated for the maximum voltage of the tractive system. All conductive surfaces on the outside of the container must have a low-resistance connection to the GLV system ground. All conductive penetrations (mounting hardware, etc.) must be located outside of the insulation and configured such that there is no possibility that they could penetrate the insulating barrier.

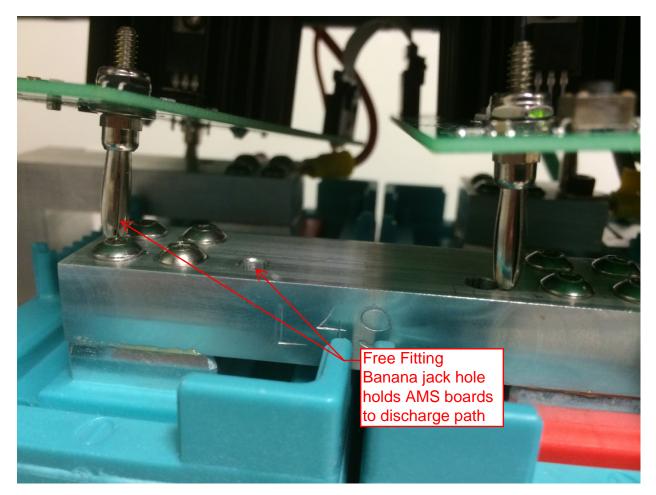
EV 3.3.2

Every accumulator container must contain at least one fuse



EV 3.3.5

Contacting / interconnecting the single cells by soldering in the high current path is prohibited.

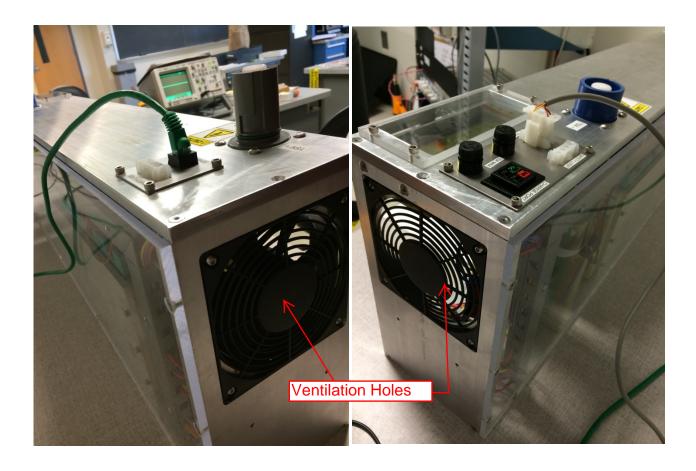


EV 3.3.6 (Failed)

Each accumulator container must have a prominent indicator, such as an LED, that will illuminate whenever a voltage greater than 30 VDC is present at the vehicle side of the AIRs. Alternatively, an analog voltmeter may be used.

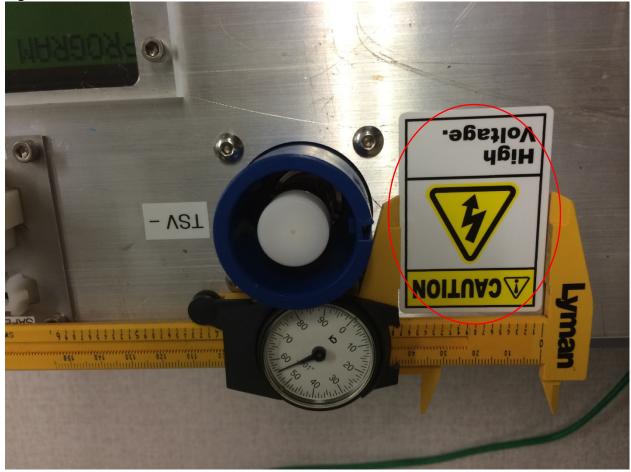
EV 3.4.8

Holes in the container are only allowed for the wiring-harness, ventilation, cooling or fasteners. These holes must be sealed according to EV4.5



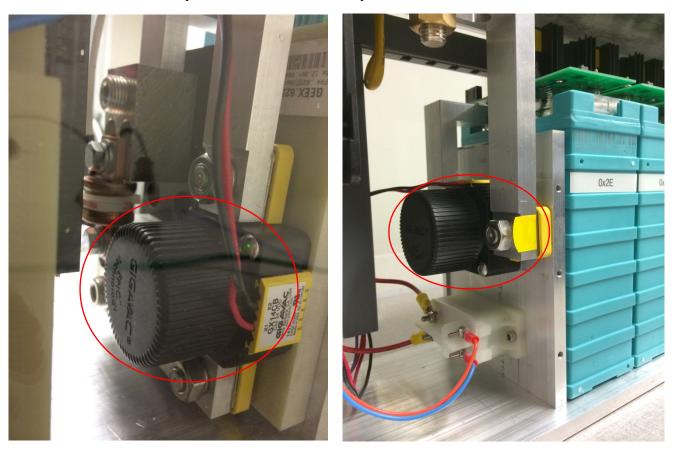
EV 3.4.10

A sticker with an area of at least 750mm² and a red or black lightning bolt on yellow background or red lightning bolt on white background must be applied on every accumulator container. The sticker must also contain the text "High Voltage" or something similar if the accumulator voltage is greater than 30 VDC.



EV 3.5.1

At least two isolation relays must be installed in every accumulator container.



No mention of

EV 3.5.4

3.5.4 - The isolation relays must be of a "normally open" type.

PRODUCT SPECIFICATIONS

Specifications	Units	Data	
Contact Arrangement			
Main	Form X	SPST-NO	\supset

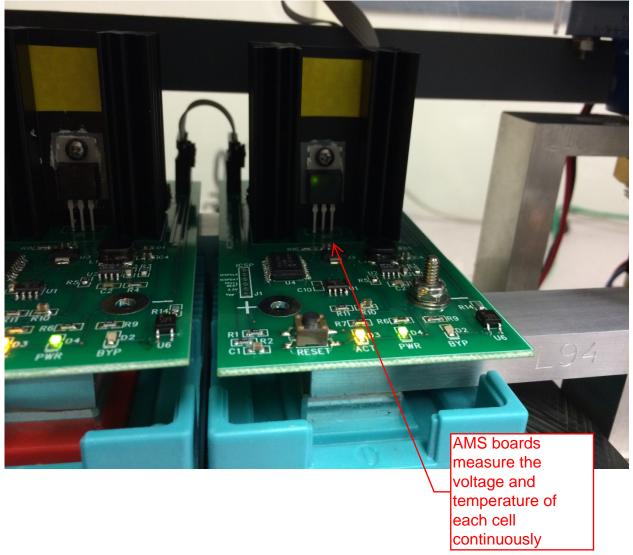
EV 3.5.6

3.5.6 - Accumulator isolation relays containing mercury are not permitted.

FEATURES	hazardous materials like mercury in datasheet
> Chassis level power terminals - No need for specially routed power cables, special bus bars	s, or spei
Rugged EPIC® seal rated to 175°C – Reduced risk of fire or meltdown in over current conditions the same technology used for advanced aerospace programs.	itions.
Hermetically sealed – UL listed: UL1604 for Class I & II, Div 2 and Class III for use in hazard locations, IP67 for temporary water immersion for 30 min, IP69K for perssure washing, SAE ignition protection, and IS08846 for protection against ignition around flammable gasses.	
High Efficiency Dual DC Coils – Very low 12, 24 or 48 VDC continuous coil power with no EN talk on your system control power. Ideal for battery powered systems or where low power is	
> Built-in coil suppression for all DC coils – Saves you engineering time and parts cost to add exte	ernal coil suppression.
> Stainless steel nuts, washers and mounting inserts, for years of corrosion free service.	
> Not position sensitive - can be mounted in any position for ease of installation.	

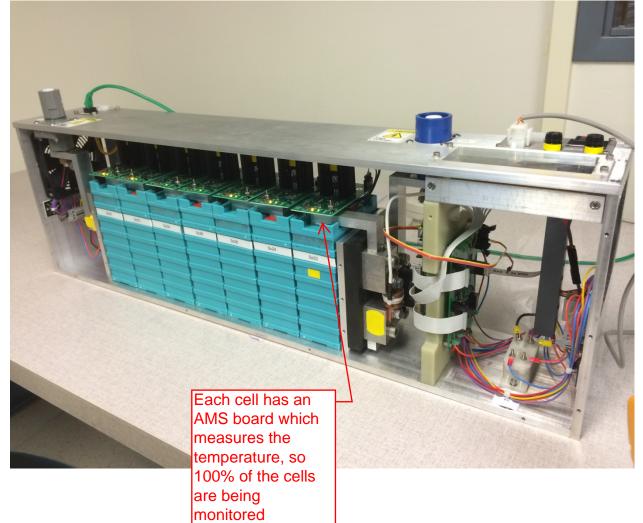
EV 3.6.1

Each accumulator must be monitored by an accumulator management system whenever the tractive system is active or the accumulator is connected to a charger.



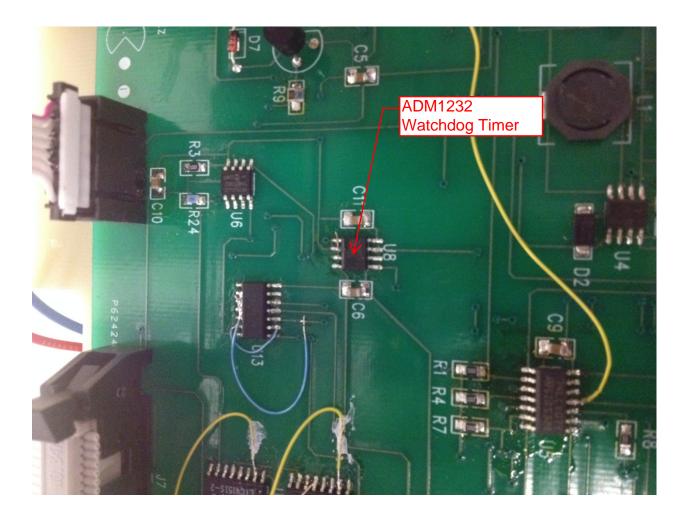
EV 3.6.6

The AMS must monitor the temperature of the minimum number of cells in the accumulator as specified in Table 12 below. The monitored cells must be equally distributed over the accumulator container(s). According to Table 12, 15% of the LiFePO4 cells must be monitored.



EV 3.6.8

Team-Designed Accumulator Management Systems: Teams may design and build their own Accumulator Management Systems. However, microprocessor-based accumulator management systems are subject to the following restrictions: (a) The processor must be dedicated to the AMS function only. However it may communicate with other systems through shared peripherals or other physical links. (b) The AMS circuit board must include a watchdog time (Maxim MAX6373 or similar) which is physically separate from the CPI. (c) The external watchdog time must be hardwired to the AIRs through an electro-mechanical relay such that a watchdog timeout or lost of power to the circuit board will result in the AIRs opening (d) The watchdog "tickle" input must be driven high and low in separate routines (i.e. no "compliment port pin" code) At least one watchdog input transition must be driven inside a foreground routine, i.e. both transitions may not be contained in timer or externally-triggered interrupt routines. (e) The code that drives the watchdog input may not be located such that a malfunction resulting in continuous internal watchdog timeouts could prevent the external watchdog timer from timing out. (f) The external watchdog time must be demonstrable.

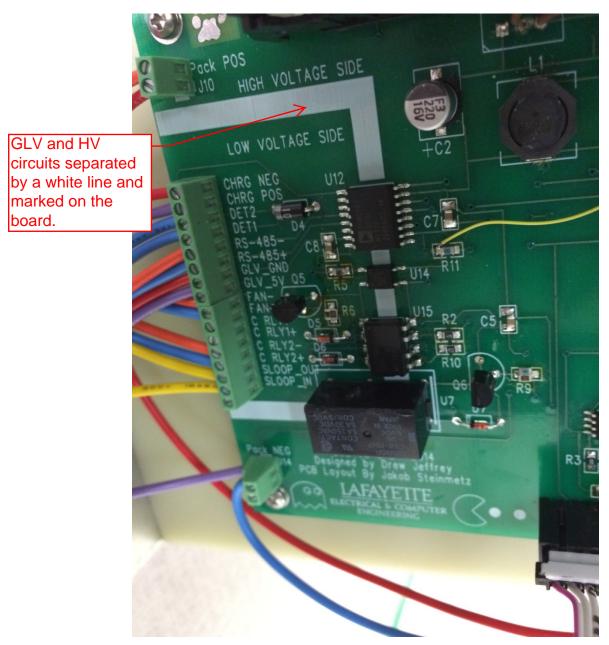


EV 4.1.6 (Failed)

Spacing must be clearly defined. Components and cables capable of movement must be positively restrained to maintain spacing.

EV 4.1.7

If tractive system circuits and GLV circuits are on the same circuit board they must be on separate, clearly defined areas of the board. Furthermore, the tractive system and GLV areas must be clearly marked on the PCB.

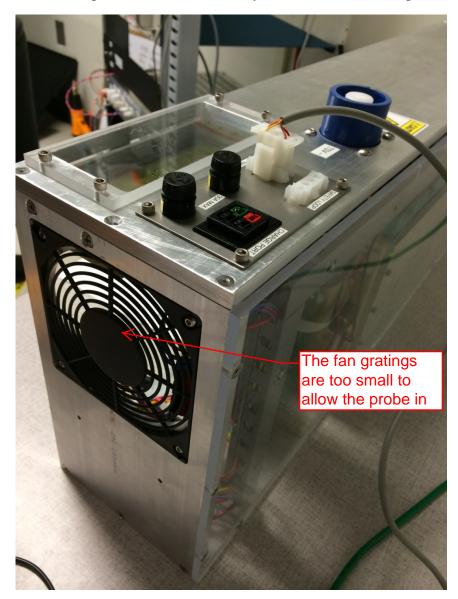


EV 4.2.5 (Failed)

There must be a layer of an electrically insulating material between any tractive terminal or connection and the firewall or frame if they are within 50 mm (2 inches) of one another.

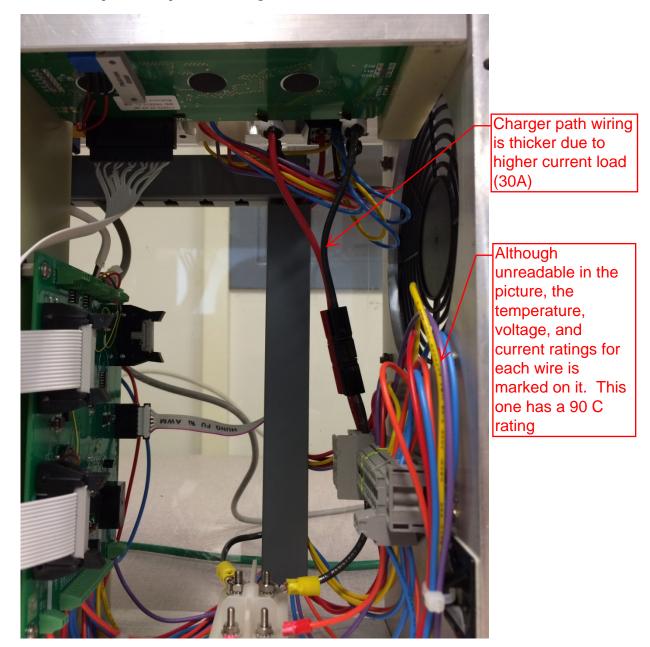
EV 4.5.1

All parts especially live wires, contacts, etc. of the tractive system need to be isolated by nonconductive material or covers to be protected from being touched. In order to achieve this, it must not be possible to touch any tractive system connections with a 10 cm long, 0.6 cm diameter insulated test probe when the tractive system enclosures are in place.



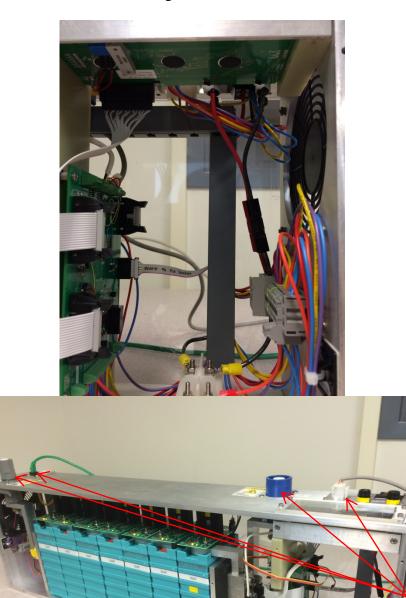
EV 4.5.6

All wires and terminals and other conductors used in the tractive system must be sized appropriately for the continuous rating of the fuse which protects them. Wires must be marked with wire gauge, temperature rating and insulation voltage rating. Alternatively a manufacturers part number printed on the wire is sufficient if this can be referenced to a manufacturers data sheet. The minimum acceptable temperature rating for TSV cables is 90°C.



EV 4.5.7

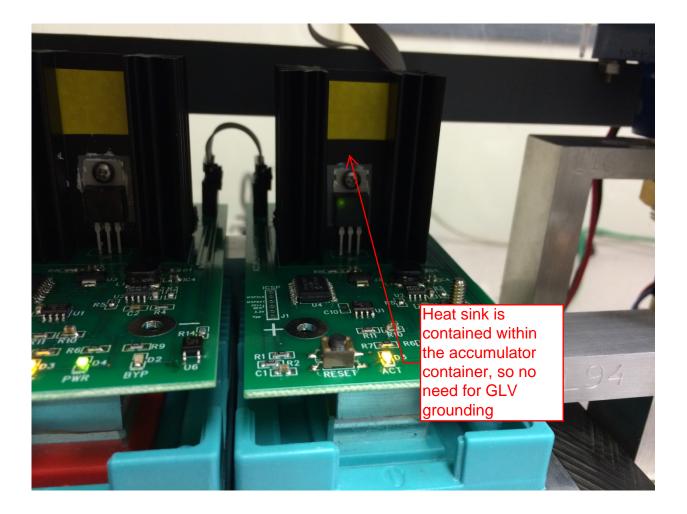
All tractive system wiring must be done to professional standards with appropriately sized conductors and terminals and with adequate strain relief and protection from loosening due to vibration etc. Conductors and terminals cannot be modified from their original size/shape and must be appropriate for the connection being made.



Connectors are in original shape and size

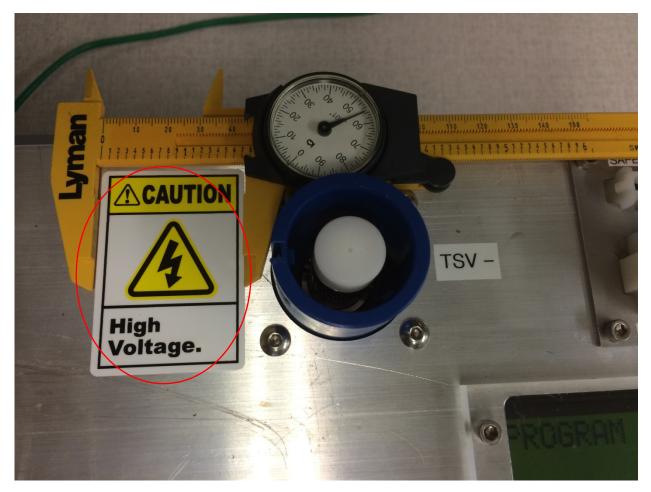
EV 4.5.13

If external, un-insulated heat sinks are used, they must be properly grounded to the GLV system ground



EV 4.6.1

Every housing or enclosure containing parts of the tractive system except motor housings must be labeled with (a) reasonably sized sticker(s) with a red or black lightning bolt on yellow background or red lightning bolt on white background. The sticker must also contain the text "High Voltage" or something similar if the voltage is more than 30 VDC or 25 VAC.



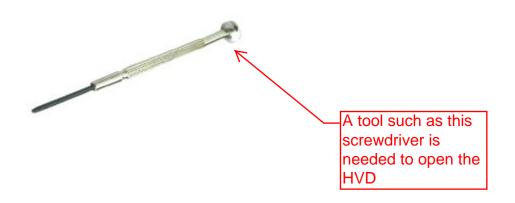
EV 4.7.4

The Disconnect must be clearly marked with "HVD".



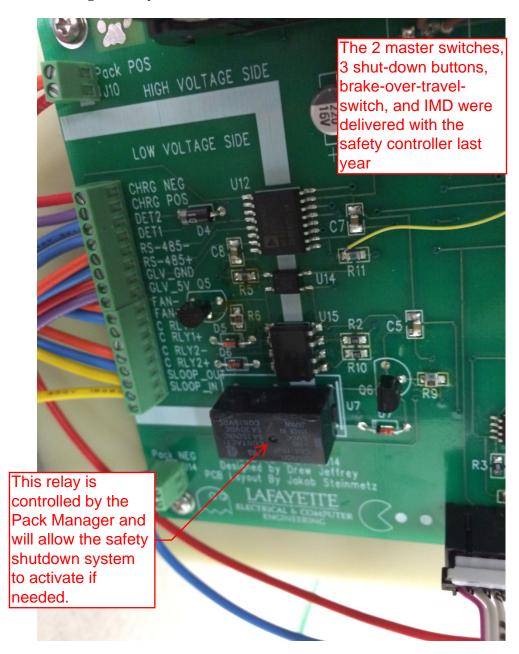
EV 4.7.6

If no tools are needed to open the HVD, an interlock must open up the shutdown circuit when the HVD is removed.



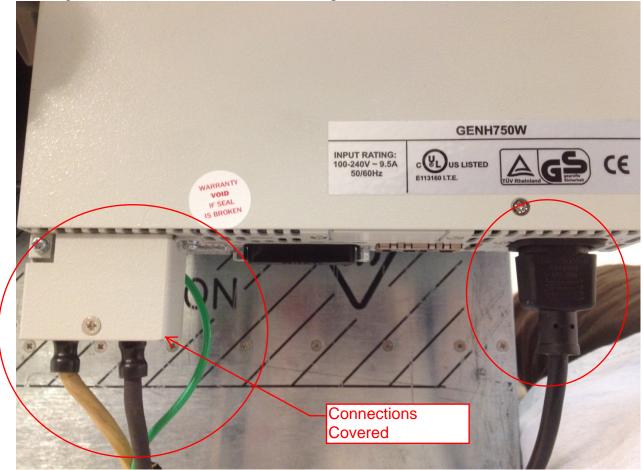
EV 5.1.2

The shutdown circuit consists of at least 2 master switches, 3 shut-down buttons, the brake-over-travel-switch, the insulation monitoring device (IMD), all required interlocks and the **accumulator management system (AMS).**



EV 8.2.5

Only chargers presented and sealed at Electrical Tech Inspection are allowed. All connections of the charger(s) must be isolated and covered. No open connections are allowed.



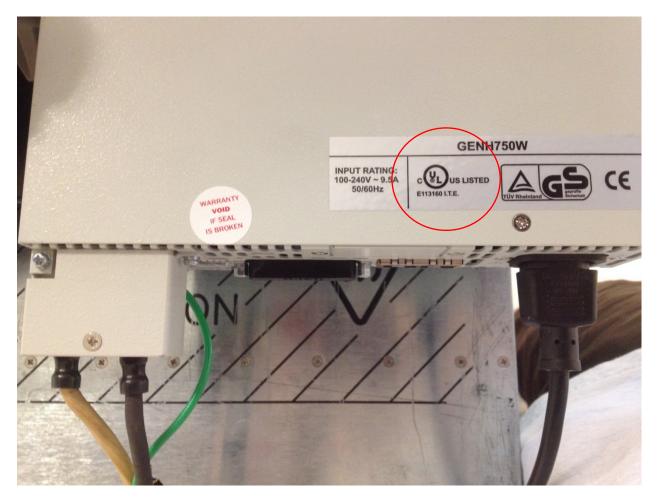
EV 8.2.10

High Voltage wiring in an off board charger does not require conduit; however it must be a UL listed flexible cable that complies with NEC Article 400; double insulated.



EV 8.2.11

All chargers must be UL (Underwriters Laboratories) listed. Any waivers of this requirement require approval in advance, based on documentation of the safe design and construction of the system, including galvanic isolation between the input and output of the charger. Waivers for chargers must be submitted at least 30 days prior to the start of the competition.



Test Results Form

This form is provided in order to quickly see which tests (and thus, which requirements) have been passed.

Test	Description	P/F	Date
T000	Battery Pack Display and Safety Qualification		
	The multimeter measured voltage of the total pack voltage	Р	5/13/14
T000.1	is within ± 0.1 V of the displayed total voltage on the		
	character LCD screen.		
T000.2	The absolute value of the pack current displayed on the	Р	5/13/14
1000.2	character LCD screen is < 1A		
T000.3	The pack state of charge (SOC) displayed on the character	Р	5/9/14
1000.5	LCD screen is between 0 and 100 %.		
	The measured resistance between the poles of the	Р	5/9/14
T000.4	accumulator container and the inside wall of the pack is >		
	1 ΜΩ.		
T000.5	The measured resistance between the discharge path of the	Р	5/9/14
1000.5	pack and GLV components are $> 1M\Omega$.		
T000.6	The safety loop is closed when the Safety Loop reset	Р	5/13/14
1000.0	button is pressed.		
T000.7	The safety loop is opened when the "reset" switch is	Р	5/13/14
1000.7	triggered on the battery pack		
	TS-8160-4200's software begins automatically after the	Р	5/13/14
T000.8	reset switch is triggered and the computer boots itself up		
	again.		
	The safety loop is opened when the TWD 0 command is	F	5/13/14
T000.9	sent to the pack manager and the watchdog timer times		
	out.		
	The Pack Manager returns to normal operation and the	F	5/13/14
T000.10	safety loop closes when TWD 1 is sent to the pack		
	manager.		
	The safety loop is opened when the TOB 1 command is	F	5/13/14
T000.11	sent to the pack manager to simulate an out of bounds		
	reading.		
T001	Low Current Discharge Test		
T001.1	Connectors cannot be removed without use of tools	Р	5/9/14
T001.2	Resistance measurement between the pack's HV poles is >	Р	5/9/14
1001.2	$1M\Omega$ when at least one of the AIRs are open.		
T001.3	The safety loop is closed when the "reset safety loop"	Р	5/9/14
	button is pressed.		
T001.4	The discharge current displayed on the LCD screen of the	F	5/13/14

	battery pack is within \pm 1A of the drawn current displayed on the load resistor unit.		
T001.5	The pack manager's LCD display shows the system is in discharge mode.	Р	5/9/14
T001.6	The safety loop is opened by the pack manager when a cell voltage reaches the low voltage threshold.	Р	5/9/14
T001.7	The TS-8160-4200's green power LED is still lit when it opens the safety loop to end the discharge cycle.	Р	5/9/14
T002	Charge Cycle Test		
T002.1	Safety Loop is closed before the charging cable is plugged into the battery pack and the "dummy" plug is removed from the charging port.	Р	5/13/14
T002.2	Safety Loop is opened when the "dummy" plug is removed from the battery pack and the charging cable is plugged into the battery pack.	Р	5/13/14
T002.3	The pack manager enters the charging state when the charging cable is plugged into the battery pack by displaying a status message that the pack is charging on the LCD screen.	Р	5/13/14
T002.4	The charging relays are closed automatically by the pack manager to allow the battery to begin charging as shown by the drawn current on the power supply.	Р	5/13/14
T002.5	Safety Loop does not close when the reset safety loop button is pressed during the charging cycle.	Р	5/13/14
T002.6	No error messages or system failures related to charging were encountered during the charge cycle.	Р	5/13/14
T002.7	The time to complete the charge cycle is within ± 0.5 hours of the estimated time of charge based on beginning SOC reported by the pack manager.	Р	5/13/14
T002.8	The LCD screen on the battery pack display a status message indicating charging has completed successfully.	Р	5/13/14
T002.9	The LCD screen displays an SOC of $100 \pm 1\%$ when the pack manager indicates the battery pack is fully charged.	Р	5/13/14
T002.10	The charge relays are opened automatically when the pack manager indicates the battery pack is fully charged.	Р	5/13/14
T002.11	Safety Loop does not open when the reset safety loop button is pressed after the charging cycle has completed but before the charger cable has been removed from the battery pack.	Р	5/13/14
T002.12	Pack manager enters the discharging state and removes the charging complete status message from the LCD display after the charging cable is disconnected from the battery pack.	Р	5/13/14
T002.13	Safety Loop is closed after the charging cable is removed	Р	5/13/14

	from the battery pack and the "dummy" charge plug is		
	inserted into the charging port.		
T003	High Current Discharge Test		
T003.1	The safety loop is closed when the "reset safety loop" button is pressed.	Р	5/13/14
T003.2	The discharge current displayed on the LCD screen of the battery pack is within \pm 1A of the drawn current displayed on the load resistor unit.	F	5/13/14
T003.3	The discharge fuse remains intact and not blown during the entire high current discharge cycle.	Р	5/13/14
T003.4	The safety loop is opened by the pack manager when a cell voltage reaches the low voltage threshold	Р	5/13/14
T004	RS-485 Communication with Off-Board Systems		
T004.1	The pack manager's returns the value 0x42 to RealTerm upon sending the command 1 TEST?.	F	5/13/14
T004.2	The pack manager returns to RealTerm 7 as the number of cells when the command 1 CELLCNT? is sent.	F	5/13/14
T004.3	The pack manager returns to RealTerm 7 voltage measurements when the command 1 V? is sent.	F	5/13/14
T004.4	The pack manager does not return any information to RealTerm when it receives a command addressed to a different pack manager board	Р	5/13/14
T005	Reliability Test		
T005.1	Testing area and setup are confirmed to be safe for future testing as defined by the LFEV-14 Safety Plan.	Р	5/13/14
T005.2	At least two qualified individuals were present at all times during any charging and load discharging periods applied to the system over the 24 hour test period.	Not Run Officially - F	5/13/14
Т005.3	System runs through a series of idle, charging, and discharging cycles for 24 hours without any obvious failures.	Not Run Officially - F	5/13/14
T006	Maintainability Tests		
T006.1	A novice user can replace a blown fuse in the system.	Р	5/9/14
T006.2	An expert user can solve an unexpected maintenance problem.	Not Run Officially - F	5/13/14

Detailed Test Results

T000: Battery Pack Display and Safety Qualification

This test ensures the battery pack meets the necessary safety guidelines before beginning discharge and charging cycle tests. The onboard watchdog and pack manager's ability to open the safety loop will be tested. In addition the RS-485 communication link will also be exercised. This test must be completed before beginning T001 - T003.

Preconditions:

- All AMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- System is connected in test configuration B
- Dummy plug is placed in the charging port
- System has been calibrated according to D11: Calibration and Accuracy Memo and tolerance values for all ATP measurements have been written in based on the statistical analysis found in D11.
- The USB to RS-485 adapter is plugged into a USB port of the personal computer being used for testing.
- The RS-485 adapter is connected to the battery pack's RS-485 serial port.
- RealTerm is running on the host personal computer
- All LFEV subsystems outside of the battery pack are powered off
- The power hub is plugged into the wall
- Software is running on the TS-8160-4200

- 1. Perform tests for passing criteria 1-4
- 2. Press the switch on the power hub labeled "GLV" to power the GLV power system. The switch should light up to indicate it is on. Turn the two red key switches labeled SCADA and Safety/Traction to power up the system.
- 3. Attach the battery pack to the safety loop and press the reset safety loop button on the safety controller box
- 4. Perform tests for passing criteria 5-6
- 5. Press the "reset" button on the battery pack
- 6. Perform test for passing criteria 7-8
- 7. Press the reset safety loop button on the safety controller box
- 8. Send Command TESTMODE 1 and followed by TWD 0 to exercise the on-board watchdog's operation during timeout
- 9. Perform test for passing criteria 9
- 10. Send command TWD 0 to return the watchdog to normal operation
- 11. Perform test for passing criteria 10
- 12. Send Command TESTMODE 1 followed by TOB 1 to fake an out of bounds sensor reading
- 13. Perform test for passing criteria 11

Date of Test: <u>5/9/14 and 5/13/14</u>	Time of Test: <u>2:00PM</u>
Person Performing Test:	Ben Richards, Drew Jeffrey

ECE Professor Witnessing Test: N/A(Permission Given To Run Test Without Professor)

Note: RS-485 communication was not working in current design, so criteria 9-11 fail due to inability to use the RS-485 protocol and communicate with the computer

Passing Criteria

1. The absolute value of the pack current displayed on the character LCD screen is < 1A.

Displayed Pack Current
(A)
0.13

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

2. The pack state of charge (SOC) displayed on the character LCD screen is between 0 and 100 % inclusive.

	Displayed Pack State of Charge (%)		
	29		
Drew Jeffrey Witness/Examiner Signat	ure	5/13/14 Date	P Pass/Fail

3. The measured resistance between the poles of the accumulator container and the outside wall of the pack is $> 1M\Omega$.

Measured Resistance	
(Ohms)	
OVLD	

Drew Jeffrey	5/9/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

4. The measured resistance between the poles of the pack and following GLV components are $>1M\Omega.$

GLV Component	Measured Resistance (Ohms)
Safety Loop In Wire	OVLD
Safety Loop +24V Wire	OVLD
Safety Loop -24V Wire	OVLD
Safety Loop Out Wire	OVLD
RS-485 Serial Port Out Pin	OLVD
1 (D+)	
RS-485 Serial Port Out Pin	OLVD
2 (D-)	

Drew Jeffrey	5/9/14	P
Witness/Examiner Signature	Date	Pass/Fail

5. The safety loop is closed when the Safety Loop reset button is pressed.

Drew Jeffrey	5/9/14	<u>P</u>
Witness/Examiner Signature	Date	Pass/Fail

6. The multimeter measured voltage of the total pack voltage across the poles is within \pm 0.1V of the displayed total voltage on the character LCD screen.

Measured Voltage (V)	Displayed Voltage (V)	% Error
22.77	22.83	-0.26%

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

7. The safety loop is opened when the "reset" switch is triggered on the battery pack

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

8. TS-8160-4200's software begins automatically after the reset switch is pressed and the computer boots itself up again.

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

9. The safety loop is opened when the TWD 0 command is sent to the pack manager and the watchdog timer times out.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

10. The safety loop closes when TWD 1 is sent to the pack manager and the safety loop reset button is pressed.

Drew Jeffrey	5/13/14	F
Witness/Examiner Signature	Date	Pass/Fail

11. The safety loop is opened when the TOB 1 command is sent to the pack manager to simulate an out of bounds reading.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

T001: Low Current Discharge Test

This test will simulate a discharge cycle of the battery pack and exercise the safety features of the pack which will be utilized when the voltage in the pack reaches critical levels.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- System is connected in test configuration B
- All systems outside of the battery pack are powered off
- The power hub is plugged into the wall
- Test T000 must have been performed and passed. If this has not been passed, the instructor's explicit approval must be given to perform this test.

- 1. Perform test for Passing Criterion 1 by attempting to decouple the Powerlock connectors from each side of the pack.
- 2. Perform tests for passing criteria 2.
- 3. Press the switch on the power hub labeled "GLV" to power the GLV power system. The switch should light up to indicate it is on.
- 4. Ensure that all safety systems are enabled and press the "reset safety loop" button
- 5. Perform test for passing criteria 3
- 6. Turn on the Load switch on the power hub and press the AC power switch on the resistive Load. Turn the Load Adjust knob on the resistive load completely counter clockwise to its lowest position.
- 7. Close the load controller relays to connect the battery pack HV terminals to the resistive load.
- 8. Depress the button labeled "200 A" on the resistive load.
- 9. Engage the DC load switch on the resistive load to beginning driving the load with the battery pack.
- 10. Adjust the coarse adjustment knob (larger knob) on the dial labeled "Load Adjust" until the LED on the Load indicates that 60 A are being drawn by the load.
- 11. Perform tests for passing criteria 4-5
- 12. Wait for the safety loop to become opened by the pack manager when the lower voltage bound of the pack reaches its configured value or the pack manager system shuts down due to lack of sufficient voltage. This ensures a fully discharged cell
- 13. Perform tests for passing criteria 6-7

Date of Test: <u>5/9/14 and 5/13/14</u>	Time of Test: <u>2:30PM</u>
Person Performing Test:	Ben Richards, Drew Jeffrey
ECE Professor Witnessing Test: N/	A(Permission Given To Run Test Without Professor)

Passing Criteria

1. Connectors cannot be removed without use of tools

Drew Jeffrey	5/8/14	P
Witness/Examiner Signature	Date	Pass/Fail

2. Resistance measurement between the pack's HV poles is $> 1M\Omega$ when at least one of the AIRs are open.

	AIR(s) open (+, -, both)	Measured Resistance (Ohms)	9
	Both	OVLD	
D	rew Jeffrey	5/8/14	P
	Examiner Signature	Date	Pass/Fail

3. The safety loop is closed when the "reset safety loop" button is pressed.

Drew Jeffrey	5/9/14	P
Witness/Examiner Signature	Date	Pass/Fail

4. The discharge current displayed on the LCD screen of the battery pack is within \pm 1A of the drawn current displayed on the load resistor unit.

Load Resistor Displayed Current (A)	LCD Displayed Current (A)	% Error
61.9	66.65	-7.13
	- 4044	
Drew Jeffrey	5/13/14	_ :
Witness/Examiner Signature	Date	Pass/

5. The pack manager's LCD display shows the system is in discharge mode.

Drew Jeffrey	5/9/14	P
Witness/Examiner Signature	Date	Pass/Fail

6. The safety loop is opened by the pack manager when a cell voltage reaches the low voltage threshold.

Drew Jeffrey	5/9/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

7. The TS-8160-4200's power LED is still lit when it opens the safety loop to end the discharge cycle.

Drew Jeffrey	5/9/14	P
Witness/Examiner Signature	Date	Pass/Fail

T002: Charge Cycle Test

This test will simulate a charge cycle of the battery pack and exercise its "plug and forget" features.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- System is connected in test configuration C, with the charging cable unconnected from the battery pack
- All systems outside of the battery pack are powered off
- The charger is plugged into the wall and is powered on
- Test T000 must have been performed and passed. If this has not been passed, the instructor's explicit approval must be given to perform this test.
- T001 was recently completed or the battery pack's state of charge is less than 10% of the full charge

- 1. Press the switch on the power hub labeled "GLV" to power the GLV power system. The switch should light up to indicate it is on.
- 2. Ensure that all safety systems are enabled and press the "reset safety loop" button
- 3. Perform tests for passing criterion 1.
- 4. Remove the dummy plug from the charging port and plug the charging cable into the charging port on the battery pack
- 5. Perform tests for passing criteria 2-4.
- 6. Press the reset safety loop button
- 7. Perform tests for passing criteria 5
- 8. Wait for the pack manager to state charging has completed
- 9. Perform tests for passing criteria 6-10
- 10. Press the reset safety loop button
- 11. Perform tests for passing criteria 11-12
- 12. Disconnect the charging cable from the battery pack
- 13. Plug the dummy plug into the charging port and then press the reset safety loop button
- 14. Perform tests for passing criteria 13

Date of Test:5/13/14	Time of Test: <u>3:10PM</u>	
Person Performing Test:	Ben Richards, Drew Jeffrey	

ECE Professor Witnessing Test: N/A(Permission Given To Run Test Without Professor)

Passing Criteria

1. Safety Loop is closed before the charging cable is plugged into the battery pack and the "dummy" plug is removed from the charging port.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

2. Safety Loop is opened when the "dummy" plug is removed from the battery pack and the charging cable is plugged into the battery pack.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

3. The pack manager enters the charging state when the charging cable is plugged into the battery pack by displaying a status message that the pack is charging on the LCD screen.

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

4. The charging relays are closed automatically by the pack manager to allow the battery to begin charging as shown by the drawn current on the power supply.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

5. Safety Loop does not close when the reset safety loop button is pressed during the charging cycle.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

6. No error messages or system failures related to charging were encountered during the charge cycle.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

7. The time to complete the charge cycle is within ± 0.5 hours of the estimated time of charge based on beginning SOC reported by the pack manager.

Initial SOC	Charging	Estimated Time to	Actual Time of	Error
(%)	Current (A)	Charge (Hrs)	Charge (Hrs)	
0	25A	2.4	2.33	-2.9%

Drew Jeffrey	5/13/14	<u>P</u>
Witness/Examiner Signature	Date	Pass/Fail

8. The LCD screen on the battery pack display a status message indicating charging has completed successfully.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

9. The LCD screen displays an SOC of 100 ± 1 % when the pack manager indicates the battery pack is fully charged

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

10. The charge relays are opened automatically when the pack manager indicates the battery pack is fully charged.

Drew Jeffrey5/13/14PWitness/Examiner SignatureDatePass/Fail

11. Safety Loop does not close when the reset safety loop button is pressed after the charging cycle has completed but before the charger cable has been removed from the battery pack.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

12. Pack manager enters shows that it enters the discharging state after charging completes

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

13. Safety Loop is closed after the charging cable is removed from the battery pack, the "dummy" charge plug is inserted into the charging port, and the reset safety loop button is pressed.

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

T003: High Current Discharge Test

This test will simulate a discharge cycle of the battery pack under the maximum current load and exercise the safety features of the pack which will be utilized when the voltage in the pack reaches critical levels.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- System is connected in test configuration B
- All systems outside of the battery pack are powered off
- The power hub is plugged into the wall
- Test T000 and T001 must have been performed and passed. If this has not been passed, the instructor's explicit approval must be given to perform this test.

- 1. Press the switch on the power hub labeled "GLV" to power the GLV power system. The switch should light up to indicate it is on.
- 2. Ensure that all safety systems are enabled and press the "reset safety loop" button
- 3. Perform test for passing criteria 1
- 4. Close the load controller relays to connect the battery pack HV terminals to the resistive load.
- 5. Depress the button labeled "200 A" on the Load. Adjust the coarse adjustment knob (larger knob) on the dial labeled "Load Adjust" until the LED on the Load indicates that 180 A are being drawn by the load.
- 6. Perform tests for passing criteria 2
- 7. Wait for the safety loop to become opened by the pack manager when the lower voltage bound of the pack reaches its configured value or the pack manager system shuts down due to lack of sufficient voltage. This ensures a fully discharged cell
- 8. Perform tests for passing criteria 3-4

Date of Test: <u>5/13/14</u>	Time of Test:5:30PM
Person Performing Test: _	Ben Richards, Drew Jeffrey
ECE Professor Witnessing	Test: <u>N/A(Permission Given To Run Test Without Professor)</u>

Passing Criteria

1. The safety loop is closed when the "reset safety loop" button is pressed.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

2. The discharge current displayed on the LCD screen of the battery pack is within $\pm 1A$ of the drawn current displayed on the load resistor unit.

Load Resistor Displayed Current (A)	LCD Displayed Current (A)	% Error
180.2	201	11.5%

Drew Jeffrey	5/13/14	F
Witness/Examiner Signature	Date	Pass/Fail

3. The discharge fuse remains intact and not blown during the entire high current discharge cycle.

Drew Jeffrey	5/13/14	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

4. The safety loop is opened by the pack manager when a cell voltage reaches the low voltage threshold

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

T004: RS-485 Communication with Off-Board Systems

This test verifies correct operation of the Pack Management System's software in being able to receive messages via RS-485 and supply the requested battery details to the requesting system.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- The USB to RS-485 adapter is plugged into a USB port of the personal computer being used for testing.
- The RS-485 adapter is connected to the battery pack's RS-485 serial port.
- RealTerm is running on the host personal computer

- 1. Send command 1 TEST? To the pack manager from RealTerm
- 2. Perform tests for passing criteria 1
- 3. Send command 1 CELLCNT? To the pack manager from RealTerm
- 4. Perform tests for passing criteria 2
- 5. Send command 1 V? to the pack manager from RealTerm.
- 6. Perform tests for passing criteria 3
- 7. Send command 2 TEST? to the pack manager from RealTerm to send a command with a mismatched address.
- 8. Perform tests for passing criteria 4

Date of Test: <u>5/9/14 and 5/13/14</u>	Time of Test: <u>6:10PM</u>
Person Performing Test:	Naing Htet, Drew Jeffrey

ECE Professor Witnessing Test: N/A(Permission Given To Run Test Without Professor)

Note: RS-485 communication was not working in current design, so criteria 1-3 fail due to inability to use the RS-485 protocol and communicate with the computer

Passing Criteria:

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1. The pack manager's returns the value 0x42 to RealTerm upon sending the command 1 TEST?.

Expected Value	Returned Value
0x42	

Drew Jeffrey	5/13/14	<u>F</u>
Witness/Examiner Signature	Date	Pass/Fail

2. The pack manager returns to RealTerm 7 as the number of cells when the command 1 CELLCNT? is sent.

Expected Value	Returned Value

Drew Jeffrey	5/13/14	F
Witness/Examiner Signature	Date	Pass/Fail

3. The pack manager returns to RealTerm 7 voltage measurements when the command 1 V? is sent.

Drew Jeffrey	5/13/14	F
Witness/Examiner Signature	Date	Pass/Fail

4. The pack manager does not return any information to RealTerm when it receives a command addressed to a different pack manager board

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

T005: Reliability Test

This test verifies that the system can run without obvious failure for 24 hours. Combining analysis with this test will prove that our system meets reliability specifications.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- System is connected in test configuration B
- All systems outside of the battery pack are powered off
- The power hub is plugged into the wall
- Tests T000-T002 have been performed and passed. If these have not been passed, the instructor's explicit approval must be given to perform this test.
- Per safety regulations, at least two qualified individuals must monitor the system at all times during charging and load discharging periods. For further information, see the Safety Plan.

- 1. Perform the test for passing criteria 1.
- 2. Press the switch on the power hub labeled "GLV" to power the GLV power system. The switch should light up to indicate it is on.
- 3. Ensure that all safety systems are enabled and press the "reset safety loop" button
- 4. Begin discharging the battery pack as specified in T001 steps 6-7
- 5. Wait for the battery pack to finish its discharge cycle as specified in T001 step 9.
- 6. Power off all systems and connect the system into configuration C.
- 7. Charge the battery pack as specified in T002 steps 1-2, 4, and 8.
- 8. Wait for 24 hours from the start of T007 to complete.
- 9. Repeat steps 2-7 of T005.
- 10. Perform the tests for Passing Criteria 2-3.

Date of Test: ____5/13/14____ Time of Test: ____8:10PM_____

Person Performing Test: _____Ben Richards, Drew Jeffrey_____

ECE Professor Witnessing Test: N/A(Permission Given To Run Test Without Professor)

NOTE: Test was not run for 24 hour period as specified in procedure due to time constraints, so criteria 2-3 fail for this reason

Passing Criteria:

1. Testing area and setup are confirmed to be safe for future testing as defined by the LFEV-14 Safety Plan.

Drew Jeffrey	5/13/14	P
Witness/Examiner Signature	Date	Pass/Fail

2. At least two qualified individuals were present at all times during any charging and load discharging periods applied to the system over the 24 hour test period.

Drew Jeffrey	5/13/14	F
Witness/Examiner Signature	Date	Pass/Fail

3. System runs through a series of idle, charging, and discharging cycles for 24 hours without any obvious failures.

Drew Jeffrey5/13/14FWitness/Examiner SignatureDatePass/Fail

T006: Maintainability Test

This test verifies that a novice user can perform basic maintenance on the system using the user's manual. The ability for an expert user to fix an unlikely error in the system will also be tested.

Preconditions:

- All BMS boards and Pack Manager components are being sufficiently powered by the current state of charge of the battery pack
- The pack manager's test mode is off
- All systems outside of the battery pack are powered off
- The power hub is plugged into the wall
- Tests T000-T002 have been performed and passed. If these have not been passed, the instructor's explicit approval must be given to perform this test.

- 1. Remove a charging fuse from the system to simulate a blown fuse.
- 2. Perform the test for passing criteria 1
- 3. Configure the system in order to simulate an unlikely error in the system.
- 4. Perform the tests for Passing Criteria 2.

Date of Test: <u>5/9/14</u>	Time of Test: <u>1:56 PM</u>		
Person Performing Test:	Ben Richards, Drew Jeffrey		
ECE Professor Witnessing T	est: N/A(Permission Given To Run Test Without Professor)		
NOTE: Passing criteria 2 was not completed due to time constraints.			

Passing Criteria:

1. A novice user can replace a blown fuse in the system.

Drew Jeffrey	<u> </u>	<u> </u>
Witness/Examiner Signature	Date	Pass/Fail

2. An expert user can solve an unexpected maintenance problem.

Problem:

Drew Jeffrey Witness/Examiner Signature <u>5/9/14</u> Date

ATP Scoring Summary

Type of Requirement Verification	Passed	Failed	Total
Deliverables	20	5	25
Inspection	41	5	46
Analysis	24	6	30
Test	33	11	44
Total	118	27	145